
COSPAS-SARSAT DATA DISTRIBUTION PLAN

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COSPAS-SARSAT DATA DISTRIBUTION PLAN

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1. INTRODUCTION

1.1 Overview

The purpose of the Cospas-Sarsat System is the provision of distress alert and location data for search and rescue (SAR), using spacecraft and ground facilities to detect and locate the signals of Cospas-Sarsat distress radiobeacons operating on 406 MHz. The position of the distress and other related information is transmitted to appropriate SAR authorities by the responsible Cospas-Sarsat Mission Control Centre (MCC).

1.2 Document Objective

The Cospas-Sarsat System is operated in accordance with the 1988 International Cospas-Sarsat Programme Agreement (ICSPA) and related documents. The purpose of this document is to:

- establish basic data distribution principles; and
- define the corresponding procedures to be implemented by Cospas-Sarsat MCCs for distributing Cospas-Sarsat alert data and System information.

1.3 Document Organization

The Cospas-Sarsat policy with regards to MCC operations is contained in the text of this Cospas-Sarsat Data Distribution Plan (DDP).

A brief description of the Cospas-Sarsat operational concept is given in section 2. Section 3 describes the basic approach for exchanging System information between MCCs and distributing to Rescue Coordination Centres (RCCs) or other SAR points of contact (SPOCs) alert data and notification of country of beacon registration (NOCR) messages.

The annexes to this DDP provide:

- a) a description of the Cospas-Sarsat Space and Ground Segments (Part I); and
- b) a detailed description of the operational procedures to be applied by MCCs (Part II).

1.4 Reference Documents

- a) C/S A.002 Cospas-Sarsat Mission Control Centres Standard Interface Description.
- b) C/S A.003 Cospas-Sarsat System Monitoring and Reporting.
- c) C/S A.005 Cospas-Sarsat Mission Control Centre Performance Specification and Design Guidelines.

- d) C/S G.004 Cospas-Sarsat Glossary*.
- e) C/S T.002 Cospas-Sarsat Local User Terminal Performance Specification and Design Guidelines.
- f) C/S T.004 Cospas-Sarsat LEOSAR Space Segment Commissioning Standard.
- g) C/S T.009 Cospas-Sarsat GEOLUT Performance Specification and Design Guidelines.
- h) C/S T.013 Cospas-Sarsat GEOSAR Space Segment Commissioning Standard.
- i) C/S T.017 Cospas-Sarsat MEOSAR Space Segment Commissioning Standard.
- j) C/S T.019 Cospas-Sarsat MEOLUT Performance Specification and Design Guidelines.
- k) C/S P.011 Cospas-Sarsat Programme Management Policy.

Note: * A list of acronyms used in this document is contained in the Cospas-Sarsat Glossary (document C/S G.004) and in the “Acronyms and Terminology” page on the Cospas-Sarsat website, available at <http://www.cospas-sarsat.int/en/pro>, under the Documents menu.

- END OF SECTION 1 -

2. GENERAL OPERATIONAL CONCEPT

2.1 General Alert Data Flow

The distribution of Cospas-Sarsat alert data throughout the world is summarized as follows:

- the LUTs receive the beacon signals relayed by the satellites; and
- the signals are processed and alert data is sent to the associated MCC for distribution.

Each MCC distributes alert data according to this Cospas-Sarsat Data Distribution Plan (DDP), and according to its own unique requirements and procedures, to any country within its service area which has agreed to accept such services. Alert data is provided to SPOCs, which are RCCs or other recognized national points of contact that will use the data to enable fast and effective rescue of persons in distress.

Any MCC receiving alert data relating to a distress beacon located outside its service area will relay that information to another MCC or responsible SPOC in accordance with the principles listed in section 2.2 and the agreed procedures detailed in this DDP.

2.2 Alert Data Distribution Principles

The exchange of alert data between MCCs in the Cospas-Sarsat System and its distribution to RCCs or SPOCs is based on the following principles:

Cospas-Sarsat alert data should be:

- validated at the MCC to ensure the reliability of distress information provided to RCCs and SPOCs;
- distributed in a timely manner to the appropriate RCC or SPOC, as determined by the rules defined in this Data Distribution Plan; and
- provided to SPOCs in accordance with the applicable Cospas-Sarsat procedures, or procedures agreed bilaterally between an MCC and the SPOCs in its service area.

In the case of maritime emergencies, any MCC not able to deliver the alert to the responsible SPOC should forward the alert to a RCC in the same country as the MCC.

In the case of inland emergencies, any MCC not able to deliver the alert to the responsible SPOC should deliver the alert to an ARCC in the same country as the MCC, and could also consider contacting the control tower of an international airport in the country concerned.

In addition, MCCs should follow the Cospas-Sarsat agreed procedures to:

- filter out redundant alert messages;
- confirm the position of distress beacons and notify all recipients of incorrect positions after position has been confirmed; and
- ensure through appropriate backup arrangements, the uninterrupted distribution of alert data.

2.3 Service Area of Cospas-Sarsat MCC

An MCC's service area is that part of the world within which a Cospas-Sarsat alert data distribution service is provided by that MCC, in accordance with document C/S P.011 "Cospas-Sarsat Programme Management Policy".

An MCC service area is defined by the list of SPOCs to which that MCC distributes Cospas-Sarsat alert data. The list of countries / regions included in the service area of each MCC is provided at Annex I / A of this DDP.

Nothing in this DDP or other Cospas-Sarsat System documents prevents the parties from adopting other arrangements more suitable for the distribution of Cospas-Sarsat alert data at some future date.

It is essential that MCCs establish appropriate arrangements with all the countries / SPOCs in their service area on communication links to be used for the distribution of alert data. If such arrangements have not been made for a particular country in the MCC service area, the MCC shall notify its own national SAR authorities of any Cospas-Sarsat alert in that country's SRR, for handling in accordance with national SAR procedures.

As new SPOCs are identified, either through agreements with Cospas-Sarsat or via other channels, they will be incorporated into existing MCC service areas by mutual consent of the SPOC national authority and the appropriate MCCs. All MCCs should be notified of new SPOCs.

2.4 Data Distribution Regions

A data distribution region (DDR) comprises two or more MCC service areas. Cospas-Sarsat alert data and System information are exchanged between DDRs through a single MCC which acts as the point of contact for that DDR. This MCC is identified as the nodal MCC of the DDR. However, bilateral arrangements can be implemented between adjacent MCC service areas included in different DDRs to facilitate the exchange of alert data in overlapping service areas or adjacent search and rescue regions.

The DDR structure of the Cospas-Sarsat data distribution network is defined at Annex II / A of the DDP, together with the specific arrangements for the exchange of alert data in each DDR.

2.5 General Flow of System Information

System information assists in the operation of the Cospas-Sarsat System. This information includes Cospas-Sarsat satellite ephemeris and time calibration data that affect location processing, messages used for commanding the satellite SAR instruments, and notification messages providing the status of System elements. The flow of System information through the Cospas-Sarsat System is detailed in section 3.5.

- END OF SECTION 2 -

This document has been superseded
by a later version

3. PROCEDURES

3.1 General Procedures for the Distribution of Cospas-Sarsat Alert Data

3.1.1 Introduction

Alert data (or “alert”) is the generic term for Cospas-Sarsat alert and position data derived from 406 MHz distress beacon signal processing. Alert data derived from beacon signals contains the beacon identification and may contain beacon position information and other coded information.

Beacon signals are relayed via three search and rescue (SAR) satellite systems, low Earth orbit (LEOSAR), geostationary Earth orbit (GEOSAR) and medium Earth orbit (MEOSAR). Position data can be derived in three ways:

- by Doppler processing via the tracking of a LEOSAR satellite receiving 406 MHz beacon transmissions,
- by difference of arrival (DOA) processing using time of arrival (TOA) and frequency of arrival (FOA) measurements received from multiple MEOSAR satellites relaying the same beacon transmissions,
- by position data encoded in beacon messages.

MCCs receive alert data from their LUTs or from other MCCs and distribute this alert data to the appropriate RCC or SPOC in their service area, or forward the alert data to another MCC. Alert data received from a single LEOSAR satellite pass or in a single MCC message shall be processed in TCA or detection time order. MCCs shall transmit Cospas-Sarsat alert data in accordance with the principles for data distribution listed in section 2.2 of this Cospas-Sarsat Data Distribution Plan (DDP). The corresponding procedures are outlined in Figure 3.1, and in the following sections. These procedures are further detailed at Annex II / B of this DDP.

3.1.2 Geographical Sorting of Alert Data

Except for ship security alert data (described in section 3.2.6), alert data are distributed according to the geographical sorting of the available position(s). The geographical distribution of alert data is organized as follows:

- a) Beacon position is within an MCC's service area:

An MCC that receives alert data for a beacon position in its own service area forwards the alert data to the appropriate SPOC or national RCC, in accordance with the applicable Cospas-Sarsat or national procedures.

- b) Beacon position is within another MCC's service area:

An MCC that receives alert data for a beacon position in another MCC's service area forwards the alert data to the appropriate MCC, in accordance with the applicable Cospas-Sarsat procedures as described in the Annexes II / A and II / B to this DDP.

c) Unlocated alerts:

There will be occasions when a LEOLUT or MEOLUT is unable to calculate a location for a beacon or a beacon is detected by a GEOLUT, and the only information available is the beacon message. If this data does not contain an encoded position, the alert is unlocated. In these cases the only information available will be the digital identification contained in the beacon message which includes a country code designating the country of registration of the beacon. MCCs shall transmit this information to the country of registration according to the procedure described in section 3.2.8.

3.1.3 Message Formats

Alert messages are exchanged between MCCs using standard formats which permit automatic processing and retransmission of all data. These message formats are defined in the Cospas-Sarsat Mission Control Centres Standard Interface Description (C/S A.002). A list of message formats that are implemented at each MCC is provided at Annex II /B of this DDP.

3.1.4 Beacon Identification

MCCs when transmitting narrative messages and making reference to beacon identification should take particular care in providing the identification as 15 contiguous hexadecimal characters comprising bits 26 to 85 of the beacon message. If a location protocol beacon is involved, the coarse position fields shall be set to the specified default values.

Figure 3.1: 406 MHz Alert Data Distribution Procedures (1/2)

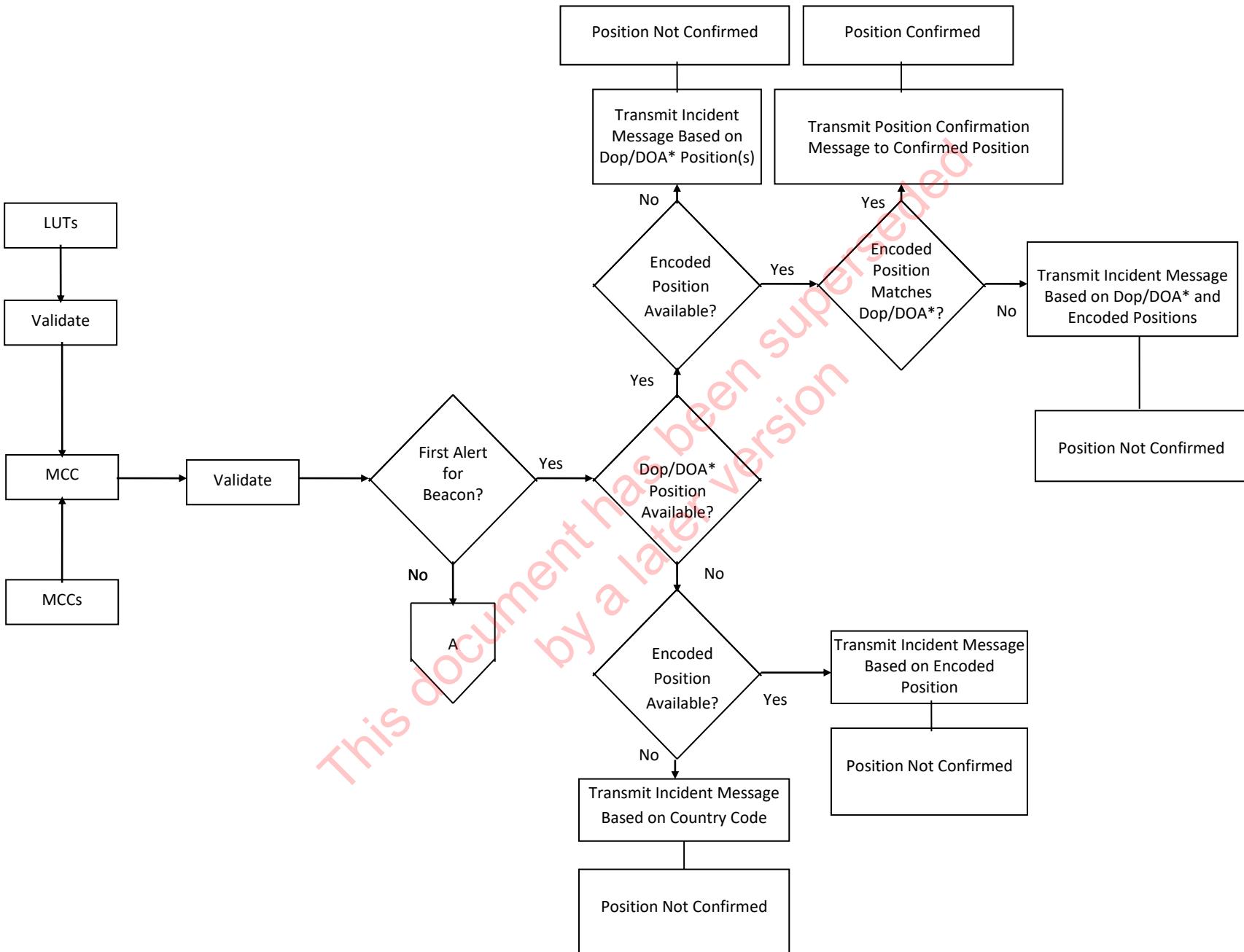
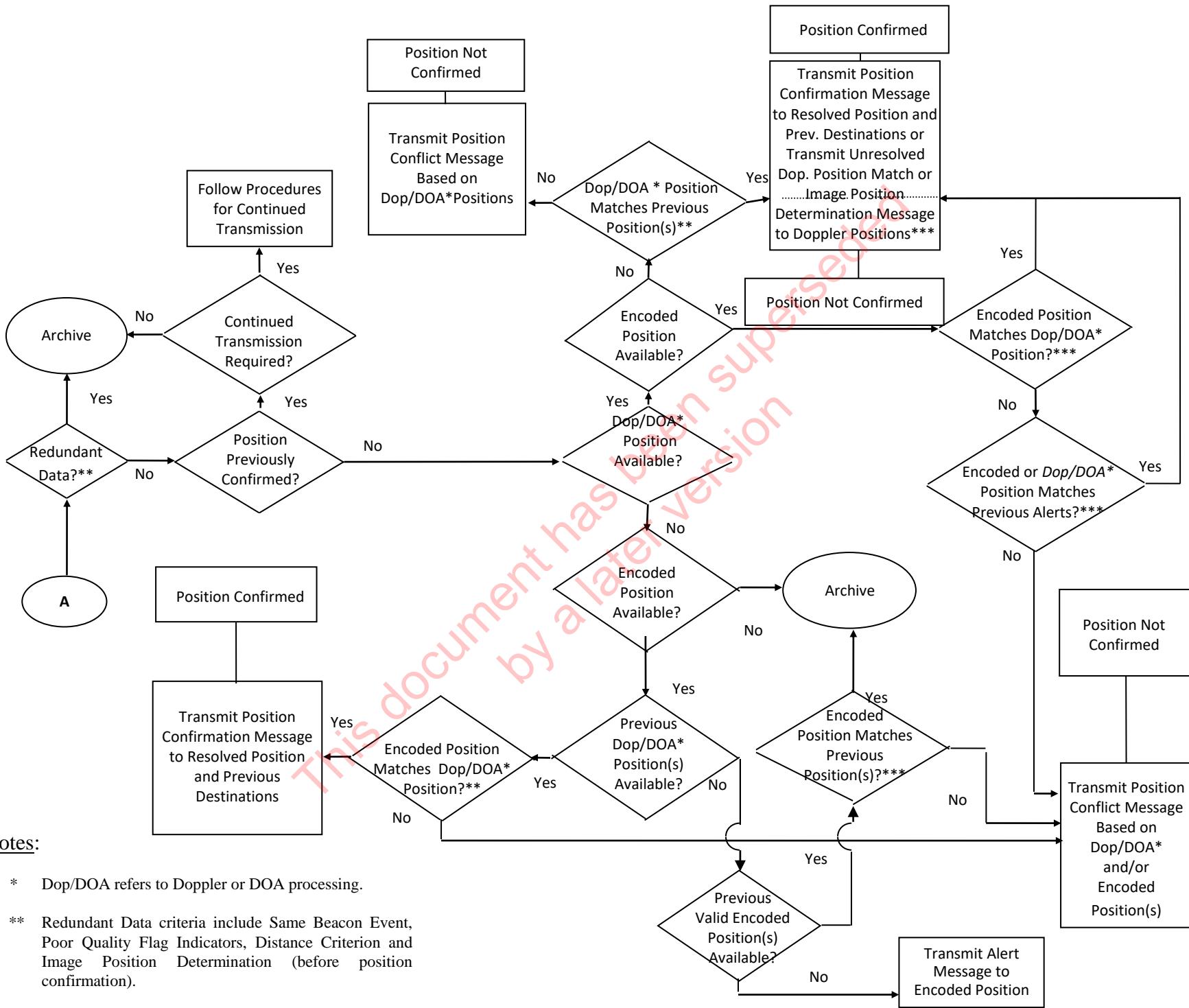


Figure 3.1: 406 MHz Alert Data Distribution Procedures (2/2)



3.2 Alert Data Distribution Procedures

3.2.1 Doppler, DOA and Encoded Positions

Position data provided by LEOLUT Doppler processing, provided by MEOLUT DOA processing, and encoded in beacon messages, constitute independent sources of beacon position information. All types of position data are used by MCCs in the filtering and geographical sorting process, and distributed with alerts to RCCs and / or SPOCs, in accordance with the procedures described hereunder.

An MCC shall verify that each alert location that it receives is inside the footprint of each satellite through which it was detected per the associated alert message, using the algorithm described in the Appendix “Determining the Satellite Footprint Check” in document C/S A.002. If a Doppler or DOA position fails this footprint check, then:

- a) the Doppler or DOA position data shall be processed;
- b) a warning shall be provided about the out of footprint position data in the alert distributed to a SPOC or RCC (per document C/S A.002); and
- c) the MCC operator shall be notified.

If an encoded position fails this footprint check, then the encoded position shall not be processed.

3.2.2 Validation of Beacon Message Data

Under various circumstances such as interference, weak beacon signals or high noise levels, the LUT processing can produce erroneous alert data (i.e., processing anomalies) which may cause false alerts.

The alert data produced by the LEOLUTs, GEOLUTs and MEOLUTs must be validated in accordance with the requirements of documents C/S T.002, C/S T.009 and C/S T.019, respectively. In addition, to avoid propagating invalid alerts through the Cospas-Sarsat Ground Segment, the procedure for validating alert data described at Annex II / B of this DDP shall be implemented at the MCC level to satisfy the requirements of document C/S A.005.

3.2.3 Processing Multiple Alerts for the Same Beacon Identification

After validation, alert data received by an MCC shall be compared to previous information concerning the same beacon identification which has already been processed by that MCC.

3.2.3.1 Resetting Beacon Activation Status

If the satellite detection time or time of closest approach of a new alert is more than 18 hours after the detection time of the latest alert distributed by the MCC for the same beacon identification, then:

- a) the new alert shall be treated as a new beacon activation (i.e., the beacon activation status word (Sw) is reset to zero, per Annex II / B.5); and
- b) all alerts with any associated detection time not after all associated detection times of the latest alert distributed by the MCC for the previous beacon activation shall be filtered from MCC processing of the new beacon activation.

MCCs may reset the beacon activation status (i.e., open a new alert site) prior to the expiration of this time threshold based on other criteria.

3.2.3.2 Filtering of Redundant Data

Position data from LEOLUT, GEOLUT and MEOLUT alerts shall be matched using the distance criteria defined at Annex II / B of this DDP and the criteria for Position Confirmation described in section 3.2.4.

Alert data produced by LEOLUTs is considered to be for the same beacon event when it has the same beacon identification (ID), same spacecraft and same time of closest approach (TCA) \pm 20 minutes; otherwise LEOLUT alert data is considered to be for a different beacon event.

Prior to position confirmation, LEOLUT alert data for the same beacon ID is not redundant if it can be used to confirm the position, because either:

- a) Doppler position data in the new alert matches Doppler position for a different beacon event in a previous LEOLUT alert; or
- b) Doppler position data in the new alert matches DOA position in a MEOLUT alert; or
- c) Doppler position data in the new alert matches encoded position in a previous alert; or
- d) encoded position in the new alert matches either:
 - i. Doppler position in the same alert, or
 - ii. Doppler position in a previous alert, or
 - iii. a DOA position.

Otherwise, LEOLUT alert data for the same beacon ID is deemed to be redundant if:

- a) the new alert message does not include Doppler position data and the encoded position matches encoded position information received earlier by the MCC; or

- b) position was previously confirmed, the new alert message includes Doppler position data, a Doppler position in the new alert matches the confirmed position, and either:
 - the new alert message does not include encoded position data, or
 - the encoded position data in the new alert message matches encoded position information received earlier by the MCC; or
- c) the new alert message includes Doppler position data, each Doppler position in the new alert matches a Doppler position in one alert received previously for the same beacon event and, either:
 - the new alert message does not include encoded position data, or
 - the encoded position data in the new alert message matches encoded position information received earlier by the MCC; or
- d) an alert with the same beacon ID has already been processed for the same beacon event and the new alert message does not include Doppler position data or encoded position data.

Before position confirmation, LEOLUT alert data for the same beacon event should not be considered redundant if it contains information on image position determination not previously received (see document C/S A.002, Appendix B.2 to Annex B entitled “Validating the Satellite Footprint and LEOSAR Image Position”).

Alert data produced by MEOLUTs is considered to be a dependent beacon event based on the criterion for setting the ‘Dependent Beacon Event’ flag defined at Annex II / B of this DDP.

Prior to position confirmation, MEOLUT alert data for the same beacon ID is not redundant if it can be used to confirm the position, because either:

- a) DOA position data in the new alert matches DOA position for a non-dependent beacon event; or
- b) DOA position data in the new alert matches a Doppler position; or
- c) DOA position data in the new alert matches encoded position in a previous alert; or
- d) encoded position in the new alert matches either:
 - i. DOA position in the same alert, or
 - ii. DOA position in a previous alert, or
 - iii. a Doppler position.

Otherwise, MEOLUT alert data for the same beacon ID is deemed to be redundant if either:

- a) the new alert message does not include DOA position data and the encoded position matches encoded position information received earlier by the MCC; or
- b) the new alert message includes DOA position data, the DOA position in the new alert matches a DOA position in an alert received previously for a dependent beacon event and, either:
 - the new alert message does not include encoded position data, or
 - the encoded position data in the new alert message matches encoded position information received earlier by the MCC; or
- c) an alert with the same beacon ID has already been processed for a dependent beacon event and the new alert message does not include DOA position data or encoded position data.

However, prior to position confirmation, a dependent beacon event alert shall be transmitted if:

- a) the time of the latest beacon burst used to compute the new DOA position is more than 5 minutes after the time of the latest beacon burst used to compute all previously sent DOA positions; or
- b) the new alert has better quality DOA position, per the procedure “Distribution of Alerts with Better Quality DOA Position” in section 3.2.3.3; or
- c) the new alert is a position conflict alert.

Prior to position confirmation, GEOLUT alert data for the same beacon ID is not redundant if it can be used to confirm the position, because encoded position in the new alert matches either Doppler or DOA position in a previous alert.

Otherwise, GEOLUT alert data produced by GEOLUTs for the same beacon ID identification is deemed to be redundant if:

- a) the new alert message does not include encoded position data; or
- b) the encoded position data in the new alert message matches encoded position data received in an earlier message.

To minimize redundant message traffic in the Ground Segment, MCCs shall not distribute alert data which have been determined as redundant in accordance with the procedure described at Annex II / B of this DDP. MCCs shall distribute alert data which have not been determined to be redundant.

The matching test for new encoded position data shall be performed with all encoded position data previously received and forwarded (i.e., not deemed redundant) for the same beacon ID, taking into account whether the encoded position is coarse (i.e., without usable encoded position in the second protected field of the beacon message) or refined (i.e. with usable encoded position in the second protected field of the beacon message), as follows:

- a) if the new encoded position is refined, and
 - i. no previous refined encoded position has been sent, then the new encoded position is sent regardless of the difference with any previously sent coarse encoded position (and the alert will be distributed as a “position update”), else
 - ii. another refined encoded position was previously sent, then the new encoded position is sent if it:
 - a. does not match any previously sent refined encoded position, or
 - b. it has a detect time more recent than any previously sent refined encoded position and does not match any previously sent refined encoded location with the most recent detect time; and
- b) if the new encoded position is coarse, and
 - i. it matches the position encoded in the first protected field of a previously sent beacon message, then it shall be deemed redundant, else
 - ii. the new encoded position is sent if it does not match any previously sent encoded position (coarse or refined).

LEOSAR, GEOSAR and MEOSAR data deemed to be redundant shall not be used to determine whether subsequent data is redundant.

3.2.3.3 Distribution of Alerts with Better Quality DOA Position

Before or after position confirmation, a new alert with DOA position shall be transmitted if the expected error (Message Field 89 in document C/S A.002) is available (i.e., set to a non-default value) for a previously transmitted DOA position and the expected error of the new DOA position is:

- a) less than 150 nm (277.8 km); and
- b) at least 2 nm (3.704 km) less than the lowest expected error for all previously transmitted DOA position alerts; and
- c) at least 50% less than the lowest expected error for all previously transmitted DOA position alerts.

Each of the above criteria shall be independently configurable.

3.2.4 Confirmation of 406 MHz Positions

The objective of this process is to confirm the position of a beacon on the basis of information provided by two independent sources.

A Doppler location always includes two sets of position data, the ‘true’ and the ‘image’ solutions which are symmetrical relative to the trace of the orbit. Each solution is associated with a probability which is generally sufficient to resolve the Doppler ambiguity. However, the actual characteristics of the 406 MHz transmission are not known by the receiving LUT and reliable ambiguity resolution of the Doppler solutions can only be achieved with a set of Doppler positions from a different beacon event, a DOA position, or an external source of data such as position data encoded in the beacon message. Ambiguity resolution is a specific type of position confirmation; the ‘true’ position is a type of confirmed position, the ‘image’ position is a type of incorrect position and an unresolved (Doppler) position is a type of unconfirmed position.

While a DOA position does not have inherent ambiguity, confirmation of a DOA position is required as errors may occur. Confirmation of a DOA position can only be achieved with a DOA position from a different beacon event, a Doppler position, or an external source of data such as position data encoded in the beacon message.

A beacon message with encoded position data provides a unique position which may be very accurate. However, errors may occur and confirmation of the encoded position via an independent source is desirable. As several alert messages from the same beacon received through different satellites and/or different LUTs can all originate from the same beacon transmission and, therefore, from the same navigational data, confirmation of encoded position data can only be provided by a Doppler or DOA position matching the encoded position.

Therefore, independent position information will consist of:

- a) Doppler positions obtained from two different beacon events;
- b) Doppler position and encoded position data;
- c) DOA positions obtained from two different beacon events;
- d) DOA position and encoded position data; or
- e) Doppler position and DOA position.

The beacon position is confirmed only if two independent sets of position data match the distance criteria specified at Annex II / B of this DDP.

Alert data for beacons located outside an MCC’s service area shall be forwarded until position is confirmed. Prior to position confirmation, alert data shall be transmitted to all previous message recipients. Once position is confirmed, a position confirmation

message shall be transmitted to each MCC and/or SPOC that has the resolved position or a previous incorrect position in its MCC service area, or its SAR Region(s), respectively.

3.2.5 Continued Transmission after Position Confirmation

Continued transmission of alert data after position confirmation may be requested by an MCC or SPOC. An MCC requesting continued transmission by another MCC shall also request continued transmission by any nodal MCCs involved in the distribution of the continued transmission alert data.

After position confirmation, alert data shall not be geographically sorted according to the received position, but sent to the same MCC or SPOC that has the resolved position in its MCC service area or its SAR Region, respectively, or requested continued transmission. Ship security alerts are not sent based on the received position, as described in section 3.2.6.

Alert data shall not be distributed after position confirmation to an MCC that has requested that it not receive alert data for its service area after position confirmation. Therefore, nodal MCCs (and Central DDR MCCs) shall be capable of filtering alert data after position confirmation based on the request of the destination MCC. MCCs that do not want to receive alert data after position confirmation shall notify other MCCs of this request, and shall request the Secretariat to update the associated table on the Cospas-Sarsat website.

After position confirmation, MCCs shall send a new alert when:

- a) a non-redundant encoded position is received (per section 3.2.3); or
- b) Doppler position is received for a new beacon event; or
- c) a Doppler position conflict alert is received for the same beacon event, provided that the new alert has sufficient quality (per section II/ B.4);
- d) the new alert has better quality DOA position, per the procedure “Distribution of Alerts with Better Quality DOA Position” in section 3.2.3.3; or
- e) a DOA position alert matching the confirmed position is received, provided that the time of the latest beacon burst used to compute the new DOA position is more than 15 minutes after the time of the latest beacon burst used to compute all previously sent DOA positions that matched the confirmed position; or
- f) a DOA position conflict alert is received, provided that the time of the latest beacon burst used to compute the new DOA position is more than 10 minutes after the time of the latest beacon burst used to compute all previously sent DOA position conflict alerts.

3.2.6 Exchange of Ship Security Alerts

Ship security alerts are initiated and transmitted by vessels whose security is threatened and who need to notify a competent authority designated by the flag state. The transmission of ship security alerts is based on the country code contained in the beacon identification, which is then used to route the alert to the appropriate MCC or competent authority.

MCCs will exchange ship security alerts using the formats specified in the document C/S A.002 and according to the ship security alert distribution procedures described in Annex II / B of this DDP.

An MCC shall transmit a ship security alert only to the MCC or competent authority associated with the country code. An MCC shall not transmit a ship security alert to the RCC or SPOC associated with the location of the alert.

3.2.7 Requesting Transmission of Alerts

MCCs, SPOCs or RCCs may request transmission of alerts by geographical area or 15-hexadecimal beacon identifier.

If the request is by geographical area, then the request should specify the area for which new alerts would be provided, either as a radius in nautical miles around a position or as a rectangle defined by two opposing corner positions.

The request should indicate the MCCs that would receive alerts for that area in real time. A nodal MCC that receives a request for transmission shall forward the request to the appropriate MCCs, to ensure that the requested alerts are sent.

The requesting agency should indicate when transmissions are to be discontinued.

3.2.8 Exchange of Unlocated Alerts

When a LEOLUT or MEOLUT is unable to calculate a location for a beacon, or a beacon message is detected by a GEOLUT, the only information available is the beacon message. If this data does not contain an encoded position, the alert is unlocated. An unlocated alert shall be distributed using the country code in the beacon identification for routing to the appropriate MCC or SPOC, so that the unlocated alert is distributed to the country that maintains the beacon registry for the country code contained in the 406 MHz beacon message, as provided on the Cospas-Sarsat website "Contact List" for "406 MHz Beacon Registers (available 24/7 for SAR services)". Unlocated alerts shall be validated at LUT and MCC level in accordance with the applicable procedure.

MCCs shall exchange unlocated alert messages using the formats specified in the document C/S A.002 and according to the alert distribution procedures described in Annex II / A of this DDP.

Prior to position confirmation, an MCC shall transmit an unlocated alert message only if no position information has been received previously for the same beacon identification. To increase the probability of Image Position Determination (as defined in document C/S A.002), multiple LEOLUT/GEOLUT unlocated alert messages may be transmitted for a beacon, provided that:

- a) only one unlocated alert message is sent per GEOSAR satellite; and
- b) only one unlocated alert message is sent per LEOSAR satellite beacon event.

3.2.9 Combined LEOSAR/GEOSAR/MEOSAR Processing

For the purposes of alert data distribution procedures, solutions derived from combined LEOSAR/GEOSAR processing shall be treated as LEOSAR alerts. Solutions derived from MEOSAR processing that contain LEOSAR and/or GEOSAR data shall be treated as MEOSAR alerts.

3.2.10 Filtering Old Alert Data

Alert data with a detect time older than 24 hours shall be filtered.

3.3 Notification of Country of Beacon Registration (NOCR) Service

The NOCR service provides notification to the SPOC of a country when an alert is located outside of that country's SRR for a beacon registered to the country. The NOCR service ensures that a country is notified whenever one of its beacons is activated. The NOCR service is especially beneficial when a distress alert is located in an area of the world where suitable search and rescue resources are not available to perform the SAR mission. This service provides the parties responsible for the vessel, aircraft, or persons in distress an opportunity to assist the SAR services in their response to the emergency situation.

An NOCR message should not be interpreted as a request for information. If necessary, requests for information regarding the vehicle carrying a particular beacon should be made to the beacon registry.

The detailed procedure for the NOCR service is described in section II / B.7.

3.4 Exchange of Beacon Registration Information

It is essential that every country using beacons maintain a register where SAR agencies can obtain vital information at any time. The maintenance of such a register is a national responsibility and the release of information is subject to national regulations.

Each country using beacons should make appropriate arrangements to ensure 24-hour access to their national register(s) by SAR services and inform Cospas-Sarsat of their

point of contact. Cospas-Sarsat Participants should also make appropriate arrangements with the associated MCC listed on the Cospas-Sarsat website, to ensure fast and easy access to its national register via the associated MCC.

IMO Assembly Resolution A.887(21) concerning registration databases of satellite EPIRBs requires the EPIRB identification code to be included in the database amongst other SAR related information. It is possible that the only means to query a database would be through the beacon ID and thus it is imperative that the correct beacon ID usage be applied. The beacon ID, as described in the Cospas-Sarsat Glossary (document C/S G.004) and in the “Acronyms and Terminology” page on the Cospas-Sarsat website, available at <http://www.cospas-sarsat.int/en/pro>, under the Documents menu, should be used whenever requests for beacon registration information are made or provided.

3.5 System Information

System information messages include ephemeris or orbit vector messages, time and frequency calibration messages, spacecraft telemetry and commands, Ground Segment elements and spacecraft operational status, and narrative messages. Figure II / A.8 shows the network structure for System information distribution and indicates the senders and receivers of each type of System information. Orbitography beacons also provide System information. MCCs shall send orbitography and reference beacon data to the associated nodal MCC to satisfy the Cospas-Sarsat Quality Management System (QMS) continuous monitoring and objective assessment process described in document C/S A.003. Information on orbitography beacons can be found on the Cospas-Sarsat website at www.cospas-sarsat.int.

The CMC and the USMCC distribute orbit ephemeris data for the Cospas and Sarsat spacecraft daily. They automatically receive, process, confirm by their own calculations and transmit the ephemeris data to the other MCCs and their own LUTs.

Search and Rescue Repeater (SARR) frequency calibration offset data for a given LEOSAR satellite is used by those LEOLUTs which perform combined LEO/GEO processing to adjust the SARR frequency measurements obtained from that LEOSAR satellite. SARR frequency calibration offset information is computed at the CMCC using a reference beacon. The CMCC automatically sends SARR frequency calibration offset messages to other MCCs once per week, as needed. SARR frequency calibration offset will be computed and distributed by the CMCC for all LEOSAR satellites which have an operational SARR channel.

Time calibration data is used to convert the Sarsat Search and Rescue Processor (SARP) time code to co-ordinated universal time (UTC). Time information provided for each 406 MHz data point must be corrected for computing the beacon location. Time and frequency calibration information for the Sarsat SARP is computed at the FMCC using signals from a time calibration platform relayed through Sarsat spacecraft. The FMCC automatically sends SARP time calibration messages to other

MCCs once per week. Time calibration is not required for processing SAR incident data from Cospas spacecraft.

Sarsat payload commands requested by the CMCC (for the SARR), the FMCC (for the SARP), or the USMCC are co-ordinated, validated and then automatically forwarded by the USMCC to the NOAA Satellite Operations Control Center (SOCC) for transmission to the NOAA spacecraft. Verification of command execution is sent from the NOAA SOCC to the USMCC for transmission to the FMCC or CMCC. The Cospas payload commands are generated by the CMC.

Narrative and coordination messages are exchanged between the MCCs. Requests for retransmissions of messages will be addressed to the appropriate MCC. System information will be archived until it is updated, and retrieved and transmitted when requested.

Changes in the distribution of System information will be subject to review at regular Cospas-Sarsat Council meetings. Changes in orbitography beacon information may be updated by System status messages sent to other MCCs.

3.6 System Status Changes

System status changes are the result of System element and System function failures, scheduled maintenance, integration or testing of new System elements, and the commissioning of new equipment or new capabilities of existing equipment. These changes will impact the operation of the Cospas-Sarsat System and should be notified to appropriate MCCs.

Space Segment Providers shall initiate System status messages to all MCCs whenever Space Segment out-of-limit conditions or changes occur, and when changes in the satellite SAR equipment are scheduled. The FMCC shall initiate notification of changes for Galileo satellites and EUMETSAT Meteosat Second Generation (MSG) satellites on behalf of the associated Space Segment Providers. Ground Segment Operators shall initiate System status messages for changes of Ground Segment status. All changes of System status shall be notified by MCCs in accordance with this section and Annex II / A of this DDP.

3.6.1 Space Segment Status

Space Segment Providers shall provide notice to all Ground Segment Operators on the operational status of the spacecraft payloads in accordance with documents C/S T.004, C/S T.013 and C/S T.017. Payload status shall be declared with a System status message as described in Annex I / C. Distribution of satellite ephemeris and SARP time calibration data, which may precede declaration of Initial Operational Capability (IOC) status, shall not itself be understood as a declaration of IOC status.

A satellite that is in IOC status shall be treated as though it were operational except that Ground Segment Operators may at their option elect to not acquire data from it via their LUTs. All Ground Segment Operators shall process alerts generated by other MCCs from this satellite data in their MCCs. It is recommended that satellites in IOC status be given lower priority in LUT scheduling.

3.6.2 Changes of Operational Capabilities

Changes of operational capabilities resulting from new equipment or new processing which impact the operation of the Cospas-Sarsat System, should be notified by the responsible MCC in accordance with Table 3.1 and Figure II / A.8.

Changes of System status resulting from the decommissioning of System equipment should be notified by the responsible MCC to all MCCs in accordance with Figure II / A.8.

Failure or Outage	Notification Level
Space Segment	- All MCCs should be notified
MCC	- All MCCs and the reporting MCC's SPOCs should be notified
LUT	- All MCCs should be notified
Communication Networks	- Only affected MCCs should be notified
Orbitography beacons	- All MCCs should be notified

Table 3.1: Notification Level for Failure or Outage

3.6.3 System Failures

System status changes resulting from either a failure or outage of a System element or a System function should be reported to the appropriate MCC in accordance with Table 3.1 and the System Information Flow Diagram of Figure II / A.8. Nodal MCCs shall update System element status in the appropriate section of the Cospas-Sarsat website in accordance with the Cospas-Sarsat Quality Management System (QMS) continuous monitoring and assessment process, as described in document C/S A.003.

3.6.4 Scheduled Outages

System status changes for any System element or function which result from scheduled outages for maintenance, integration or testing, should be notified by the responsible MCC to all MCC(s) and SPOCs in accordance with Table 3.1 and Figure II / A.8. The responsible MCC should provide advance notification as early as possible before interrupting operations, including a description of the planned backup arrangements (see section 3.7 and Annex I / A). Additionally, the responsible MCC should repeat the notification 24 hours prior to the scheduled activity.

The MCC that performs a backup shall inform by a narrative message SIT 915, the non-operational MCC's SPOCs of the failure of their associated MCC and that the originating MCC is performing backup service according to section 3.7 of document C/S A.001.

3.6.5 Scheduled Satellite Manoeuvres

Some LEOSAR satellites are subject to scheduled manoeuvres periodically, in order to maintain their sun synchronous orbit and thus to increase their useful life.

A satellite may be manoeuvred in two ways, in-plane or out-of-plane. An in-plane manoeuvre is issued to counteract the effect of drag on the semi-major axis. An in-plane manoeuvre changes satellite position by an amount that increases with each subsequent orbit. An out-of-plane manoeuvre is issued to counteract the effects of Luni-solar pull on inclination. An out-of-plane manoeuvre changes satellite position by an amount that does not increase with subsequent orbits.

A satellite manoeuvre may induce significant Doppler location errors, due to the possible application of incorrect orbit vectors by LEOLUTs. In order to mitigate the impact of planned satellite manoeuvres on Doppler location accuracy, MCCs shall implement the following procedures.

For each satellite that is subject to scheduled manoeuvres, one MCC shall be responsible for notification about its manoeuvres and is designated the responsible MCC. The USMCC is the responsible MCC for the manoeuvres of all LEOSAR satellites with Sarsat payloads.

The responsible MCC shall provide notification to all MCCs of the scheduled satellite manoeuvre. The responsible MCC shall provide notification 5 to 7 days in advance of a scheduled satellite manoeuvre, to allow Ground Segment Providers adequate preparation time. The responsible MCC shall repeat the notification 24 hours prior to the scheduled manoeuvre. The responsible MCC shall provide notification of the execution of the satellite manoeuvre as soon as possible after the manoeuvre is complete. If the maximum expected change in satellite position is more than 2 km in the 24 hours following completion of the manoeuvre, then the responsible MCC shall provide new orbit vectors for the satellite as soon as possible after the manoeuvre is

complete. Orbit vectors associated with a satellite manoeuvre shall be provided in a SIT 216 message.

Notification of a satellite manoeuvre shall be provided in a System status message as described in Annex I / C, Figure I / C.2 and in accordance with Figure II / A.9. The responsible MCC shall provide information on the magnitude and duration of the expected change in satellite position. The magnitude should be provided for the 24 hour period after the manoeuvre, when possible, since the impact of the change should be negligible after 24 hours.

Based on notification of a satellite manoeuvre, MCCs shall:

- a) treat orbit ephemeris data received in a SIT 216 message within 24 hours after the end of the manoeuvre as valid, if they are within the maximum tolerance specified for the satellite in the associated System status message;
- b) use the validated SIT 216 orbit ephemeris data to immediately initialise orbit vectors at the MCC and its associated LUTs; and
- c) notify its RCCs and SPOCs, if the maximum expected error in Doppler location exceeds 10 kilometres within 24 hours of the manoeuvre.

MCC responsibilities for scheduled satellite manoeuvres are outlined in Figure 3.2.

3.6.6 Reactivation of the SARP Instrument

On occasion, the SARP instrument on a satellite with a Sarsat payload is deactivated, due to an unexpected or a scheduled outage. Since accurate SARP time calibration (TCAL) data is required to compute accurate Doppler locations from SARP data, it is necessary that LEOLUTs be updated with new SARP TCAL data after the SARP instrument is reactivated, prior to computing Doppler solutions from SARP data. In order to mitigate the impact of SARP reactivation on Doppler location accuracy, MCCs shall implement the following procedures.

As the MCC responsible for the SARP instrument on satellites with a Sarsat payload, the FMCC provides notification about the reactivation of the SARP instrument. The FMCC shall provide notification that new SARP TCAL data will be distributed, as far in advance as possible, in order to allow adequate preparation time for each Ground Segment Provider. The notification shall be provided in a System status message as described in Annex I / C, Figure I / C.3, and should include the time it is expected that new SARP TCAL data will be sent to other MCCs, as available.

The FMCC shall provide new SARP TCAL data (in a SIT 415 or 417 message) as soon as reliable SARP TCAL data is available.

When notification about new SARP TCAL data is received by the MCC, each Ground Segment Provider shall:

- a) ensure that the calibration time (per document C/S A.002, Message Field 37) in the new SARP TCAL data is treated as valid in its MCC, without regard to previous SARP TCAL data. The Ultra-Stable Oscillator (USO) frequency (C/S A.002, Message Field # 38) shall be validated per normal procedures;
- b) ensure that the new SARP TCAL data (validated as noted above) is used to initialise the SARP TCAL data in its LEOLUTs, without regard to previous SARP TCAL data; and
- c) ensure that all Doppler solutions generated by its LEOLUT(s) that contain SARP data for the associated satellite are filtered, until new SARP TCAL data is loaded into the associated LEOLUT.

Once new SARP TCAL data is processed by MCCs and LUTs, each Ground Segment Provider shall resume normal validation of SARP TCAL data for the satellite, unless contrary notification is received from the FMCC.

3.6.7 Space Segment Anomaly Reporting Procedures

Any Ground Segment Provider which detects anomalies of the Space Segment during routine system monitoring, shall inform the relevant Space Segment Provider so that special tests can be conducted and appropriate notification can be provided. Analysis of Space Segment anomalies shall be coordinated among the relevant Space Segment Providers and possible corrective action (e.g., switch to backup payload) will be taken, as appropriate.

Information on any anomalies which could significantly degrade system performance shall be provided by the MCC associated with the relevant Space Segment Provider:

- a) in a System status message as described in Annex I / C, Figure I / C.4; and
- b) to the Secretariat.

The MCC associated with the relevant Space Segment Provider shall provide status updates on spacecraft anomalies at least once per week until the anomaly ends or its effects are mitigated. Further information on Space Segment Status Reporting Procedures is provided in documents C/S T.004, C/S T.013 and C/S T.017.

3.7 Contingency Procedures

3.7.1 Operational Backup

In general, each LUT and MCC tests itself and notifies the operator of an improper condition. Should the equipment become non-operational, the responsible MCC will notify other MCCs as described in section 3.6 by the best means available. Alternative MCCs and communication links could be designated for routing message traffic and assuming some of the functions of the non-operational MCC, in accordance

with predetermined backup procedures described in Annex I / A or following direct coordination with other relevant MCCs.

The MCC serving as the backup MCC may support the RCCs/SPOCs of the non-operational MCC directly, or by routing message traffic to a SAR authority nominated by the non-operational MCC. Non-operational MCCs should recognize the additional workload placed on the backup MCC and provide all possible support when operating in the contingency scenario.

When an MCC assumes backup for another MCC, it shall send notification to each destination (i.e., MCC, RCC/SPOC and SAR authority) for which it will deliver alert data directly on behalf of the MCC being backed up. To ensure that the communication link to the destination is working successfully, this notification shall:

- a) be sent by the communication link that will be used to deliver alert data; and
- b) include a request for acknowledgement, if the communication link to the destination has been not been successfully used in the last 6 hours.

Backup procedures for the distribution of System information and alert data should be described for each MCC in the relevant section of Annex I / A. Any MCC may also communicate directly with any other MCC and an MCC shall respond to direct requests for information.

During back-up conditions MCCs may redirect message traffic to the backup MCC without effecting any change to the SIT destination, MF#5 (i.e., Message Field # 5 per document C/S A.002). Each MCC is to specify their redirection capability in its backup procedures. MCCs shall not transmit QMS data to the backup nodal MCC.

When an MCC that originates System data (e.g., the USMCC originates orbit data) is not operational, the MCC that backs up the non-operational MCC is not expected to originate the system data, unless this capability is identified in the published backup procedure. In addition, requests for beacon registration data should be made directly of the non-operational MCC and not the backup MCC.

3.7.2 Backup Test

Annually, each MCC should arrange to test its backup procedures. This test should include the exercise of each specific action listed in the backup procedures and agreements section described in Annex I / A to this DDP. Each MCC should review the results of the testing, and document problems for corrective action. To ensure that the backup testing does not impact operational activity within a DDR, each nodal MCC should co-ordinate backup testing within its DDR. Each MCC should also report the backup test results to the Cospas-Sarsat Secretariat as part of their annual report on System Status and Operations (as described in document C/S A.003). In addition, each MCC should perform a quarterly test of all backup communication

methods. Each MCC should review the results of the tests and document problems for corrective action.

The annual backup test will not be required if the backup procedure has been successfully exercised for a period of time not less than 6 hours during the year prior to the planned annual test, taking care to ensure that no more than one year passes between the tests. The backup test will take place for at least 6 hours to ensure the Cospas-Sarsat Quality Management System objectives of providing timely and accurate alert data are met. Longer backup periods may be agreed bilaterally and described in the backup procedures and agreements section of Annex I / A to this DDP. A specific mention of this operational backup shall be noted in the annual status report.

The backup test between nodal MCCs should be conducted on a “no notice” basis, that is to say, no notification will be sent to non-nodal MCCs prior to the commencement of the test, in order to check the real-time reconfiguration ability and replicate as much as possible a real world scenario. The affected MCCs shall send a confirmation narrative message to the backup nodal MCC after reconfiguration. Administrators for affected MCCs may be notified prior to the commencement of the test, on a bilateral basis, in order to ensure that the test has maximum effectiveness.

The quarterly communication test shall also be considered to be accomplished when the backup procedure has been exercised during the quarter for a time period which meets the needs of the specific MCC operator.

3.7.3 Backup Timing

When an MCC is found to be unable to operate within the specifications of this document and of the MCC Specification and Design Guidelines (document C/S A.005), arrangements shall be made to switch the services from the failed MCC to a backup system, according to the backup procedures for the failed MCC, as described in the relevant section of Annex I / A. The timing of the switch to the backup system should be planned to ensure that the system will meet the requirement of the Cospas-Sarsat Programme Management Policy (document C/S P.011) that “the capability of an MCC to continuously deliver alert messages shall not be interrupted for longer than one hour”.

To meet this goal, the MCC operators shall, during the initial MCC testing or during subsequent tests of backup procedures, make note of the time required for the backup to take effect. The backup procedures shall then be established to ensure that, when an actual failure occurs, the backup arrangements shall be initiated early enough that the backup facility is expected to take over the service from the failed MCC within one hour of the original failure.

When an MCC is to be shut down for scheduled maintenance that is expected to last for more than one hour, the backup arrangements should be initiated before the MCC is shut down.

3.7.4 Long-term Backup and Restoration of Operations

This section summarizes the sequence of actions to handle a long-term MCC outage and to restore MCC operations.

If an MCC remains non-operational for 45 days after its initial failure, the associated nodal MCC shall notify the MCC that it is considered to be “commissioned, not operational” (CNO) and that it is preparing a plan for the re-assignment of MCC responsibilities. If the MCC remains non-operational for another 45 days, the associated nodal MCC shall coordinate alternate provisions for distribution of alert data to the SPOCs that were served by the “commissioned non-operational” MCC. If the associated nodal MCC is notified that an outage is expected to exceed 90 days, the associated nodal MCC shall coordinate alternate provisions for distribution of alert data to the SPOCs that were served by the CNO MCC as soon as possible. The sequence of events will be:

- Day 0 - Failure of the MCC is detected,
- Day 0-1 - Suitable backup arrangements are put in place,
- Day 2-45 - The associated nodal MCC is notified that this is a long-term issue,
- Day 45* - The associated nodal MCC notifies the non-operational MCC and the backup MCC of the CNO status, and that it is preparing a plan for the re-assignment of responsibilities,
- Day 90* - The nodal MCC coordinates the implementation of the alternate distribution plan.

(* These relative days indicate a maximum period; the events may occur earlier, based on the notification of a long-term outage.)

For the purposes of this re-distribution of responsibilities, the country that operates the non-operational MCC shall be considered as a SPOC until it has been restored to full operation.

When the CNO MCC indicates that it is ready to resume operations, the associated nodal MCC shall conduct a new set of commissioning tests as described in document C/S A.006. On successful completion of these tests, the associated nodal MCC shall declare the CNO MCC at Initial Operational Capability (IOC). Once the associated nodal MCC confirms that MCC performance is satisfactory for a time period that the associated nodal MCC determines is appropriate, the associated nodal MCC shall declare the MCC at full operational capability (FOC). When an MCC regains FOC status, data distribution procedures affected by the loss of FOC status shall be restored.

Whenever an MCC enters IOC, FOC or CNO status, the responsible nodal MCC shall notify all MCCs using a SIT 605 message, and update the MCC status associated with the Quality Management System (QMS) on the Cospas-Sarsat website.

3.7.5 Distribution of MEOSAR Alerts to MCCs that are Only LEOSAR/GEOSAR-Capable

Until all LEOSAR/GEOSAR capable MCCs are commissioned as LEOSAR/GEOSAR/MEOSAR capable, LEOSAR/GEOSAR/MEOSAR capable MCCs shall transmit MEOSAR alert data to other MCCs in:

- a. a SIT 915 message with Message Field # 5 set to the identification code of the final destination MCC, that contains alert data in SPOC format (i.e., SIT 185), if the destination MCC is LEOSAR/GEOSAR only capable; or
- b. MCC format (i.e., SITs 138 - 147), if the destination MCC is LEOSAR/GEOSAR/MEOSAR capable.

The format for transmitting MEOSAR alert data (SIT 915/SPOC or MCC) shall be configurable by destination MCC. The implementation status of MEOSAR SIT messages by MCC is provided in Annex I / B.

3.8 Exchange of Test and Exercise Data

3.8.1 Coordination of Beacon Tests

Beacons coded with operational protocols shall not be used for tests, except on rare occasions when required by and under control of a national administration, or for international exercises co-ordinated by the Cospas-Sarsat Joint Committee. All MCCs shall be notified of tests using beacons coded with operational protocols, in accordance with the procedure of Annex II / C of the DDP. Tests using beacons coded with the Test User Protocol, may be performed by anyone having co-ordinated the test with, and received approval from the responsible MCC. Coordination with affected MCCs should be performed by the responsible MCC in accordance with the procedure of Annex II / C of the DDP.

3.8.2 Exchange of Test Messages

Test data obtained for beacons coded with operational protocols or test protocols shall be exchanged between MCCs only upon request. Such requests shall contain the 15 hexadecimal characters of the Beacon Identification (bits 26 to 85 of the beacon message include, as appropriate, the default values of position data in location protocols).

3.9 Archived Information

Each LEOLUT, GEOLUT, MEOLUT and MCC shall archive alert data and other messages transmitted, as specified in documents C/S T.002, C/S T.009, C/S T.019 and C/S A.005, respectively. This information will be provided upon request to another MCC, SPOC or RCC, for a specific period of time and for activities in their area of responsibility. It may be also provided to the Cospas-Sarsat Secretariat for the

analysis of particular beacon events when such analysis has been requested in accordance with the procedure approved by the Cospas-Sarsat Council.

3.10 Communication Networks

Each MCC transfers alert data to other MCCs and SPOCs within its service area as described in Annex I / A.

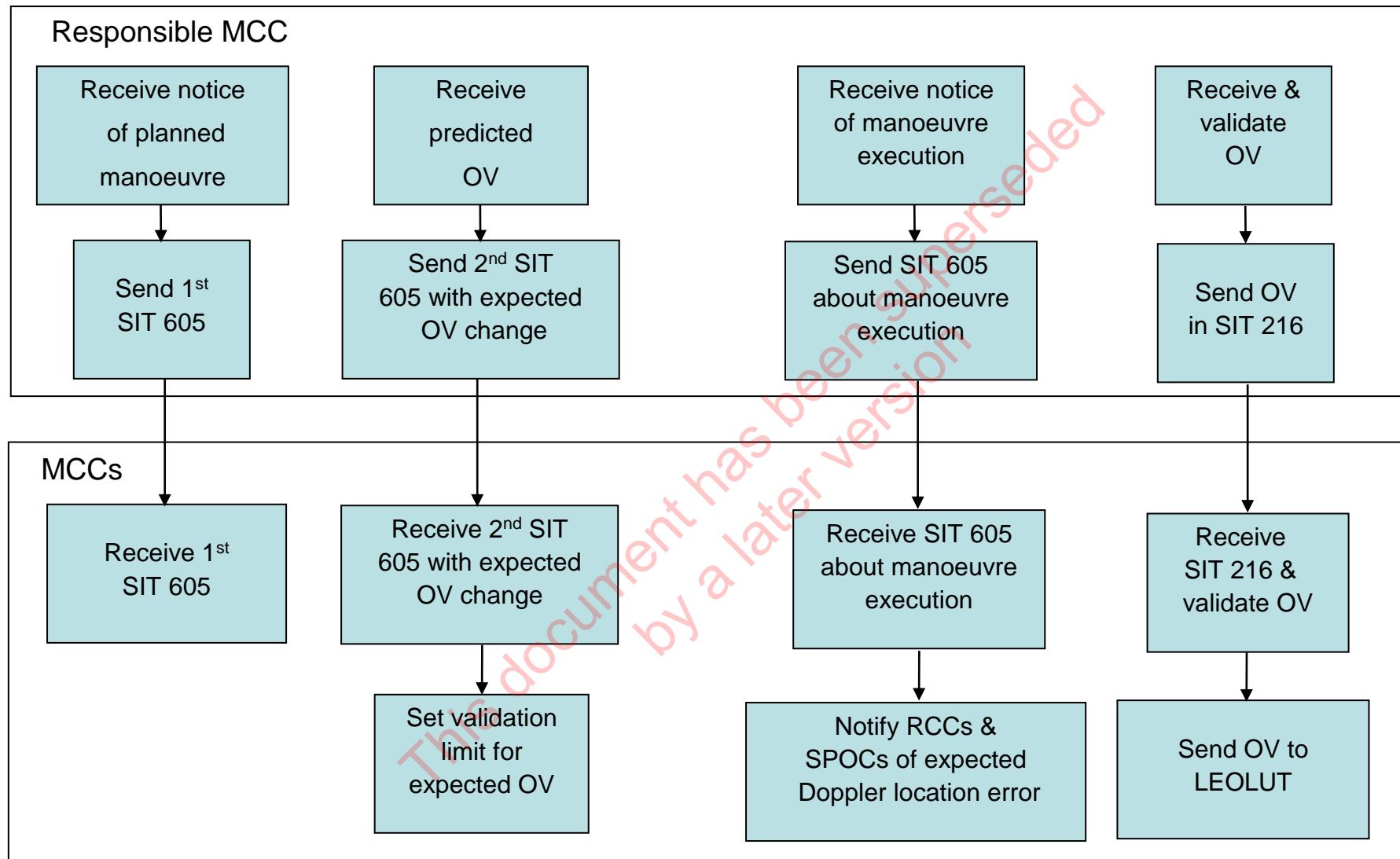
3.11 Return Link Service (RLS)

The Return Link Service (RLS) provides notification to a 406 MHz beacon that an alert transmitted by the beacon has been detected by a LUT and distributed via the Cospas-Sarsat MCC network to the designated Return Link Service Provider (RLSP). This service is intended to provide information to persons in distress about the disposition of the SAR effort, and is only available for 406 MHz beacons coded to provide a return link.

Once notified that an RLS capable beacon has been located the RLSP interfaces to the ground segment for uploading return link messages to appropriate satellites, which, in turn, download return link messages to the transmitting beacon. After receipt of the return link message by the beacon, subsequent beacon transmissions include the return link message receipt status, and an alert that includes the receipt status is distributed via the C/S MCC network to the designated RLSP. Once notified that the beacon has received the return link message, the RLSP interfaces to the relevant ground segment which will cease uploading return link messages to satellites. Further information on the Return Link Service is provided in document C/S R.012.

The detailed procedure for the RLS is described in Annex II / B, section II/B.10.

Figure 3.2: MCC Processing for Scheduled Satellite Manoeuvres



- END OF SECTION 3 -

**ANNEXES TO THE
COSPAS-SARSAT
DATA DISTRIBUTION PLAN**

PART I: COSPAS-SARSAT SPACE AND GROUND SEGMENT DESCRIPTION

PART II: OPERATIONAL PROCEDURES FOR COSPAS-SARSAT MCCs

C/S A.001 ANNEXES

PART I:

COSPAS-SARSAT SPACE AND GROUND SEGMENT DESCRIPTION

*This document has been superseded
by a later version*

ANNEX I / A**DESCRIPTION OF COSPAS-SARSAT MCCS****I / A.1 GENERAL**

The purpose of this Annex is to describe the Cospas-Sarsat MCCs and their interfaces, types of messages originated, normal routing of these messages, and any backup arrangements with other MCCs and a list of supported SPOCs. Any general information, such as 406 MHz beacon register queries, may be included in this section.

Any changes which are unique to the MCC may be amended by that MCC. If bilateral changes are involved, both MCCs shall draft appropriate amendments to their sections once the new interface has been successfully tested.

NOTE

Annex I / A will be updated by Ground Segment Providers with MEOLUT descriptions as associated MEOLUTs are commissioned for operational use.

*This document has been superceded
by a later version*

I / A.AE AEMCC - UNITED ARAB EMIRATES MISSION CONTROL CENTRELast updated: December 2015**1. GENERAL**

The UAE Mission Control Centre is manned and operates 24/7. AEMCC operates two Operational Control Consoles. The primary (AEMCC) is located in Abu Dhabi, the secondary (AEMCC2) is a backup to the primary and it is co-located with Abu Dhabi SAR Coordination Centre in Abu Dhabi.

AEMCC controls one LEOLUT and one GEOLUT located in Albateen Airbase (Abu Dhabi, UAE) at the following locations:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT	24° 25.89' N	054° 26.87' E
GEOLUT	24° 25.89' N	054° 26.87' E

2. SPOCs SUPPORTED

United Arab Emirates

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at AEMCC:

Orbit vectors: receive from SPMCC;
SARP calibration: receive from SPMCC;
System status: originate to and receive from SPMCC;
Narrative: received and originated as required.

4. BACKUP PROCEDURES AND AGREEMENTS

In the case of complete failure of the AEMCC, the SPMCC will assume the duties of the AEMCC. SPMCC will send validated Cospas-Sarsat alert data within the AEMCC service area to Abu Dhabi SAR Coordination Center.

Operators will forward a written notice to their backup MCC of intention to perform maintenance routines requiring a backup at least 24 hours in advance.

As described in section I / A-SP-2, in the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. In that case, the AEMCC will change its configuration in order to consider the FMCC as its current nodal MCC until the backup situation is finished. When the backup is finished, the AEMCC will revert to its normal configuration in order to consider the SPMCC as its nodal MCC.

5. OTHER INFORMATION**Beacon Registration**

Beacon registration is maintained by AEMCC.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.AL ALMCC - ALGERIAN MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The Algerian Mission Control Centre is located at Algiers. The ALMCC controls two LEOLUTs at Algiers and Ouargla and one GEOLUT at Algiers at the following locations:

	<u>Latitude</u>	<u>Longitude</u>
Algiers LEOLUT	36 ° 45.20' N	003 ° 22.86' E
Ouargla LEOLUT	31 ° 52.80' N	005 ° 29.40' E
Algiers GEOLUT	36 ° 45.20' S	003 ° 26.87' E

The Ouargla and Algiers LEOLUTs coverage overlaps with French, Italian, Spanish and UK LEOLUTs on Western Africa and Europe and extends southward to the Guinea Gulf up to Gabon and Congo and eastward up to the Red Sea.

The two LEOLUTs can localise transmitters and distress beacons in local mode and global mode. Interferers in the 406.0 to 406.1 MHz band are localised in the local mode and this information is provided to the Algerian Telecommunication for action through the ITU.

The GEOLUT is co-located with the LEOLUT at Algiers and it operates with MSG-3 satellite.

The SAR Administration is the head agency in Algeria for the Cospas-Sarsat Programme.

2. SPOCs SUPPORTED

ALMCC provides alert data to SPOCs in the ALMCC service area including:

Algeria	Libya
Burkina Faso	Niger
Egypt	

It also routes alert messages to SPMCC, and can receive these messages from this source.

Alert messages in other DDR service areas are routed to the SPMCC.

A communication summary for these interfaces is shown below:

Algerian RCC:	AFTN, Telex, Fax, Voice
SPMCC:	FTP-VPN, AFTN, Fax, Voice

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at ALMCC:

Orbit vectors: received from SPMCC;
SARP calibration: received from SPMCC;
System status: received and originated as required;
Narrative: received and originated as required.

4. BACKUP PROCEDURES AND AGREEMENTS

The Ouargla LEOLUT has overlapping local mode coverage areas to a greater or lesser extent with the following LEOLUTs: Abuja, Bari, Combe Martin, Maspalomas and Toulouse. It is therefore feasible for one to back up the other in the case of a failure or planned maintenance downtime.

Operators will forward a written notice to their backup MCC of intention to perform maintenance routines requiring a backup at least 24 hours in advance.

In the case of a complete failure of the ALMCC, the SPMCC will assume the duties of the ALMCC. SPMCC will send validated Cospas-Sarsat alert data within the ALMCC service area to designated SPOCs. In the Algerian SRR this will be Algiers RCC (this AFTN address is DAALZSZX).

As described in section I / A-SP-2, in the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. In that case, the ALMCC will change its configuration in order to consider the FMCC as its current nodal MCC until the backup situation is finished. When the backup is finished, the ALMCC will revert to its normal configuration in order to consider the SPMCC as its nodal MCC.

5. OTHER INFORMATION

To be determined.

- END OF THIS SECTION -

I / A.AR ARMCC - ARGENTINE MISSION CONTROL CENTRELast updated: October 2012**1. GENERAL**

The Argentine Mission Control Centre (ARMCC) is located in El Palomar, Buenos Aires. The ARMCC controls two LEOLUTs and one GEOLUT at the following locations:

	<u>Latitude</u>	<u>Longitude</u>
El Palomar GEOLUT	34° 36.00' S	058° 36.00' W
Rio Grande LEOLUT	53° 46.75' S	067° 42.32' W
El Palomar LEOLUT	34° 36.00' S	058° 36.00' W

The Argentine LEOLUTs provide full processing of 406 MHz frequency alert data, including G-SARP processing of the transponded SARR data and combined LEO/GEO processing, according to the relevant Cospas-Sarsat specifications. The local coverage area of the Argentine LEOLUTs includes Argentina, South of Brazil and Peru, Bolivia, Paraguay, Uruguay, Chile, part of Antarctica, the Southwestern Atlantic Ocean and Southeastern Pacific Ocean.

The Argentine GEOLUT receives data from the GOES-12 satellite and provides it to the ARMCC for distribution and to the LEOLUTs for combined LEO/GEO processing.

The communication interfaces available at the ARMCC are AFTN, FTP-PNV, Telephone and Fax. These communication means are used as follows:

ARMCC-USMCC:	FTP-VPN	AFTN
ARMCC-RCCs:	AFTN	
ARMCC-Falkland Islands (Malvinas)*:	Telephone	Facsimile
ARMCC-CHMCC:	AFTN	

The entire ground segment is maintained and operated twenty-four hours a day, seven days a week by SASS (Servicio de Alerta y Socorro Satelital), a joint Argentine Navy / Air Force office.

2. SPOCs SUPPORTED

The ARMCC supports the RCCs in Argentina and Falkland Islands (Malvinas)* SRR.

Note: * A dispute exists between the Governments of Argentina and the United Kingdom of Great Britain and Northern Ireland concerning sovereignty over the Falkland Islands (Malvinas).

3. SYSTEM INFORMATION MESSAGES

The ARMCC receives and process the following System information messages:

- Orbit vectors
- SARP calibration data
- SARR calibration data
- System status
- Narrative

The ARMCC is capable of originating the following System information messages:

- System status
- Narrative

These messages are normally received from, or sent to the USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The backup procedure described herein is available for the whole Argentine Mission Control Centre (ARMCC) service area in such a way that the coverage in local mode provided by the LEOLUT stations of the Chilean Mission Control Centre (CHMCC) overlaps the LEOLUT coverage of the ARMCC.

The procedure whereby the backup service is implemented in case of an unexpected failure or scheduled interruption of the ARMCC service may occur and is expected to last more than four (4) hours is as follows:

The CHMCC sends Cospas-Sarsat alerts data to the ARMCC over AFTN.

During scheduled or unscheduled ARMCC outages, incoming AFTN data is re-routed to appropriate RCCs using the SIT 185 format as defined in the C/S A.002 document.

When this procedure is implemented, the ARMCC's duty personnel will contact the National RCCs (maritime and aerial) and advice them that CHMCC provide the Cospas-Sarsat alert distress distribution.

The ARMCC will attempt to pass them to its service area RCCs/SPOCs by manually geosorting them and using the AFTN link communication, facsimile and/or other alternative links.

The backup procedures for the ARMCC consist of the following steps:

- a. Whenever backup service is required, the ARMCC notifies CHMCC and USMCC, requesting them to provide the backup service. The requirement is voice-transmitted to the USMCC and CHMCC by the ARMCC and optionally confirmed by means of Email or Fax.
- b. The CHMCC notifies USMCC and ARMCC when the backup service is being provided.
- c. The USMCC notifies CHMCC and ARMCC when the backup service is being provided. During the backup service provision, the USMCC sends to CHMCC the messages for and to be forwarded to ARMCC. The USMCC will hold the messages intended for ARMCC for re-transmission upon request.
- d. The USMCC notifies all MCCs of the start of the backup service by means of a SIT 605 message (as established in C/S A.001, section 3.6).
- e. The ARMCC sends a SIT 605 message when the ARMCC normal service is restored.
- f. The USMCC sends a SIT 915 message to ARMCC and CHMCC notifying them that data distribution to / from ARMCC is back to normal.
- g. The CHMCC sends a SIT 915 message to ARMCC and USMCC notifying them that data distribution to / from ARMCC is back to normal.

5. OTHER INFORMATION

The beacon database is maintained by the ARMCC.

- END OF THIS SECTION -

I / A.AS ASMCC - SOUTH AFRICAN MISSION CONTROL CENTRE

Last updated: October 2014

1. GENERAL

The South African Mission Control Centre is located in Milnerton (Cape Town). The ASMCC controls one LEOLUT with G-SARP. This LEOLUT is located at:

<u>Latitude</u>	<u>Longitude</u>
33° 52.80' S	018° 30.00' E

The South African MCC and LEOLUT operate 24 hours a day throughout the year.

The Maritime division of Telkom SA is responsible for the operation of the South African MCC and LEOLUT.

2. SPOCs SUPPORTED

Angola	Lesotho	South Africa	Zimbabwe
Botswana	Malawi	St. Helena	
Burundi	Mozambique	Swaziland	
Democratic Republic of Congo	Namibia	Uganda	
	Rwanda	Zambia	

The communication interfaces used by the ASMCC are:

AFTN FTP-VPN

3. SYSTEM INFORMATION MESSAGES

The ASMCC originates and receives the following System information:

Orbit vectors: receive from AUMCC;
SARP calibration: receive from AUMCC;
System status: originate and receive from AUMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

In the event the ASMCC becomes unserviceable, the AUMCC will provide backup support to the ASMCC. All alerts for the ASMCC service area will be transmitted on SIT 185 format and faxed to a number nominated by the ASMCC. The ASMCC will ensure distribution to the RCCs it supports.

5. OTHER INFORMATION

To be determined.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.AU AUMCC - AUSTRALIAN MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The Australian Mission Control Centre is co-located with the RCC Australia in Canberra. The AUMCC controls two advanced technology LEOLUTs (ATLUT-500) with G-SARP. These two LEOLUTs are located in lighthouses on the coast at:

	<u>Latitude</u>	<u>Longitude</u>	
Albany, Western Australia	35° 07.20' S	117° 53.94' E	(Cave Point Lighthouse)
Bundaberg, Queensland	24° 45.50' S	152° 24.77' E	(South Head Lighthouse)

These two LEOLUTs are known nationally as AULUTW (AULUT West - ID: 5033) and AULUTE (AULUT East - ID: 5032) and provide local mode coverage of the continental land mass and extending to seaward into the Indian and South Pacific Oceans and Coral and Tasman Seas.

Both LEOLUTs were registered with ITU in October 1999 (ID numbers: 96.944556 and 96.944558 - for Albany LEOLUT, 96.944552 and 96.944554 - for Bundaberg LEOLUT).

The AUMCC receives alert data from the Wellington LEOLUT (NZLUT - ID: 5121) and Wellington GEOLUTs (NZGEO1 - ID: 5122 and NZGEO2 - ID: 5123) and distributes them in accordance with this document.

The AUMCC and LEOLUTs operate 24 hours a day throughout the year providing alert data through the co-located RCC in accordance with this document.

The AUMCC also assumes the nodal responsibilities for the Southwest Pacific DDR as defined at Annex II / A of this document.

The Australian Maritime Safety Authority (AMSA) is responsible for the management and operation of the Australian Cospas-Sarsat ground segment.

2. SPOCs SUPPORTED

American Samoa, Nauru, Samoa, Vanuatu, Australia, New Caledonia, Solomon Islands, Fiji, New Zealand, Tonga, Kiribati, Papua New Guinea, and Tuvalu.

American Samoa, Tonga, and Samoa are within the New Zealand SRR. Kiribati, Tuvalu, and Vanuatu are within the Fiji SRR. Nauru is within the Solomon Islands SRR.

The AUMCC, in supporting its service area, passes alerts to the following SRRs: Australia, New Zealand, Papua New Guinea, Solomon Islands and Fiji.

Alerts in vicinity of New Caledonia are passed to the SAR authority in Noumea.

3. SYSTEM INFORMATION MESSAGES

The AUMCC originates, receives and forwards System Information messages as follows:

Orbit vectors: receive from CMC and USMCC and forward to ASMCC, IDMCC, SIMCC and THMCC;

SARP calibration: receive from FMCC and forward to ASMCC, IDMCC, SIMCC and THMCC;

System status: originate, receive and forward from/to ASMCC, CMC, FMCC, IDMCC, JAMCC, SIMCC, SPMCC, THMCC and USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The Australian and New Zealand LEOLUTs provide partial backup for each other as there is some overlapping local mode coverage.

An agreement is in place with the USMCC to provide backup of the AUMCC nodal responsibility. The following procedure has been agreed to:

In the event of a failure of the nodal AUMCC, the duty personnel will:

- a. contact the USMCC and advise them to assume AUMCC nodal responsibilities;
- b. request the USMCC to transmit AUMCC service area alerts in SIT 185 format. The AUMCC will attempt to pass them to its service area RCCs/SPOCs by manually geosorting them and using the RCC communication modes available; and
- c. advise the USMCC that alerts from the local Australian or New Zealand LEOLUTs will be passed by the RCC in some form on a 'best effort' basis.

It should be noted that the RCC/AUMCC has a disaster recovery plan and if conditions are such that the primary site has to be abandoned then personnel will be transferred to an alternative site. This alternate site is already set up to support most of the RCC functions and some AUMCC functions.

5. OTHER INFORMATION

The AUMCC is responsible for the allocation of serial numbers for all serialized coded beacons and the maintenance of the Australian beacon database register and can be contacted at any time to obtain database information. Purchasers of beacons are required to complete a registration form (<http://beacons.amsa.gov.au>) giving details of craft, emergency contact numbers and beacon 15 Hex ID.

If national serial numbers, as provided by Australia's national authority, AusSAR (Email: ausbeacon@amsa.gov.au), are to be used, the Cospas-Sarsat type approval number (TAC) should **NOT** be inserted and bit 43 should be set to "0". If the TAC No is to be inserted, bit 43 should be set to "1" and the manufacturer's serial number of the beacon used.

EPIRBs and PLBs for sale in Australia should meet the requirements of the Australian Standard 4280. The 121.5 MHz homing transmitter referred to in Standard 4280 must be approved by the Australian Communications Authority or by a laboratory providing an equivalent service. Beacons being sold to the general public in Australia should have compliance folders that demonstrate the beacon meets the operational and environmental requirements of the Australian Standard.

EPIRBs carried by vessels under the Australian Navigation Act must comply with the relevant Parts of Marine Orders.

ELTs for sale in Australia are required to comply with Aviation Regulation 252.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.BR BRMCC - BRAZILIAN MISSION CONTROL CENTRELast updated: October 2010**1. GENERAL**

The Brazilian Mission Control Centre (BRMCC) operates two Operational Control Consoles (OCCs). The first one as primary OCC located in Brasilia, the second one as secondary OCC being a backup facility co-located with RCC-RE in Recife. Three LEOLUTs are located at Brasilia, Manaus and Recife; the BRMCC also operates two GEOLUTs at Brasilia and Recife with the following co-ordinates:

LEOLUTs:

	<u>Latitude</u>	<u>Longitude</u>
Brasilia	15° 51.43' S	047° 54.16' W
Manaus	03° 01.39' S	060° 03.24' W
Recife	08° 08.30' S	034° 55.50' W

GEOLUTs:

Brasilia	15° 51.43' S	047° 54.16' W
Recife	08° 08.30' S	034° 55.50' W

All Brazilian LEOLUTs can localise 406 MHz distress beacons in local and global coverage mode also Brazilian LEOLUTs can process 406 MHz interference data in local coverage mode.

The local mode coverage of the Brazilian LEOLUTs includes the central part of South America and western area of South Atlantic Ocean.

The BRMCC, GEOLUTs and LEOLUTs operate 24 hours a day throughout the year.
The communication interfaces used by BRMCC are:

AFTN FTP-VPN Voice Facsimile

2. SPOCs SUPPORTED

The BRMCC provides primary support to the Brazilian RCCs and Ascension Island and routes alert and notification (NOCR) messages to other countries and can receive these messages from them.

3. SYSTEM INFORMATION MESSAGES

The BRMCC originates and receives the following System information:

Orbit vectors:	receive from USMCC;
SARP calibration:	receive from USMCC;

System status: originate to and receive from USMCC;
406 MHz SARR frequency calibration: receive from USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

Brasilia, Manaus and Recife LUTs have overlapping local mode coverage areas to a greater or lesser extent with the following LEOLUTs: Parana, Callao, Florida and Santiago. It is therefore feasible for the Brazilian area to be partly covered in the case of failure or planned maintenance downtime.

The BRMCC operates two Operational Control Consoles (OCCs). The first one as primary OCC located in Brasilia, the second one as secondary OCC being a backup facility co-located with RCC-RE in Recife.

In the event of failure of primary OCC, Brazil has backup agreements and procedures in place with the USA. The following procedures have been agreed to:

- a) the BRMCC (from Brasilia) notifies the USMCC whenever the backup service is required by means of Fax, Phone or Email;
- b) the USMCC notifies the BRMCC (Brasilia) when the backup service commences by fax, phone or email. In case of failure of these contacts, USMCC shall notify the BRMCC (Recife), as contact list bellow;
- c) the USMCC sends a SIT 605 message notifying the other MCCs of the BRMCC failure, and that the USMCC is performing backup service according to section 3.7, document C/S A.001;
- d) the USMCC transmits alert messages or status messages, as appropriate, for the Brazilian service area to RCC-RE using the BRMCC OCC-2 AFTN address SBRFZSZX (primary communication link) or via FTP-VPN link;
- e) in the event that the USMCC is unable to communicate with the BRMCC (OCC-2 Recife) as described in "d" above, the USMCC shall transmit alerts for the Brazilian service area in SIT 185 format to the Brasilia RCC (RCC-BS) AFTN address (primary communication link) or via Fax. In this case, the USMCC will advise the RCC-BS of their inability to communicate with the BRMCC (OCC-2 Recife). Other Brazilian RCCs as well as BRMCC (Brasilia) will be advised by RCC-BS;
- f) the BRMCC (from Recife) advises the Brazilian RCCs about the BRMCC failure and about the backup procedures;
- g) the BRMCC (from Brasilia or Recife) will notify the USMCC as soon as the problem is solved, and will advise the time when the BRMCC (Brasilia) plans to restore normal operations;

- h) when the BRMCC (Brasilia) returns to normal operations it will send a SIT 605 message notifying the USMCC and other MCCs that the BRMCC (Brasilia) has resumed normal operations;
- i) the USMCC will send all requested missing messages to the BRMCC (Brasilia).

CONTACT LIST	
BRMCC in Brasilia	Phone: (55) 61 3364 8395 / (55) 61 33652964 Fax: (55) 61 3365 2964 / (55) 61 3365 1212 Email: brmcc@cindactal.aer.mil.br
BRMCC in Recife	Phone/Fax: (55) 81 21298102 or (55) 81 34624927 AFTN RCC-RF: SBREYCYX Email: salvaero.re@gmail.com
RCC Brasilia	Phone: (55) 61 3364 8394 Fax: (55) 61 3365 2964 / (55) 61 3365 1212 AFTN RCC-BS: SBBSYCYX Email: rccbs@cindactal.aer.mil.br

5. OTHER INFORMATION

To be determined.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.CA CMCC - CANADIAN MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The Canadian Mission Control Centre is located in Trenton, Ontario and controls four LEOLUTs:

Churchill, Manitoba
Edmonton, Alberta
Goose Bay, Labrador
Ottawa, Ontario (test / backup facility)

And three GEOLUTs at the following locations:

Edmonton, Alberta
Ottawa (1), Ontario (test / backup facility)
Ottawa (2), Ontario

Locations are provided on www.cospas-sarsat.int.

The LEOLUTs provide full coverage of Canadian SRRs from mid-Atlantic to the Gulf of Alaska and from the North Pole south to approximately 30 degrees north latitude. Operations are 24 hours per day, 7 days per week.

The communication interfaces used by the CMCC are:

Canadian RCCs:	FTPS (File Transfer Protocol Secure), PSTN (Public Switched Telephone Network), Voice, Fax
LUTs to CMCC:	FTPS, PSTN
USMCC:	FTP-VPN, AFTN, Voice, Fax
AUMCC (as part of USMCC backup):	FTP-VPN, AFTN, Voice, Fax

2. SPOCs SUPPORTED

The CMCC has no SPOCs in its SRR. However, the CMCC provides primary support to three Canadian Joint Rescue Coordination Centres (JRCCs Victoria, Trenton and Halifax) and one Canadian Maritime Rescue Sub-Centre (MRSC Quebec), and through JRCC Halifax, to Saint Pierre and Miquelon (French Islands off the south coast of Newfoundland).

CMCC distributes unlocated and NOCR alerts for Saint-Pierre-et-Miquelon to FMCC through the USMCC. On a national level to assist the coordination between RCC Gris-Nez and JRCC Halifax, CMCC also sends Saint-Pierre-et-Miquelon unlocated alerts to JRCC Halifax.

3. SYSTEM INFORMATION MESSAGES

Canada originates and receives the following System information messages:

SARR command:	originate to USMCC;
SARR command verification:	receive from USMCC;
System Status:	originate and receive, as required;
Narrative:	originate and receive, as required;
Orbit Vectors:	receive via USMCC;
SARP calibration:	receive via USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The LUTs operated by the CMCC and USMCC provide overlapping coverage of each other's areas of responsibility.

In the event of a complete CMCC failure, Canada has a backup agreement and procedure in place with the USMCC. The USMCC would route alert data directly to appropriate Canadian JRCC and MRSC.

In the event of a USMCC failure, the USMCC has a backup agreement and procedure in place with CMCC and AUMCC. CMCC would assume USMCC national Sarsat responsibility and send alerts directly to the appropriate US RCCs. For alerts outside the USMCC SRR, CMCC will send alerts via FTP-VPN or AFTN to AUMCC, as AUMCC assumes nodal responsibilities for USMCC. The USMCC provides CMCC with the current Geosort data for its national RCCs and SPOCs.

Canada has installed a completely functional backup system for CMCC at Belleville, Ontario. In the event of the need to transition to this alternate location, CMCC would inform the USMCC as soon as possible. Once all communication links have been reconfigured, operation of the backup site would be transparent to external MCCs/agencies.

The CMCC will initiate a communications test once per quarter with the AUMCC and all the US RCCs. These communications tests are to test both modes of communications (FTPV/AFTN), using direct routing to / from AUMCC, to ensure that these routes are operational in the event MCC Backup Procedures are required.

5. OTHER INFORMATION

Registration of Beacons

A register for Canadian beacons is maintained by the Canadian Beacon Registry, located at CMCC in Trenton, Canada.

I / A.CH CHMCC - CHILEAN MISSION CONTROL CENTRELast updated: December 2015**1. GENERAL**

The Chilean Mission Control Centre is located in Los Cerrillos, Santiago. The CHMCC controls three LEOLUTs and one GEOLUT at the following locations:

LEOLUTs

	<u>Latitude</u>	<u>Longitude</u>
Punta Arenas	53° 00.36' S	070° 50.82' W
Santiago	33° 29.70' S	070° 42.24' W
Easter Island	27° 09.01' S	109° 26.22' W

GEOLUT

	<u>Latitude</u>	<u>Longitude</u>
Santiago	33° 29.70' S	070° 42.24' W

All Chilean LEOLUTs can localize 406 MHz distress beacon alerts in local and global coverage mode.

The local mode coverage of the Chilean LEOLUTs covers the areas of Chile, Argentina, Bolivia, Paraguay, Uruguay, part of Brazil, Peru, Pacific Ocean and Antarctica.

The CHMCC also controls one GEOLUT located in Santiago.

The CHMCC, LEOLUTs and GEOLUT operate 24 hours a day throughout the year.

The Chilean Air Force (FACH) is responsible for the operation of the Chilean MCC, LEOLUTs and GEOLUT.

The communication interfaces used by the CHMCC are:

Chilean RCCs	AFTN, Telephone, Fax, E-mail
SPOCs	AFTN, Telephone, Fax, E-mail (Bolivia, Uruguay y Paraguay)
Chilean MRCC	FTP-VPN, Telephone, Fax, E-mail
USMCC	FTP-VPN, AFTN, Telephone, Fax, E-mail (nodal)

2. SPOCs SUPPORTED

The Chilean Mission Control Centre receives alert data from the LEOLUTs and GEOLUT and from other Cospas-Sarsat MCCs in accordance with document C/S A.001. It provides Cospas-Sarsat alert data to the following countries (SPOCs):

Bolivia
Paraguay
Uruguay

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at CHMCC:

Orbit vectors: received from USMCC;
SARP calibration: received from USMCC;
System status: received and originated as required;
Narrative: received and originated as required.

4. BACKUP PROCEDURES AND AGREEMENTS

In the unlikely event of a CHMCC failure, Chile has backup agreements and the following procedures in place with the USA:

- a. The CHMCC shall notify the USMCC by phone or email when the back service is required.
- b. The USMCC shall notify the CHMCC by phone, fax or email when the backup service commences.
- c. The USMCC shall send a SIT 605 message notifying the other MCCs of the failure of the CHMCC and that the USMCC is performing backup service according to section 3.7 of document C/S A.001. The USMCC shall also notify the CHMCC's SPOCs of the same information by SIT 915 message.
- d. The data distribution procedures and formats during the backup are the follows:

If the alert message is located within Chile's search and rescue area, all messages shall be sent by the USMCC directly to Santiago RCC (AFTN address SCTIYCYX), using a SIT 185 message.

If the alert message is located within the search and rescue area of any of the Chilean's SPOCs (Bolivia, Paraguay and Uruguay); the USMCC shall send the alert message directly to the SPOC where the alert has been located, using a SIT 185 message.

The AFTN addresses for the Chile's SPOCs are:

- Bolivia (BOLISPOC: SLLPZRZX),
- Paraguay (PARASPOC: SGASSARX) and,
- Uruguay (URUGSPOC: ZUMUYCYX).

e. Once the failure is overcome, the CHMCC shall notify the USMCC and other MCCs that the CHMCC has resumed normal operations using a SIT 605 message. The CHMCC shall also notify its SPOCs that it has resumed normal operations by a SIT 915 message.

f. By default, the USMCC shall send all held system information messages (including SIT 605, 215, 216 and 417 messages) and all held alert messages within the Chilean Service Area to the CHMCC when the CHMCC resumes its normal operation.

5. OTHER INFORMATION

Beacon Registration

A 406 MHz EPIRBs / ELTs have been approved for carriage on Chilean vessels and aircraft. A database of Chilean registered Cospas-Sarsat maritime beacons is maintained by the General Directorate of Maritime Territory and Merchant Marine, and another database of Chilean registered Cospas-Sarsat aviation beacons is maintained by the General Directorate of Civil Aviation. The CHMCC also maintains a copy of the Chilean register for Cospas-Sarsat aviation beacons.

- END OF THIS SECTION-

I / A.CN CNMCC - CHINESE MISSION CONTROL CENTRE

Last updated: October 2012

1. GENERAL

The Chinese Mission Control Centre is co-located with the China Maritime Search and Rescue Centre and controls two LEOLUTs installed at the Ministry of Communications at the following location:

<u>Latitude</u>	<u>Longitude</u>
39° 54.30' N	116° 25 00.05' N

The local mode of the Chinese LEOLUTs covers the main land of China, the East China Sea, the Yellow Sea and the part of the South China Sea.

Both LEOLUTs can locate transmitters and distress beacons in local mode as well as global mode. The Beijing (1) LEOLUT includes a Ground Search and Rescue Processor (G-SARP) to process the repeater band. The Beijing (2) LEOLUT is used as a backup of Beijing (1).

The CNMCC and LEOLUTs operate 24 hours a day throughout the year and provide alert data to Chinese RCCs and to SPOCs within the CNMCC service area in accordance with document C/S A.001 and national procedures.

2. SPOCs SUPPORTED

The CNMCC provides primary support to Chinese RCCs.

The communication interfaces used by the CNMCC are:

AFTN FTP-PNV Voice Facsimile

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at CNMCC:

Orbit vectors: received from JAMCC;
SARP calibration: received from JAMCC;
System status: originated to and received from JAMCC.

4. BACKUP PROCEDURE AND AGREEMENTS

The LEOLUTs at Beijing, Incheon, Nakhodka, among others, have overlapping local mode coverage areas. It is therefore feasible for one to backup the other in case of failure or planned maintenance downtime. Co-operation in the coverage of individual satellites passes may also be feasible in the future.

In the unlikely event of a CNMCC failure, China has backup agreements with Hong Kong.

5. OTHER INFORMATION

A register of maritime EPIRBs is maintained at China Transport Telecommunications Centre. The CNMCC is able to get access to the register.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.CO CMC - COSPAS MISSION CENTRE

Last updated: December 2015

1. GENERAL

The Cospas Mission Centre (i.e., the Russian Mission Control Centre) is located in Moscow and controls three national LUTs at the following locations:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT Moscow *	55° 37.30' N	037° 30.63' E
LEOLUT Nakhodka	42° 51.52' N	132° 47.44' E
GEOLUT Moscow	55° 44.60' N	037° 43.36' E

Note: * Under development.

LEOLUTs can localise transmitters and distress beacons in local mode and global mode.

The local mode coverage of the Russian LEOLUTs includes Europe, northern and central parts of Asia, western part of North Pacific, north-eastern part of Africa.

The Russian MCC and LEOLUTs operate 24 hours per day throughout the year.

The CMC also assumes the nodal responsibilities for the Eastern DDR as defined at Annex I / A of this document.

The agency Morsviazputnik is responsible for operation of the Russian MCC and LEOLUTs.

2. SPOCs SUPPORTED

The CMC service area includes the territory of Armenia, Azerbaijan, Belarus, Bulgaria, Czech Republic, Hungary, Kazakhstan, Kyrgyz Republic, Moldova, Mongolia, Poland, Romania, Russia, Slovakia, Tajikistan, Turkmenistan and Uzbekistan.

Note: There is an overlap with the TRMCC service area over Georgia and Ukraine.

The CMC routes alert data to RCCs of the Russian Federation and to other States in its service area and to the AUMCC, FMCC, INMCC, JAMCC, PAMCC, SPMCC and USMCC in accordance with the document C/S A.001 (DDP).

The following communication lines are used by the CMC:

Russian RCCs: PSTN (Public Switched Telephone Network) communications, Fax
Russian LUTs: FTP, PSTN communications
AUMCC: FTP-VPN, AFTN
FMCC: FTP-VPN, AFTN

INMCC: FTP-VPN, AFTN (TBD)
JAMCC: FTP-VPN, AFTN
PAMCC: FTP-VPN, AFTN
SPMCC: FTP-VPN, AFTN
USMCC: FTP-VPN, AFTN

3. SYSTEM INFORMATION MESSAGES

The CMC originates and receives the following System information messages:

Orbit vectors: originate to AUMCC, FMCC, INMCC, JAMCC, PAMCC, SPMCC and USMCC and receive from USMCC;
SARP calibration: receive from FMCC, forward to INMCC and PAMCC;
System status: originate to and receive from AUMCC, FMCC, INMCC, JAMCC, PAMCC, SPMCC and USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The Russian LEOLUTs in Moscow and Arkhangelsk have largely overlapping local mode coverage areas, which is taken into account in planning satellite pass processing so that one LEOLUT backs up the other in the case of failure or planned maintenance downtime. In the event of CMC equipment failure, alert messages may be received or transmitted by Telephone. If the CMC is inoperative, Russian LEOLUTs forward their alert data to national RCCs.

All alert information obtained at CMC is archived for up to 90 days.

In the case of complete failure of the CMC, the FMCC will assume the duties of the CMC. FMCC will send validated Cospas-Sarsat alert data within the CMC service area to designated SPOCs or RCCs.

5. OTHER INFORMATION

Beacon Registration

A register on national units equipped with beacons is maintained at the CMC.

- END OF THIS SECTION -

I / A.CY CYMCC - CYPRUS MISSION CONTROL CENTRE

(Under development until commissioned once the MEOSAR system is at IOC)

Last updated: December 2015

1. GENERAL

The Cyprus Mission Control Centre (CYMCC) is located at Larnaca, Cyprus. The CYMCC controls a MEOLUT located at Larnaca.

The MEOLUT is located at the following co-ordinates:

Latitude	Longitude
34° 51.90' N	033° 23.02' E

The CYMCC and MEOLUT operate 24 hours a day throughout the year.

The communication interfaces used by CYMCC are as follows:

FTP-VPN (TBD) AFTN Facsimile Voice

2. SPOCs SUPPORTED

The CYMCC provides primary support to JRCC Larnaca and routes alert and notification (NOCR) messages to other countries and can receive these messages from them.

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at CYMCC:

System status: originate and receive as required;
Narrative: as required;
Orbit vectors: receive via FMCC;
SARP calibration: receive via FMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The CYMCC operates two (2) Mission Control Centres (MCCs), one of them being a backup. In the event of failure of both MCCs, Cyprus has backup agreements and procedures in place with Italy. The following procedures have been agreed to:

- a) Whenever the backup service is required, the CYMCC notifies the ITMCC by means of Fax, Telephone or Email.
- b) The ITMCC notifies the CYMCC when the backup service commences by Fax, Telephone or Email.

- c) The ITMCC sends a SIT 605 message notifying all other MCCs of the CYMCC failure and that ITMCC is performing backup service according to section 3.7, document C/S A.001.
- d) The CYMCC advises JRCC Larnaca about the CYMCC failure and about the backup procedures.
- e) The ITMCC transmits alerts for the Cyprus service area in SIT 185 format to JRCC Larnaca using the AFTN network (primary communication link) or via Fax.
- f) In the event that the ITMCC is unable to communicate with the JRCC Larnaca as described above, the ITMCC shall transmit alerts for the CYMCC service area in SIT 185 format to JRCC Larnaca via satellite fax and satellite telephone.
- g) The CYMCC will notify the ITMCC about the problem status and will advise the time when the CYMCC plans to restore normal operations.
- h) When the CYMCC returns to normal operations it will send a SIT 605 message notifying the ITMCC and other MCCs that the CYMCC has resumed normal operations. The CYMCC will also notify the JRCC Larnaca that it has resumed normal operations.
- i) The ITMCC will send all requested missing messages to the CYMCC and will notify it about the events handled during the backup.
- j) The ITMCC shall contact with the CYMCC by means of:

Phone: +357 24 643005
Fax: + 357 24 643254
Email: jrcc_cyp @cytanet.com.cy
AFTN: LCLK YCYX
Inmarsat C: 421099999
Satellite Telephone: 870 77 254 56 96
Satellite Fax: 870 78 217 48 53

Note: Address to JRCC (co-located with CYMCC) until finalization of communication details.

- k) The ITMCC shall contact with JRCC Larnaca by means of:

Phone: +357 24 643005
Fax: + 357 24 643254
Email: jrcc_cyp@cytanet.com.cy
AFTN: LCLK YCYX
Inmarsat C: 421099999
Satellite Telephone: 870 77 254 56 96
Satellite Fax: 870 78 217 48 53

- 1) The CYMCC shall contact with the ITMCC by means of:

Phone: (39.080) 5341571, (39.080) 5344033

Fax: (39.080) 5342145

Email: itmcc247@cospas-sarsat-italy.it

AFTN: LIJCYFYX

5. OTHER INFORMATION

Beacon Registration

The CYMCC has access 24/7 to all Cypriot beacon registries (EPIRBs, ELTs and PLBs with country codes 209, 210 and 212).

Registration of EPIRBs is provided by the Department of Merchant Shipping, Cyprus.

Registration of ELTs is provided by the Department of Civil Aviation, Cyprus.

Registration of PLBs is provided by JRCC Larnaca.

Location of CYMCC

The CYMCC is collocated with the JRCC Larnaca.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.FR FMCC - FRENCH MISSION CONTROL CENTRELast updated: December 2015**1. GENERAL**

The French Mission Control Centre is co-located with dual LEOLUTs in Centre National d'Études Spatiales (CNES) technical centre in Toulouse. The LEOLUTs are equipped with dedicated antennas which makes possible tracking of all Cospas-Sarsat satellites passing over Toulouse, unless two satellites are in conflict (i.e., pass at the same time).

The dual LEOLUTs can localise transmitters and distress beacons in both the global and local modes. Interferers in the 406.0 MHz to 406.1 MHz frequency band are localised in the local mode and this information is provided to the French Telecommunication Administration for action through ITU. The Toulouse LEOLUTs provide local mode coverage of Europe, eastern half of North Atlantic and Africa to latitude 20 degrees North. Operations are 24 hours per day throughout the year. The French Administration (Civil Aviation and Maritime Affairs) is responsible for validation and transmission of alert data to MCCs and SPOCs, in accordance with C/S A.001 and national procedures.

The FMCC also assumes the nodal responsibilities for the Central DDR as defined at Annex I / A of this document.

2. SPOCs SUPPORTED

The French Mission Control Centre receives alert data from the Toulouse dual LEOLUT and GEOLUT and from other Cospas-Sarsat MCCs in accordance with the document C/S A.001.

It provides Cospas-Sarsat alert data to the following countries / territories:

EUROPE		AFRICA Region		CARIBBEAN Region	
Andorra	(2)	Chad		Anguilla	(3)
Austria		Djibouti		Antigua and Barbuda	(3)
Belgium		Morocco		Dominica	(3)
France		Tunisia		Guadeloupe (F)	
Germany				Martinique (F)	
Gibraltar				Montserrat	(3)
Liechtenstein	(1)			Saint Kitts and Nevis	(3)
Luxemburg				Saint Lucia	(3)
Monaco	(2)				
Netherlands					
Portugal					
Switzerland					
INDIAN OCEAN					
		Comoros	(3)		
		Crozet Archipelago (F)			
		Kerguelen Islands (F)			
		Madagascar			
		Mauritius			
		Reunion (+ Mayotte) (F)			

ATLANTIC OCEAN	PACIFIC OCEAN	SOUTH AMERICAN Region
Azores (4) Madeira (4)	French Polynesia (F) Pitcairn (3)	Guiana (F) Surinam

- (1) FMCC provides alert data via Switzerland SPOC.
- (2) FMCC provides alert data via French SPOC.
- (3) FMCC provides alert data via French overseas SPOC.
- (4) FMCC provides alert data via Portugal SPOC.
- (F) French overseas country / department / territory.

The listed countries are part of the FMCC service area, unless they indicate that they wish to receive the alert data from another MCC or start operation of their own LEOLUT/MCC.

Cospas-Sarsat alerts localised inside the FMCC service area are forwarded to the responsible SPOC or RCC. For alerts localised inside the FMCC service area in a country which has not designated a SPOC, the FMCC forwards alert data to the CROSS Gris-Nez (MRCCGris-Nez) for handling in accordance with agreed international SAR regulation.

AFTN and FTP-VPN are used for communication with other MCCs. AFTN,FTP-VPN and Fax are used for communication with the supported SPOCs.

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at FMCC:

- SARP command: originate to USMCC;
- SARP command verification: receive from USMCC;
- System status: originate and receive as required;
- Narrative: as required;
- Orbit vectors: receive from CMC and USMCC and forward to TRMCC, NMCC, ITMCC, GRMCC and UKMCC;
- SARP calibration: originate to AUMCC, CMC, ITMCC, JAMCC, NMCC, SPMCC, UKMCC, GRMCC, TRMCC and USMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

LUT/MCC operators will forward written notice of intention to perform maintenance routines involving deactivation of the LUT/MCC well in advance. The MCC will inform all other MCCs as soon as a decision has been taken, and confirm the times a minimum of two weeks prior to deactivation.

LUT/MCC operator will inform the associated MCC by the quickest possible means, followed by a written confirmation when an estimate of the duration of the downtime is available. The MCC will immediately inform the other MCCs.

In the case of complete failure of the FMCC or in case of circumstances outside one's control, the SPMCC will assume the duties of the FMCC. SPMCC will send validated

Cospas-Sarsat alert data, within the FMCC and/or other MCC service areas to designated SPOCs or RCCs. All validated Cospas-Sarsat alert data within the Central DDR service area will be directly transmitted to the Central DDR destination MCC.

In the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. FMCC will send validated Cospas-Sarsat alert data within the SPMCC service area and within other areas to designated SPOCs or RCCs. In the Spanish SRR this will be RCC Madrid and CNCS (MRCC). It was agreed to periodically exchange test messages between FMCC and the Spanish RCCs (RCC Madrid and CNCS) to check the communication links. All validated Cospas-Sarsat alert data within the South Central DDR service area will be directly transmitted to the South Central DDR destination MCC.

The FMCC also assumes the nodal responsibilities for the Central DDR as defined at Annex I / A of this document.

Backup test between FMCC and SPMCC will be conducted on a “no noticed” basis as defined at section 3-7 (contingency procedure) of this document.

In the case of complete failure of the CMC, the FMCC will assume the duties of the CMC. FMCC will send validated Cospas-Sarsat alert data within the CMC service area and within other areas to designated SPOCs or RCCs. All validated Cospas-Sarsat alert data within the Eastern DDR service area will be directly transmitted to the Eastern DDR destination MCCs.

In the case of complete failure of the ITMCC, the FMCC will assume the duties of the ITMCC. FMCC will send validated Cospas-Sarsat alert data within the ITMCC service area to designated SPOCs or RCCs.

5. OTHER INFORMATION

A database of French registered beacons (named French 406 MHz Beacon Registration Database) is maintained by FMCC. URL: <https://registre406.cnes.fr>

Country codes supported by French registry:

COUNTRY CODE:	COUNTRY NAME:
226, 227, 228	France
329	Guadeloupe (French Department of)
347	Martinique (French Department of)
361	St. Pierre and Miquelon
501	Adelie Land
540	New Caledonia
546	French Polynesia
578	Wallis and Futuna
607	Saint Paul and Amsterdam Island
618	Crozet Archipelago
635	Kerguelen Islands
660	Reunion (French Department of)
745	Guiana (French Department of)

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.GR GRMCC - GREEK MISSION CONTROL CENTRE

Last updated: October 2014

1. GENERAL

The Greek Mission Control Centre is located at Piraeus, Greece. The GRMCC controls a LEOLUT and a GEOLUT located at Penteli Mountain.

The LUTs are located at the following co-ordinates:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT	38° 04.85' N	023° 52.98' E
GEOLUT	38° 04.85' N	023° 52.98' E

The LEOLUT can localise transmitters and distress beacons in local mode and global mode.

The GRMCC and LUTs operate 24 hours a day throughout the year.

The communication interfaces used by GRMCC are as follows:

FTP-VPN AFTN Facsimile Voice

2. SPOCs SUPPORTED

The GRMCC provides primary support to the Greek JRCC and routes alert and notification (NOCR) messages to other countries and can receive these messages from them.

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at GRMCC:

Orbit vectors:	receive from FMCC;
SARP calibration:	receive from FMCC;
System status:	originate to and receive from FMCC;
Narrative:	receive and originate as required.

4. BACKUP PROCEDURES AND AGREEMENTS

The GRMCC operates two Operational Control Consoles (OCC), one of them being a backup. In the event of GRMCC becomes unserviceable, Greece has backup agreements and procedures in place with Italy. The following procedures have been agreed:

- The GRMCC notifies the ITMCC whenever the backup service is required by means of Fax, Phone or Email. GRMCC notifies ITMCC about the alert events which were handling before the failure.
- The ITMCC notifies the GRMCC when the backup service commences by Fax/Phone or Email.

- c) The ITMCC sends a SIT 605 message notifying the other MCCs of the GRMCC failure, and that the ITMCC is performing backup service according to section 3.7, document C/S A.001.
- e) The ITMCC transmits alerts for the Greek service area in SIT 185 format to Greek JRCC using the Greek JRCC Telex (primary communication link) or via Fax.
- f) In the event that the ITMCC is unable to communicate with the JRCC as described above, the ITMCC shall ; transmit alerts for the GRMCC service area in SIT 185 format to the GRMCC via Fax. In that case, the ITMCC will advise the GRMCC of their inability to communicate with the Greek JRCC.
- f) The GRMCC advises the Greek JRCC about the GRMCC failure and about the backup procedures.
- g) The GRMCC will notify the ITMCC as soon as the problem is solved, and will advise the time when the GRMCC plans to restore normal operations.
- h) When the GRMCC returns to normal operations it will send a SIT 605 message notifying the ITMCC and other MCCs that the GRMCC has resumed normal operations. The GRMCC also notifies Greek JRCC that it has resumed normal operations.
- i) The ITMCC will send all requested missing messages to the GRMCC and will notice it about the events handled during the backup.
- j) The ITMCC shall contact with GRMCC by means of:

Phone: +30 210 4082690
Fax: + 30 210 4082870
Email: grmcc@hcg.gr
AFTN : LGGGYCYC

- k) The ITMCC shall contact with JRCC Piraeus by means of:

Phone: +30 210 4112500 Maritime section
+30 210 4191599 Aviation section
AFTN: LGGGYCYX
Fax: +30 210 4132398
Telex: 601 211588 RCC GR
Email: jrccgr@hcg.gr
eksedat@gmail.com

- 1) The GRMCC shall contact with ITMCC by means of:

Phone: +39 080 5341053 – 5341571 - 5344033

Fax: +39 080 5342145

Email: itmccoperator@cospas-sarsat-italy.it

5. OTHER INFORMATION

Beacon Registration

- a) A database of the Greek register for MMSIs (maritime beacons are coded only with MMSI) is maintained by the Merchant Ships Inspectorate / Radio Communication Department of Ministry of Shipping, Maritime Affairs and the Aegean, with a copy at the GRMCC.
- b) A database of the Greek register for aviation Cospas-Sarsat beacons is maintained by the Hellenic Ministry of Development Competitiveness Infrastructure Transport and Networks / Civil Aviation Authority / Telecommunication Services Regulatory Framework Section D4/D, with a copy at the GRMCC.
- c) A database of the Greek register for PLBs is maintained by the GRMCC, with a copy at JRCC Piraeus. An online database for registering PLBs is about to go live in order for citizens to be able to register their PLBs on their own.

- END OF THIS SECTION -

I / A.HK HKMCC - HONG KONG MISSION CONTROL CENTRE

Last updated: October 2012

1. GENERAL

The Hong Kong Mission Control Centre is located on Hong Kong Island in the MRCC controlling two advanced technology LEOSAR Local User Terminals (dual LEOLUT system) located on the Peak on Hong Kong Island at the following location:

<u>Latitude</u>	<u>Longitude</u>
22° 16.56' N	114° 08.76' E

Both LEOLUTs can locate transmitters and distress beacons in local mode as well as global mode.

The local mode coverage of the Hong Kong LEOLUT covers the area from Mongolia in the north to the south of Indonesia and from the eastern side of the Indian Ocean to the western part of the Pacific.

The HKMCC and LEOLUTs both operate 24 hours a day and provide alert data to countries within the HKMCC service area in accordance with document C/S A.001 and national procedures.

A second operator control console (OCC) is available as a backup MCC and is located at the VTC in Macau Ferry Terminal.

The Marine Department of Hong Kong is responsible for the operation of the HKMCC and the HKLEOLUT.

2. SPOCs SUPPORTED

Democratic People's Republic of Korea
Hong Kong, China
Macau
Philippines

The communications interfaces used by the HKMCC are:

FTP-VPN AFTN Facsimile Voice

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at HKMCC:

Orbit vectors: receive from JAMCC;
SARP calibration: receive from JAMCC;

System status: originate to and receive from JAMCC.

4. BACKUP PROCEDURE AND AGREEMENTS

The HKMCC established a mutual backup procedure with the TAMCC for system outage on either side.

In the case of complete failure of the CNMCC, the HKMCC will assume the duties of the CNMCC.

In the case of complete failure of the VNMCC, the HKMCC will assume the duties of the VNMCC.

The LUTs at Hong Kong, Singapore and Japan have overlapping local mode coverage areas to a greater or lesser extent. It is therefore feasible for the Hong Kong area to be fully covered in the case of failure or planned maintenance downtime.

5. OTHER INFORMATION

Beacon Registration

A register of beacons is maintained at the HKMCC.

- END OF THIS SECTION -

*This document has been superseded
by a later version*

I / A.ID IDMCC - INDONESIA MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The Indonesia Mission Control Centre (IDMCC) controls one advanced technology Local User Terminal (ATLUT System) located in Jakarta at the following location:

	<u>Latitude</u>	<u>Longitude</u>
Jakarta	06°09.42' S	106°39.36' E

This LUT (5254) can locate transmitters and distress beacons in local mode as well as global mode.

The local mode coverage of the Indonesia LUT is able to cover the area of Brunei, Malaysia, Singapore, Papua New Guinea, Thailand (ASEAN Area) as well as Laos, Myanmar, South of Philippines and North Australia.

The IDMCC and LUT operate 24 hours a day (seven days a week) throughout the year.

The National SAR Agency (BASARNAS) is responsible for the operation of the IDMCC/LUT.

2. SPOCs SUPPORTED

The IDMCC provides primary support to RCC Timor-Leste and thirty-four Indonesia RSCs and routes alert and notification (NOCR) messages to other countries and can receive these messages from them.

The communications interfaces used by the IDMCC:

FTP-VPN AFTN Facsimile Telephone HF radios on 13.545 MHz and 11.445 MHz

3. SYSTEM INFORMATION MESSAGES

The IDMCC originates and receives System information to / from the AUMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The LUTs in Indonesia, Singapore and Australia have overlapping local mode coverage to greater or less extent. It is therefore feasible for the Indonesia to be fully covered in the case of failure or planned maintenance downtime.

In the event the IDMCC becomes unserviceable, the SIMCC will provide backup support to the IDMCC. All the alerts for the IDMCC service area will be transmitted in SIT 185 format to a fax number nominated by the IDMCC or via AFTN.

5. OTHER INFORMATION

Beacon Registration

The IDMCC of the National SAR Agency (BASARNAS) maintains the database of all registered 406 MHz beacons (ELTs, EPIRBs, PLBs).

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.IN INMCC - INDIAN MISSION CONTROL CENTRELast updated: October 2010**1. GENERAL**

The Indian Mission Control Centre is located at Bangalore and controls two national LEOLUTs at the following locations:

	<u>Latitude</u>	<u>Longitude</u>
Bangalore	13°02.09' N	077°30.70' E
Lucknow	26°54.80' N	080°57.44' E

These LEOLUTs can locate transmitters and distress beacons radiating in both local mode as well as global mode.

The local mode coverage of the Indian LEOLUTs includes the entire Indian sub-continent and the adjacent sea regions and islands.

The INMCC also controls one GEOLUT located in Bangalore.

The Indian MCC and LUTs operate 24 hours a day throughout the year.

The Indian Space Research Organization (ISRO) of the Department of Space, Government of India is responsible for the operation of the Indian MCC and LUTs.

2. SPOCs SUPPORTED

Bangladesh	Maldives	Sri Lanka
Bhutan	Nepal	Tanzania
India	Seychelles	

3. SYSTEM INFORMATION MESSAGES

The INMCC originates and receives the following System information:

- Orbit vectors: receive from CMC;
- SARP calibration: receive from CMC;
- System status: originate to and receive from CMC.

4. BACKUP PROCEDURES

The Indian LEOLUTs at Bangalore and Lucknow have large local mode overlaps which are taken into account in planning satellite pass scheduling.

In the unlikely event of the INMCC failure, the INMCC has backup agreements with the CMC.

5. OTHER INFORMATION

Beacon Registration

There is a plan to maintain a register of national units equipped with beacons at the INMCC.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.ITALIAN MISSION CONTROL CENTRE

Last updated: October 2014

1. GENERAL

The Italian Mission Control Centre is located in Bari, at the Italian Coast Guard Naval Base, together with one LEOLUT and one GEOLUT.

The LEOLUT is equipped with an antenna which tracks all Cospas-Sarsat satellites passing over Bari, unless two satellites are in conflict. The LEOLUT is able to localise transmitters and distress beacons in local mode and global mode. Interferers in the 406.0 MHz to 406.1 MHz frequency band are localised in the local mode and forwarded to the Italian Telecommunication Authority for subsequent action through the ITU.

The Bari LEOLUT provides local mode coverage in South-East and Central part of Europe, the Mediterranean Sea, part of Middle-East Asia and part of Central and East Africa, from latitude 71° N to 11° N.

The ITMCC works 24 hours per day throughout the year. A dedicated team is responsible for validation of alert data and transmission to MCCs and SPOCs throughout the world, in accordance with document C/S A.001 and national procedures. ITMCC is equipped with a backup server which replaces the primary one in case of failure or scheduled downtime for maintenance. All the Cospas-Sarsat alert data are continuously replicated in the backup server, hence, in case of primary unexpected outage the MCC operator could switch on the backup server in a very short time.

Concerning communication links, the ITMCC uses FTP-VPN to exchange data with MCCs and when not available AFTN. To send Cospas-Sarsat alert data to SPOCs or RCCs the ITMCC uses AFTN and Fax. Telephone communications are also available with national and international SAR contacts.

2. SPOCs SUPPORTED

The Italian Mission Control Centre receives alert data from the Bari LEOLUT and GEOLUT and from other MCCs according to document C/S A.001. It provides alert data to the following countries:

AFRICA:

Eritrea Somalia
Ethiopia South Sudan
Kenya Sudan

ASIA:

Israel

MIDDLE EAST:

Palestine

EUROPE:

Albania	Italy	Serbia
Bosnia and Herzegovina	Malta	Slovenia
Croatia	Montenegro	The Former Yugoslav Rep. of Macedonia
Cyprus*	San Marino	Vatican City

Note: * Until IOC of Cyprus MCC (CYMCC).

3. SYSTEM INFORMATION MESSAGES

The following messages are received or originated at the Italian MCC:

System status: originate and receive as required;
Narrative: as required;
Orbit vectors: receive via FMCC;
SARP calibration: receive via FMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The Bari LEOLUT has overlapping local mode coverage areas with the following LEOLUTs in the Central Data Distribution Region: Combe Martin, Toulouse, Tromsoe, Penteli and Ankara. It is feasible for one to backup the other in case of failure or planned maintenance downtime.

LUT operators will forward written advance notice of routine maintenance deactivation of the LUT. The MCC will advise all other MCCs as soon as decision has been taken and confirm the times a minimum of two weeks before deactivation. In case of failure, the LUT operators will inform the MCC which will notice the downtime to other MCCs in CDDR using the appropriate SIT message.

In the case of complete failure or unavailability of the ITMCC, the FMCC will assume the duties of the ITMCC sending the SIT 605 to all MCCs notifying the ITMCC failure. The FMCC will send validated Cospas-Sarsat alert data within the ITMCC service area to designated RCCs or SPOCs.

ITMCC provides backup to GRMCC and TRMCC in case of their scheduled or not scheduled downtimes according to agreements established with these MCCs.

5. OTHER INFORMATION**Beacon Registration**

The ITMCC provides registration of EPIRBs, ELTs and PLBs. The ITMCC maintains the beacon registry and provides information 24 hours per day throughout the year to SPOCs or RCCs.

I / A.JA JAMCC - JAPAN MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The Japan Mission Control Centre is located at the Japan Coast Guard Headquarters in Tokyo. The JAMCC controls one LEOLUT at Gunma at the following location:

<u>Latitude</u>	<u>Longitude</u>
36°25.56' N	138°57.30' E

The Japan LEOLUT can localise transmitters and distress beacons in local mode as well as global mode.

The local mode coverage of the Japan LEOLUT covers the area from Russia in the north to the western part of the Pacific and from China in the west to the central part of the Pacific.

The JAMCC and LUT operate 24 hours a day and send alert data to national RCCs within the JAMCC service area in accordance with document C/S A.001 and national procedures.

The JAMCC also assumes the nodal responsibilities for the Northwest Pacific DDR as defined at Annex I / A of this document.

The Japan Coast Guard (JCG) is responsible for the management and operation of the Japan Cospas-Sarsat ground segment.

2. SPOCs SUPPORTED

Japan

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at JAMCC:

Orbit vectors: receive from CMC, USMCC and forward to CNMCC, HKMCC, KOMCC, TAMCC and VNMCC;

SARP calibration: receive from FMCC and forward to CNMCC, HKMCC, KOMCC, TAMCC and VNMCC;

System status: originate, receive and forward from / to AUMCC, CMC, FMCC, USMCC, CNMCC, HKMCC, KOMCC, SPMCC, TAMCC and VNMCC.

4. BACKUP PROCEDURE AND AGREEMENTS

In the event of a failure of the nodal JAMCC, the duty personnel will:

- a. contact and advise the USMCC to assume JAMCC nodal responsibilities;
- b. contact and advise the CNMCC, HKMCC, KOMCC, TAMCC and VNMCC to divert all their traffic to the USMCC and to expect System information direct from the USMCC;
- c. request the USMCC to transmit JAMCC service area alerts in SIT 185 format. The JAMCC will attempt to pass them to its service area RCCs/SPOCs by manually geosorting them; and
- d. advise the USMCC that JAMCC will pass alerts from Japanese LUTs in some form on a 'best effort' basis.

5. OTHER INFORMATION

Beacon Registration

A beacon register on national units equipped with beacons is maintained at the JAMCC.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.KO KOMCC - KOREA MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The Korea Mission Control Centre is located at the Korea Coast Guard Headquarters (KCG) in Sejong and controls one LEOLUT at the following Incheon location:

<u>Latitude</u>	<u>Longitude</u>
37° 23.58' N	126° 38.94' E

The local mode of the Korea LEOLUT covers the area from the eastern part of Russia in the north to the Philippines and from the eastern part of China in the west to the western part of Pacific Ocean.

The LUT can locate transmitters and distress beacons in local mode as well as global mode.

The Korea MCC and LUT operate 24 hours a day throughout the year and send alert data to countries within the KOMCC service area in accordance with document C/S A.001 and national procedures.

The Korea Coast Guard is responsible for the operation of the KOMCC and LUT.

2. SPOCs SUPPORTED

Korea (Republic of)

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at KOMCC:

Orbit vectors: received from JAMCC;
SARP calibration: received from JAMCC;
System status: originated to and received from JAMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The LEOLUTs at Incheon and Gunma have overlapping localmodecoverage areas. It is therefore feasible for one to backup the other in case of failure or planned maintenance downtime. Co-operation in the coverage of individual satellites passes may also be feasible in the future.

In the case of complete failure of the KOMCC, the JAMCC will assume the duties of the KOMCC. The following procedures apply:

- a. Incheon LEOLUTs manually forward their alert data to the selected SPOCs/RCCs; and
- b. the JAMCC provides alert data to the KOMCC via Fax for further distribution to SPOCs/RCCs by the KOMCC.

5. OTHER INFORMATION

Beacon Registration

A database of the Korean registered beacons is maintained at the KOMCC.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.NI NIMCC - NIGERIA MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The Nigeria Mission Control Centre is co-located with one LEOLUT in the National Emergency Management Agency Building at the following location:

<u>Latitude</u>	<u>Longitude</u>
09° 04.56' N	007° 29.58' E

The local mode of the Abuja LEOLUT covers Central Africa and the Eastern part of the Atlantic Ocean. The LEOLUT can locate transmitters and distress beacons in local mode as well as global mode. The Nigeria MCC and LEOLUT operate 24 hours a day throughout the year and send alert data to MCCs and SPOCs, in accordance with the document C/S A.001 and national procedures.

2. SPOCs SUPPORTED

Nigeria.

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at NIMCC:

Orbit vectors: receive from SPMCC;
SARP calibration: receive from SPMCC;
System status: originate to and receive from SPMCC.

4. BACKUP PROCEDURE AND AGREEMENTS

In case of complete failure of the NIMCC, the SPMCC will assume the duties of the NIMCC. The SPMCC will send validated Cospas-Sarsat alert data within the NIMCC service area to designated SPOCs.

Operators will forward a written notice to their backup MCC of intention to perform maintenance routines requiring a backup at least 24 hours in advance.

As described in section I / A-SP-2, in the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. In that case, the NIMCC will change its configuration in order to consider the FMCC as its current nodal MCC until the backup situation is finished. When the backup is finished, the NIMCC will revert to its normal configuration in order to consider the SPMCC as its nodal MCC.

5. OTHER INFORMATION

A database of registered beacons is maintained by the Nigerian Maritime Administration and Safety Agency and Nigerian Civil Aviation Authority.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.NO NMCC - NORWEGIAN MISSION CONTROL CENTRELast updated: October 2014**1. GENERAL**

The Norwegian Mission Control Centre is a combination between the LEOLUT in Spitsbergen, a GEOLUT at Fauske and MCC in Bodoe. These form the NMCC with the Spitsbergen LEOLUT and the GEOLUT at Fauske as the technical bodies of the MCC, and MCC Bodoe as the operational body. The NMCC is integrated and co-located with JRCC Bodoe.

The LEOLUT is installed at the following location:

	<u>Latitude</u>	<u>Longitude</u>
Spitsbergen	78° 13.74' N	015° 23.76' E

The GEOLUT is installed at the following location:

	<u>Latitude</u>	<u>Longitude</u>
Fauske	67° 14.14' N	015° 17.87' E

The NMCC also provides global mode locations. The NMCC operates 24 hours per day, 7 days a week.

2. SPOCs SUPPORTED

The NMCC provides alert data to SPOCs in the NMCC service area including:

Denmark	Greenland	Norway
Estonia	Iceland	Sweden
Faroe Islands	Latvia	
Finland	Lithuania	

A summary of communication systems for these interfaces follows:

SPOCs in NMCC service area:	FTP	AFTN	Fax	Voice
FMCC:	FTP-VPN	AFTN	Fax	Voice
ITMCC:	FTP-VPN	AFTN	Fax	Voice
UKMCC:	FTP-VPN	AFTN	Fax	Voice
TRMCC:	FTP-VPN	AFTN	Fax	Voice
GRMCC:	FTP-VPN	AFTN	Fax	Voice
SPMCC (nodal backup):	FTP-VPN	AFTN	Fax	Voice

3. SYSTEM INFORMATION MESSAGES

NMCC originates and receives the following System information messages:

System status: originate and receive, normally through FMCC;
Narrative: for status messages;
SARP calibration: via FMCC;
Orbit vectors: via FMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The Spitsbergen LEOLUT has overlapping local mode coverage areas to a greater or lesser extent with the following LEOLUTs: Combe Martin and Toulouse. It is therefore feasible for one to back up the other in the case of failure or planned maintenance downtime.

In the case of complete failure of the NMCC, the UKMCC will assume the duties of the NMCC. UKMCC will send validated Cospas-Sarsat alert data, within the NMCC service area to designated SPOCs or RCCs.

In the case of complete failure of the UKMCC, the NMCC will assume the duties of the UKMCC. NMCC will send validated Cospas-Sarsat alert data, within the UKMCC service area to designated SPOCs or RCCs. In the UK SRRs this will be MRCC Falmouth.

5. OTHER INFORMATION

NMCC has access 24/7 to the Norwegian beacon registries (EPIRBs, ELTs and PLBs with country codes 257, 258 and 259).

The Ministry of Justice and Public Security is responsible for the administrative coordination of the Norwegian Rescue Service (<http://www.regjeringen.no/en/dep/jd.html?id=463>).

The NMCC is collocated with JRCC North-Norway.

- END OF THIS SECTION -

I / A.PA PAMCC - PAKISTAN MISSION CONTROL CENTRE

Last updated: October 2010

1. GENERAL

The Pakistan Mission Control Centre is located at the Space Research Centre (SPARCENT), SUPARCO Karachi and controls one Local User Terminal (LUT) and two Rescue Coordination Centres (RCCs) at Karachi:

<u>Latitude</u>	<u>Longitude</u>
24° 56.76' N	067° 08.16' E

The PALUT can locate distress beacons in local mode, as well as in global mode. In addition, the PALUT can process the repeater channel for interference monitoring.

The local mode-coverage of the PALUT includes countries from Saudi Arabia to China and the Commonwealth of Independent States (CIS) to Sri Lanka.

The PALUT and PAMCC are operating 24 hours a day throughout the year. The Pakistan Space and Upper Atmospheric Research Commission (SUPARCO) is responsible for the PALUT and PAMCC operations while RCC1 is operated by Pakistan Civil Aviation Authority (CAA) and RCC2 is operated by Pakistan Maritime Security Agency (MSA).

2. SPOCs SUPPORTED

Pakistan

3. SYSTEM INFORMATION MESSAGES

The PAMCC receives and originates System status information from / to the CMC.

4. BACKUP PROCEDURES AND AGREEMENTS

In the unlikely event of the PAMCC failure, the PAMCC has backup agreements with the CMC.

5. OTHER INFORMATION

A register of national units equipped with beacons will be maintained in the IBRD and locally at PAMCC.

- END OF THIS SECTION -

I / A.PE PEMCC - PERUVIAN MISSION CONTROL CENTRE

Last updated: October 2013

1. GENERAL

The Peruvian Mission Control Centre is located in Callao and controls two LUTs located at the following co-ordinates:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT	12° 01.84' S	077° 07.79' W
GEOLUT	12° 01.85' S	077° 07.80' W

The local mode coverage of the Peruvian LEOLUT covers the areas of Bolivia, Colombia, Costa Rica, Ecuador, French Guiana, Guatemala, Guyana, Panama, Paraguay, Surinam, Uruguay, Venezuela, and parts of Argentina, Brazil, and Chile, and extends 3,000 nm into the Pacific Ocean to the West.

The PEMCC and LUTs operate 24 hours a day throughout the year.

The General Direction of Captaincies and Coast Guard of the Peruvian Navy (DICAPI) is responsible for the PELUT, PEMCC and Peruvian RCCs operations.

2. SPOCs SUPPORTED

PEMCC provides primary support to the Peruvian RCCs.

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at PEMCC:

Orbit vectors: received from USMCC;
SARP calibration: received from USMCC;
System status: received and originated as required;
Narrative: received and originated as required.

4. BACKUP PROCEDURES AND AGREEMENTS

In the unlikely event of a PEMCC failure, Peru has a backup agreement with Argentina. In accordance with the following procedures, the ARMCC will assume the duties of the PEMCC:

- a. The PEMCC notifies the ARMCC when the backup service is required by Phone or optionally by Email.
- b. The ARMCC notifies the PEMCC when backup service commences by Phone, Fax or Email.

- c. The ARMCC sends a SIT 605 message notifying all MCCs of the PEMCC failure and that the ARMCC is performing backup service according to section 3.7 of document C/S A.001.
- d. The ARMCC transmits alerts for the Peruvian service area in SIT 185 format to PEMCC via Fax or Email;
- e. Once the failure is overcome, the PEMCC sends a SIT 605 message notifying the ARMCC and all MCCs that the PEMCC has resumed normal operations.
- f. The ARMCC will send all requested missing messages to the PEMCC.

5. OTHER INFORMATION

406 MHz EPIRBs have been approved for carriage on Peruvian vessels. A beacon register of Peruvian beacons is maintained at the PEMCC.

The PEMCC is responsible for the allocation of serial numbers for all serialized coded beacons and the maintenance of the Peruvian 406 MHz beacon database register and can be contacted at any time to obtain database information. Purchasers of 406 MHz beacons are required to follow the registration procedure provided in DICAPI's Unique Text of Administrative Procedures (TUPA): www.serviciosalciudadano.gob.pe/tramites/11794/3413.htm.

- END OF THIS SECTION -

I / A.QA**QAMCC - QATAR MISSION CONTROL CENTRE**

(Under development)

Last updated: December 2016**1. GENERAL**

The Qatar Mission Control Centre is located at Losail, Qatar. The QAMCC controls a LEOLUT and a GEOLUT at the same location as the QAMCC.

The LUTs are located at the following co-ordinates:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT	25° 30.00' N	051° 27.24' E
GEOLUT	25° 29.94' N	051° 27.25' E

The QAMCC and LUTs operate 24 hours a day throughout the year.

Ministry Of Defence through Doha Joint Rescue Coordination Center (DJRCC) is responsible for management and operation of the Qatar Cospas – Sarsat ground segment.

2. SPOCs SUPPORTED

The QAMCC provides primary support to the Qatar JRCC and routes alert and notification (NOCR) messages to other countries and can receive these messages from them.

The communication interfaces used by QAMCC are as follows:

FTP-VPN and AMHS.

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at QAMCC:

Orbit vectors:	receive from SPMCC;
SARP calibration:	receive from SPMCC;
System status:	originate to and receive from SPMCC;
Narrative:	receive and originate as required.

4. BACKUP PROCEDURES AND AGREEMENTS

In case of complete failure of the QAMCC, the SPMCC will assume the duties of the QAMCC. The SPMCC will send validated Cospas-Sarsat alert data within the QAMCC service area to designated SPOCs. Operators will forward a written notice to their backup MCC of intention to perform maintenance routines requiring a backup at least 24 hours in advance.

As described in section I / A-SP-2, in the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. In that case, the QAMCC will change its configuration in order to consider the FMCC as its current nodal MCC until the backup situation is finished. When the backup is finished, the QAMCC will revert to its normal configuration in order to consider the SPMCC as its nodal MCC.

5. OTHER INFORMATION

Beacon Registration

TBD

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.SA**SAMCC - SAUDI ARABIAN MISSION CONTROL CENTRE**

Last updated: December 2016

1. GENERAL

The Saudi Arabian Mission Control Centre is co-located with the RCC in Jeddah. The SAMCC controls two LEOLUTs with G-SARP. These two LUTs are located at:

<u>Latitude</u>	<u>Longitude</u>
21° 39.90' N	039° 08.76' E

These two LEOLUTs are known as SALUT1 (ID: 4031) and SALUT2 (ID: 4032) and provide local mode coverage of the whole Middle East region.

The Saudi MCC and LEOLUTs operate 24 hours a day throughout the year providing alert data through the co-located RCC.

The Saudi General Authority of Civil Aviation (GACA) is responsible for the management and operation of the Saudi Cospas-Sarsat ground segment.

2. SPOCs SUPPORTED:

Bahrain	Lebanon	Saudi Arabia
Jordan	Oman	Syria
Kuwait	Qatar*	Yemen

Note: * Until IOC of Qatar MCC (QAMCC).

The communication interfaces used by the SAMCC are:

FTP-VPN AFTN

3. SYSTEM INFORMATION MESSAGES

The SAMCC originates and receives the following System information messages:

Orbit vectors: receive from SPMCC;
SARP calibration: receive from SPMCC;
System status: originate and receive from SPMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

In the case of complete failure of the SAMCC, the SPMCC will assume the duties of the SAMCC. SPMCC will send validated Cospas-Sarsat alert data within the SAMCC service area to designated SPOCs.

In a backup situation, it is not guaranteed that messages sent to the Saudi Arabia primary AFTN address are received by the SAMCC/Jeddah RCC staff, for that reason a secondary AFTN address has been implemented to provide message service to the Jeddah RCC during backup.

Therefore, in case of any situation that SPMCC has to backup SAMCC, the SPMCC will send alerts within the Saudi Arabia MCC service area to the Jeddah RCC using the secondary AFTN address, which was provided for that purpose. In case the AFTN link is unavailable, the SPMCC will use the Fax.

Operators will forward a written notice to their backup MCC of intention to perform maintenance routines requiring a backup at least 24 hours in advance.

As described in section I / A-SP-2, in the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. In that case, the SAMCC will change its configuration in order to consider the FMCC as its current nodal MCC until the backup situation is finished. When the backup is finished, the SAMCC will revert to its normal configuration in order to consider the SPMCC as its nodal MCC.

5. OTHER INFORMATION

To be determined.

- END OF THIS SECTION -

I / A.SI**SIMCC - SINGAPORE MISSION CONTROL CENTRE**

Last updated: October 2010

1. GENERAL

The Singapore Mission Control Centre is located at the Singapore Air Traffic Control Centre, LORADS Complex, Biggin Hill at the following location:

<u>Latitude</u>	<u>Longitude</u>
01° 23.40' N	103° 59.10' E

Singapore's LEOLUT at Changi Airport Terminal 2 can locate transmitters and distress beacons in local mode as well as global mode.

The local mode coverage of Singapore LEOLUT is able to cover the ASEAN areas (Brunei, Indonesia, Malaysia, Singapore and South West of Philippines) as well as Cambodia, Laos, Myanmar and North West of Australia.

A second operator control console (OCC) serves as a backup MCC and is located at the LORADS Complex Rescue Co-ordination Centre (RCC). A third OCC is located at the Maritime and Port Authority of Singapore, Tanjong Pagar Complex.

The Singapore MCC and LEOLUT operate 24 hours a day throughout the year.

The Civil Aviation Authority of Singapore and the Maritime Authority of Singapore are responsible for the operation of the Singapore LEOLUT and MCC.

2. SPOCs SUPPORTED

The SIMCC can provide alert data to SPOCs in the SIMCC service area including:

Brunei	Myanmar
Malaysia	Singapore

The communication interfaces used by SIMCC are:

AUMCC:	FTP-VPN	AFTN	Voice
SPOCs:	AFTN	Voice	

3. SYSTEM INFORMATION MESSAGES

The SIMCC originates and receives the following System information messages:

Orbit vectors:	receive from AUMCC;
SARP calibration:	receive from AUMCC;
System status:	originate and receive from AUMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The LEOLUTs at Singapore, Australia, India and Hong Kong have overlapping local mode coverage areas to a greater or lesser extent. It is therefore feasible for the Singapore area to be fully covered in the case of failure or planned maintenance downtime.

In the event the SIMCC becomes unserviceable, the THMCC will provide backup support to the SIMCC. All the alerts for the SIMCC service area will be transmitted in SIT 185 format to a Fax number nominated by the SIMCC or via AFTN.

The SIMCC is a backup of the THMCC and IDMCC. Should the THMCC or IDMCC become unserviceable, messages will be passed via AFTN or Fax.

5. OTHER INFORMATION

Beacon Registration

A register of national ships equipped with beacons is maintained by the Maritime and Port Authority. Users of maritime EPIRBs installed on Singapore ships are required to register their EPIRBs with the Singapore Register, the Telecommunication Authority of Singapore (TAS), Radio Standard/Licensing Department.

A register of all aviation beacons are maintained by the Civil Aviation Authority of Singapore (CAAS). Users of aviation beacons carried on board Singapore registered aircraft are required to register their beacons with the CAAS. A register for both aviation and maritime beacons is available at the SIMCC.

- END OF THIS SECTION -

I / A.SP SPMCC - SPANISH MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The Spanish Mission Control Centre is co-located with one LEOLUT in Instituto Nacional de Técnica Aeroespacial (INTA) at the Maspalomas Tracking Station in Gran Canaria, at the following location:

<u>Latitude</u>	<u>Longitude</u>
27°45.68' N	015°37.90' W

The LEOLUT is equipped with a dedicated antenna which makes possible tracking of all Cospas-Sarsat satellites passing over Canary Islands, unless satellites are in conflict.

The LEOLUT can localise transmitters and distress beacons in local mode and global mode. Interferers in the 406.0 MHz to 406.1 MHz band are localised in the local mode, and this information is provided to the Spanish Telecommunication Administration for action through ITU. The Maspalomas LEOLUT provides local mode coverage of North-Central Atlantic and North West Africa to latitude 0 degrees and operates 24 hours per day throughout the year.

The SPMCC also controls two GEOLUTs which are co-located with the LEOLUT.

Alert data are validated and transmitted to MCCs and SPOCs, in accordance with document C/S A.001 and national procedures.

The SPMCC also assumes the nodal responsibilities for the South Central DDR as defined at Annex I / A of this document.

2. SPOCs SUPPORTED

The Spanish Mission Control Centre receives alert data from the Maspalomas LEOLUT and GEOLUTs and from other Cospas-Sarsat MCCs in accordance with document C/S A.001. It provides Cospas-Sarsat alert data to the following countries:

Benin	Gabon	Mauritania
Cameroon	Gambia	Sao Tome and Principe
Cape Verde	Ghana	Senegal
Central African Republic	Guinea	Sierra Leone
Congo	Guinea-Bissau	Spain
Côte d'Ivoire	Liberia	Togo
Equatorial Guinea	Mali	

The communication interfaces used by the SPMCC are:

AEMCC:	FTP-VPN	AFTN
ALMCC:	FTP-VPN	AFTN
AUMCC:	FTP-VPN	AFTN
CMC:	FTP-VPN	AFTN
FMCC:	FTP-VPN	AFTN
JAMCC:	FTP-VPN	AFTN
NIMCC:	FTP-VPN	AFTN
SAMCC:	FTP-VPN	AFTN
USMCC:	FTP-VPN	AFTN

3. SYSTEM INFORMATION MESSAGES

The following System information is received / originated at SPMCC:

Orbit vectors: receive from CMC and USMCC and forward to AEMCC, ALMCC, NIMCC and SAMCC;

SARP calibration: receive from FMCC and forward to AEMCC, ALMCC, NIMCC and SAMCC;

System status: originate, receive from and forward to AEMCC, ALMCC, AUMCC, CMC, FMCC, JAMCC, NIMCC, SAMCC and USMCC.

4. BACKUP PROCEDURE AND AGREEMENTS

The Maspalomas LEOLUT has overlapping local mode coverage areas with the following LEOLUTs: Abuja, Bari, Combe Martin, Maspalomas, Ouargla and Toulouse. It is feasible for one to backup the other in case of failure or planned maintenance downtime. Co-operation in the coverage of individual satellite passes may also be feasible in the future.

The LUT operators will forward written advance notice of routine maintenance deactivation of a LUT. The MCC will advise all others MCCs as soon as decision has been taken and confirm the times a minimum of two weeks before deactivation. In case of failure, the LUT operators will inform the associated MCC in the quickest possible way followed by a written confirmation when an estimate of the duration of the downtime is available. The MCC will inform immediately the MCCs in South Central DDR and the nodal MCCs.

In the case of a complete failure of the SPMCC, the FMCC will assume the duties of the SPMCC. FMCC will send validated Cospas-Sarsat alert data within the SPMCC service area and within other areas to designated SPOCs or RCCs. In the Spanish SRR this will be RCC Madrid and CNCS (MRCC). It was agreed to periodically exchange test messages between FMCC and the Spanish RCCs (RCC Madrid and CNCS) to check the communication links. All validated Cospas-Sarsat alert data within the South Central DDR service area will be directly transmitted to the destination MCC.

In the case that SPMCC has to assume the backup duties for FMCC, SPMCC will be able to process and relay the alert messages originally created for FMCC, that is to say, with MF#5 set to 2270.

In the case of complete failure of the AEMCC, the SPMCC will assume the duties of the AEMCC. The SPMCC will send validated Cospas-Sarsat alert data within the AEMCC service area to Abu Dhabi SAR Coordination Center for further distribution to AEMCC designated SPOCs.

In the case of a complete failure of the ALMCC, the SPMCC will assume the duties of the ALMCC. The SPMCC will send validated Cospas-Sarsat alert data within the ALMCC service area to designated SPOCs. In the Algerian SRR this will be Algiers RCC (this AFTN address is DAALZSZX).

In the case of a complete failure of the NIMCC, the SPMCC will assume the duties of the NIMCC. The SPMCC will send validated Cospas-Sarsat alert data within the NIMCC service area to designated SPOCs.

In the case of a complete failure of the SAMCC, the SPMCC will assume the duties of the SAMCC. The SPMCC will send validated Cospas-Sarsat alert data within the SAMCC service area to designated SPOCs.

5. OTHER INFORMATION

Beacon Registration

A database of the Spanish register for maritime Cospas-Sarsat beacons is maintained by the General Directorate of Merchant Navy, and another database of the Spanish register for aviation Cospas-Sarsat beacons is maintained by the General Directorate of Civil Aviation, with a copy of both databases at the SPMCC.

- END OF THIS SECTION -

I / A.TA TAMCC - ITDC / TAIPEI MISSION CONTROL CENTRE

Last updated: October 2013

1. GENERAL

The ITDC / Taipei Mission Control Centre is located in the Taipei Air Navigation and Weather Services (ANWS), Civil Aeronautics Administration (CAA), at Taipei domestic airport. Two LEOSAR Local User Terminals (dual LEOLUT system) are located at Keelung Coast Radio Station with the following co-ordinates:

<u>Latitude</u>	<u>Longitude</u>
25° 08.10' N	121° 45.42' E

Both LEOLUTs can localise transmitters and distress beacons in local mode and global mode.

The local mode coverage of the ITDC LEOLUTs includes the area from Eastern part of the Indian Ocean to Western part of the Pacific Ocean.

The TAMCC and LEOLUTs operate 24 hours a day throughout the year.

The Civil Aeronautics Administration and the Maritime Department of the Ministry of Transport and Communications are responsible for the operation of the TAMCC and LEOLUTs.

2. SPOCs SUPPORTED

The TAMCC provides primary support to Chinese Taipei RCCs.

The communication interfaces used by TAMCC are:

FTP-VPN AFTN Voice Facsimile

3. SYSTEM INFORMATION MESSAGES

The TAMCC originates and receives the following System information messages:

Orbit vectors: receive from JAMCC;
SARP calibration: receive from JAMCC;
System status: originate to and receive from JAMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The TAMCC established a mutual backup procedure with the HKMCC for system outage on either side.

ITDC LEOLUTs have overlapping local mode coverage areas to a greater or lesser extent with the following LEOLUTs: Guam, Hong Kong, Cengkareng, Nakhodka, Singapore, Incheon and Gunma. It is therefore feasible for the Chinese Taipei area to be fully covered in the case of failure or planned maintenance downtime.

5. OTHER INFORMATION

Beacon Registration

A register of national ships equipped with beacons is maintained by the Directorate General of Telecommunications (DGT). Users of maritime EPIRBs installed on Chinese Taipei ships are required to register their EPIRBs with the Directorate General of Telecommunications (DGT), Radio Standard/Licensing Department.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.TH THMCC - THAILAND MISSION CONTROL CENTRE

Last updated: October 2010

1. GENERAL

The Thailand Mission Control Centre (THMCC) is located at the Department of Aviation in Bangkok. The THMCC controls two LEOLUTs.

The Thai LEOLUTs provide full capability processing, including G-SARP processing of the transponded SARR data and combined LEO/GEO processing, according to the relevant Cospas-Sarsat specifications. The local coverage area of the Thai LEOLUTs includes the Bay of Bengal, parts of the Indian Ocean, and the South China Sea, as well as the land area of South Asia, including all of Thailand and the Malaysian Peninsula.

The entire Thai Ground Segment is designed for 24 hours, seven days a week, operations.

2. SPOCs SUPPORTED

In its initial operational configuration, the Thai MCC will support the RCCs in Thailand.

3. SYSTEM INFORMATION MESSAGES

The THMCC will receive and process the following System information messages:

Orbit Vectors
SARP Calibration Data
SARR Calibration data
System Status
Narrative

The THMCC is capable of originating the following system information messages:

System Status
Narrative

These messages will normally be received from, or sent to, the designated nodal MCC.

4. BACKUP PROCEDURES AND AGREEMENTS

In the event the THMCC becomes unserviceable, the SIMCC will provide backup support to the THMCC. All alerts for the THMCC service area will be transmitted in SIT 185 format and to a Fax number nominated by THMCC or via AFTN. The THMCC will ensure distribution to the RCCs and SPOCs it supports.

The local coverage area of the Thai LEOLUTs overlaps with the coverage area of LEOLUTs operated by Hong Kong, China, India, Indonesia, Singapore, and ITDC. In the fringe coverage areas, there is also some overlap with LUTs operated by China (P. R. of), Japan, Korea, Pakistan, and the USA (Guam).

5. OTHER INFORMATION

None.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.TR TRMCC - TURKEY MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The Turkey Mission Control Centre is located at the Main SAR Coordination Centre (MSRCC) building (G.M.K. Bulvari No: 128/A, 06570 Maltepe, Ankara). Two LEOLUTs and one GEOLUT are installed at the Ankara Esenboga Airport.

LUTs are located at the following co-ordinates:

	<u>Latitude</u>	<u>Longitude</u>
LEOLUT (1)	40° 08.45' N	032° 59.38' E
LEOLUT (2)	40° 08.44' N	032° 59.38' E
GEOLUT	40° 08.42' N	032° 59.40' E

Turkey LEOLUTs can localise transmitters and distress beacons in local mode and global mode.

The TRMCC and LEOLUTs operate 24 hours a day throughout the year.

The communication interfaces used by TRMCC are as follows:

AFTN FTP-VPN Facsimile Voice

2. SPOCs SUPPORTED

The TRMCC provides primary support to the Turkey RCCs and routes alert and notification (NOCR) messages to other countries and can receive these messages from them. The TRMCC distributes alert data for the following SPOCs: Afghanistan, Georgia*, Iran, Iraq, and Ukraine*.

Note: * There is an overlap with the CMC service area.

3. SYSTEM INFORMATION MESSAGES

The TRMCC originates and receives the following System information messages:

Orbit vectors:	receive from FMCC;
SARP calibration:	receive from FMCC;
System status:	originate to and receive from FMCC;
Narrative:	received and originated as required.

4. BACKUP PROCEDURES AND AGREEMENTS

TRMCC operates two Operational Control Consoles (OCC), one of them being a backup. In the event of failure of both TRMCC OCCs, Turkey has backup agreements and procedures in place with Italy. The following procedures have been agreed to:

- a) Whenever the backup service is required, TRMCC notifies ITMCC by means of Fax, Telephone or Email;
- b) ITMCC notifies TRMCC when the backup service commences by Fax, Telephone or Email;
- c) ITMCC sends a SIT 605 message notifying the other MCCs of the TRMCC failure, and that ITMCC is performing backup service according to section 3.7, document C/S A.001;
- d) TRMCC advises the Turkish RCCs and SPOCs about the TRMCC failure and the backup procedures;
- e) ITMCC transmits alerts for the Turkish service area in SIT 185 format to:
 - TRMCC using the Turkish MSRCC Fax, and
 - TRMCC SPOCs using SPOCs communication links mentioned in item (l) below;
- f) In the event that ITMCC is unable to communicate with TRMCC and/or TRMCC SPOCs as described above, ITMCC shall transmit alerts for the Turkish service area in SIT 185 format to MSRCC/Ankara via Inmarsat-C Telex or Fax. In this case, ITMCC will advise MSRCC/Ankara of their inability to communicate with TRMCC and/or the TRMCC SPOCs. Other Turkish RCCs and SPOCs as well as TRMCC will be advised by MSRCC/Ankara;
- g) TRMCC will notify ITMCC as soon as the problem is solved, and will advise the time when TRMCC plans to restore normal operations;
- h) When TRMCC returns to normal operations it will send a SIT 605 message notifying ITMCC and other MCCs that TRMCC has resumed normal operations. TRMCC will also notify its RCCs and SPOCs that it has resumed normal operations;
- i) ITMCC will send all requested missing messages to TRMCC;
- j) ITMCC shall contact TRMCC by means of:

Tel : +90.312.2313374
Fax : +90.312.2312902
E-mail : trmcc@udhb.gov.tr
AFTN : LTACZSZX

k) ITMCC shall contact MSRCC/Ankara by means of:

Tel : +90.312.2319105 / 2324783
Fax : +90.312.2320823
Email : trmrcc@udhb.gov.tr
Inm-C : 427122324

l) ITMCC shall contact the TRMCC SPOCs by means of:

- Iran (Tehran RCC)
Tel: +98.214.4544116/4544060
Fax: +98.214.4544117
AFTN: OIIIZRZX
- Iraq & Afghanistan (Qatar JPRC)
Tel: +974.4589555 / 4364215
Email: jprc.chief1@afcent.af.mil
- Georgia
Tel: + 995 (422) 273913
Fax: + 995 (422) 273905
Email: mrcc@mta.gov.ge
AFTN: UGGGYCYX
- Ukraine
Tel: +380 44 351 59 91 - Senior Engineer of Ukraerocenter
E-mail: rcc@uksatse.aero (primary)
mrcc.ode@sar.gov.ua (primary)
AFTN: UKKKZDZY
Operation Center (24 hours):
Person in Charge (working hours only):
Head of ASM dept.
Tel: +380 44 351 6192

m) TRMCC shall contact ITMCC by means of:

Tel : +39 080 5341571 - 5344033
Fax : +39 080 5342145
Email : itmccoperator@cospas-sarsat-italy.it
AFTN : LIJCYFYX

5. OTHER INFORMATION

A register of beacons is maintained at the TRMCC.

- END OF THIS SECTION -

I / A.UK UKMCC - UNITED KINGDOM MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The United Kingdom Mission Control Centre is located at Fareham, Hampshire, England. The hardware equipment is co-located with the ARCC at Kinloss, in NE Scotland and controls one LEOLUT and one GEOLUT located at Combe Martin, in SW England. The UKMCC has a hot backup MCC in a separate building, also located at Kinloss. The UKMCC is manned 24 hours per day throughout the year, including public holidays.

UKMCC Address

National Maritime Operations Centre
Unit 4, Kites Croft Business Park
Fareham
Hampshire
PO14 4LW

UKMCC Telephone Numbers

MCC Administration: +443443820902
MCC Incident: +443443820903
MCC Central DDR: +443443820904

UKMCC email

General: ukmcc@hmcc.gov.uk
UKMCC Manager: ukmccmanager@hmcc.gov.uk

The UK LEOLUT operates in the global mode and provides local mode coverage of Europe, the Eastern half of the North Atlantic Ocean and part of Southern Scandinavia. Alert data from the UK LEOLUT and GEOLUT is transmitted to the UKMCC via two 64 kb Kilostream lines, one line feeding the Primary MCC and the other, the backup MCC. The UKMCC uses AFTN, FTP-VPN, Fax, point-to-point data-link and voice Telephone to distribute data to MCCs and RCCs.

2. SPOCs SUPPORTED

The UKMCC provides alert data to the United Kingdom's ARCC, MRCCs and Police Forces, and to the Republic of Ireland's MRCC Dublin.

The UKMCC also provides alert and Notification of Beacon Registration (NOCR) messages to MCCs within the Central Data Distribution Region. Alert messages for areas outside the Central DDR are routed to the FMCC. NOCR messages are routed in accordance with Figure II / A.8 of document C/S A.001.

The communications interfaces used by UKMCC are:

UK ARCC:	Data-link	Fax	Voice
UK MRCCs:	Fax	Voice	
Irish MRCC:	AFTN	Fax	Voice
UK Police:	Fax	E-mail (see note)	Voice
FMCC:	AFTN	FTP-VPN	Fax
ITMCC:	AFTN	FTP-VPN	Voice
NMCC:	AFTN	FTPV-VPN	Fax
TRMCC:	AFTN	FTP-VPN	Voice

Note: All distress-alert transmissions to SPOCs, over whichever data medium, are accompanied by a telephone call.

3. SYSTEM INFORMATION MESSAGES

The following System information messages are received / originated at UKMCC:

Orbit vectors:	received from FMCC;
SARP calibration:	received from FMCC;
System status:	received and originated as required;
Narrative:	received and originated as required;
406 MHz SARR frequency calibration:	receive from CMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

The Combe Martin LEOLUT has overlapping local mode coverage areas to a greater or lesser extent with the following LEOLUTs: Bari, Maspalomas, Ouargla, Spitsbergen, Tromsoe and Toulouse. It is therefore feasible for one to back up the other in the case of failure or planned maintenance downtime.

Co-operation in the coverage of individual satellites passes may also be feasible, but requires further study.

LEOLUT operators will forward a written notice of intention to perform maintenance routines involving deactivation of LEOLUT well in advance. The MCC will inform all other MCCs as soon as a decision has been taken, and confirm the times a minimum of two weeks prior to deactivation.

The LEOLUT operator will inform the associated MCC by the quickest possible means, followed by a written confirmation when an estimate of the duration of the downtime is available. The MCC will immediately inform the other MCCs.

The UKMCC has a backup facility also located at Kinloss but, in the case of complete failure of the UKMCC, the NMCC will assume the duties of the UKMCC. The NMCC will send validated Cospas-Sarsat alert data, within the UKMCC service area to designated SPOCs or RCCs. In the UK SRRs this will be MRCC Falmouth, and for Eire this will be MRCC Dublin.

The UKMCC provides backup facilities for the NMCC.

5. OTHER INFORMATION

An ELT register of UK serial-coded beacons is maintained at UKMCC.

A register of UK EPIRB beacons is maintained at MRCC Falmouth.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.US USMCC - UNITED STATES MISSION CONTROL CENTRE

Last updated: December 2015

1. GENERAL

The United States Mission Control Centre is located at the National Oceanic and Atmospheric Administration, Suitland, Maryland. The USMCC controls dual operational LEOLUTs at the following locations:

Fairbanks, Alaska
Vandenberg AFB, California
Wahiawa, Hawaii
Andersen AFB, Guam
Miami, Florida.

The LEOLUTs provide coverage of the U.S. SRRs from mid-Atlantic to the western-Pacific, and from the North Pole south to approximately 15 degrees south. Operations are 24 hours per day, seven days a week.

The USMCC also controls a LEOLUT at Suitland, MD known as the LEOSAR Support Equipment or LSE. The LSE is used for LEOLUT system development and testing. When not being used for development and testing, the LSE is used operationally.

The USMCC also controls two operational GEOLUTs (MD1 and MD2) which are located in Suitland, MD. A third GEOLUT, the GEOSAR Support Equipment (GSE), is used for GEOLUT system development and testing but can also be used operationally, when available.

The USMCC uses a dedicated frame relay network for communications with its LUTs and the majority of its RCCs. AFTN and FTP-VPN are used for communication with other MCCs. AFTN and Fax are used for communication with the USMCC SPOCs.

The USMCC also assumes the nodal responsibilities for the Western DDR as defined at Annex I / A of this document.

The National Oceanic and Atmospheric Administration is the lead agency in the United States for the Cospas-Sarsat Programme.

2. SPOCs SUPPORTED

In support of the United States National Search and Rescue Plan, the USMCC provides alert and NOCR messages to U.S. Coast Guard and Air Force Rescue Co-ordination Centres. The USMCC distributes alert and NOCR messages to the following SPOCs:

CARIBBEAN:

Bahamas (1)	Curacao	Jamaica (1)
Barbados (3)	Dominican Republic	Mexico
Belize (2)	El Salvador (2)	Nicaragua (2)
British Virgin Islands (3)	Grenada (3)	Panama
Cayman Islands (1)	Guatemala (2)	St. Vincent and the Grenadines (3)
Costa Rica (2)	Haiti (1)	Trinidad and Tobago (3)
Cuba (1)	Honduras (2)	Turks and Caicos Island (1)

- (1) Alert messages for this SPOC are distributed to the USCG District 7 RCC.
- (2) Alert messages for this SPOC are distributed to COCESNA (Corporación Centroamericana de Servicios de Navegación Aérea or Central American Corporation for Air Navigation Services).
- (3) Alert messages for this SPOC are distributed to USCG Sector San Juan RCC.

SOUTH AMERICA:

Colombia	Guyana
Ecuador	Venezuela

ATLANTIC:

Bermuda

PACIFIC:

Marshall Islands	Northern Mariana Islands
Micronesia	Palau

Alert messages for all Pacific SPOCs are distributed to USCG District 14 MARSEC RCC.

3. SYSTEM INFORMATION MESSAGES

The USMCC processes the following System information messages:

SARR command verification:	originates to the CMCC;
SARP command verification:	originates to the FMCC;
SARR command:	receives from the CMCC;
SARP command:	receives from the FMCC;
System status:	originates, receives and sends;
Narrative:	originates, receives and sends;
Orbit vectors:	originates, receives, validates and sends;
SARP calibration:	receives, validates and sends;
406 MHz SARR frequency calibration:	receives, validates and sends.

4. BACKUP PROCEDURES AND AGREEMENTS

In the unlikely event of a USMCC failure, the USA has backup agreements and procedures in place with Australia and Canada. Australia provides backup for nodal MCC responsibilities and Canada and Australia together provide backup for other MCC alert data intended for U.S. RCCs and SPOCs. Accordingly, the USMCC has designated separate communications

paths and procedures for RCCs and SPOCs. The USA has also installed an alternate system at a site in Wallops, VA. The backup procedures will be used during the period of time required to transition from the USMCC in Suitland, MD to the alternate site in Wallops, VA or if the USMCC in Suitland and the alternate site in Wallops experience a simultaneous outage such as may occur during a regional power outage.

The USMCC has provided Australia and Canada with Geosort data for its national RCCs and SPOCs. In the event of a USMCC outage that lasts or is expected to last more than 30 minutes, but less than one (1) hour, the CMCC will support the USMCC by sending alert data directly to the U.S. RCCs.

In the event of a USMCC outage that lasts or is expected to last more than 1 hour, the AUMCC will assume nodal responsibilities for the Western DDR, send alerts for the U.S. SRR to the CMCC, and Fax alerts for the U.S. SPOCs to the USMCC.

The USMCC does not have the capability to reroute or redirect traffic to another MCC.

5. OTHER INFORMATION

406 MHz EPIRBs / ELTs have been approved for carriage on U.S. vessels and aircraft and PLBs are authorized for personal use in the U.S. A beacon register for USA beacons is maintained at the USMCC.

- END OF THIS SECTION -

This document has been superseded
by a later version

I / A.VN VNMCC - VIETNAM MISSION CONTROL CENTRE

Last updated: December 2016

1. GENERAL

The Vietnam Mission Control Centre is located at the Vietnam Maritime Communication and Electronics Company in Haiphong. The VNMCC controls one LEOLUT.

The Vietnam LEOLUT provides full processing, including G-SARP processing of the transponded SARR data, according to the relevant Cospas-Sarsat specifications. The local coverage area of the Vietnam LEOLUT includes the Bay of Bengal, parts of the Indian Ocean, and the South China Sea, as well as the land area of South Asia, including all of Vietnam.

The entire Vietnam ground segment is designed for 24 hours, seven days a week, operations.

2. SPOCs SUPPORTED:

The communication interfaces used by the VNMCC are:

FTP-VPN AFTN Facsimile Voice

3. SYSTEM INFORMATION MESSAGES

The VNMCC receives and processes the following System information messages:

Orbit vectors: receive from JAMCC;
SARP calibration data: receive from JAMCC;
System status: originating to and receive from JAMCC.

The VNMCC is capable of originating the following System information messages:

System Status

Narrative

These messages are normally received from, or sent to JAMCC.

4. BACKUP PROCEDURES AND AGREEMENTS

In the event the VNMCC cannot provide its service, the HKMCC will provide backup to the VNMCC. All alerts in the VNMCC service area will be sent in SIT 185 format to designated RCCs/SPOCs via FTP-VPN, AFTN or Fax.

The local coverage area of the Vietnam LEOLUT overlaps with the LEOLUTs operated by Hong Kong, India, Indonesia, ITDC, Singapore, and Thailand. In the fringe coverage areas, there is also some overlap with LUTs operated by China, Japan, Korea, Pakistan, and the United States (Guam).

5. OTHER INFORMATION

None.

- END OF THIS SECTION -

This document has been superseded
by a later version

ANNEX I / B**SID IMPLEMENTATION STATUS**

Document C/S A.002 "Cospas-Sarsat Mission Control Centres Standard Interface Description", approved by the Council, contains standardised message formats, identified by "Subject Identifier Type" (SIT) codes, which may be used by MCCs.

The tables shown below indicate which SITs for System information messages and alert and narrative messages have been implemented by the various MCCs.

They also indicate whether the capability is receive, originate, both receive and originate, or not implemented.

SYSTEM INFORMATION MESSAGES

as at: 8 December 2016

MCC Name	SIT NUMBER															
	215	216	217	415	416	417	425	435	445	510	515	525	535	545	605	
AEMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
ALMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
ARMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
ASMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
AUMCC	B	B	-	B	-	B	-	-	-	B	-	-	-	-	-	B
BRMCC	R	-	R	-	R	-	-	-	-	R	-	-	-	-	-	B
CHMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
CMC	B	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
CMCC	R	R	-	R	-	R	-	-	-	B	R	R	O	R	B	
CNMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
FMCC	B	B	-	B	B	B	R	O	R	-	-	-	-	-	-	B
GRMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
HKMCC	R	-	R	-	R	-	-	-	-	-	-	-	-	-	-	B
IDMCC	R	-	R	-	R	-	-	-	-	-	-	-	-	-	-	B
INMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
ITMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
JAMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
KOMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
NIMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
NMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
PAMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
PEMCC	R	-	R	-	R	-	-	-	-	-	-	-	-	-	-	B
SAMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
SIMCC	R	-	R	-	R	-	-	-	-	-	-	-	-	-	-	R
SPMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B
TAMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
THMCC	R	-	R	-	TBD	-	-	-	-	-	-	-	-	-	-	B
TRMCC	R	R	-	R	-	R	-	-	-	R	-	-	-	-	-	B
UKMCC	R	-	R	-	TBD	-	-	-	-	R	-	-	-	-	-	B
USMCC	B	O	-	B	O	B	O	R	O	B	O	O	R	O	B	
VNMCC	R	R	-	R	-	R	-	-	-	-	-	-	-	-	-	B

Legend:

O	originate
B	both originate and receive
R	receive
-	not implemented
TBD	to be determined

ALERT & NARRATIVE MESSAGES

(SIT messages 121 to 135 contain LEOSAR/GEOSAR data. SIT messages SIT 137 to 147 contain MEOSAR data.
 LEOSAR/GEOSAR/MEOSAR capable MCCs can process all SIT messages specified below)

as at: 8 December 2016

MCC Name	SIT Number									
	121	122 - 127	132 - 133	134 - 135	137 - 138	141	142 - 147	185	915	925
AEMCC	B	B	B	-	-	-	-	B	B	B
ALMCC	B	B	B	-	-	-	-	B	B	B
ARMCC	B	B	B	-	-	-	-	B	B	B
ASMCC	B	B	B	-	-	-	-	B	B	B
AUMCC	B	B	B	-	-	-	-	B	B	B
BRMCC	B	B	B	-	-	-	-	B	B	B
CHMCC	B	B	B	-	-	-	-	B	B	B
CMC	B	B	B	-	-	-	-	B	B	B
CMCC	B	B	B	-	-	-	-	B	B	B
CNMCC	B	B	B	-	-	-	-	B	B	R
FMCC	-	B	B	-	-	-	-	B	B	B
GRMCC	B	B	B	-	-	-	-	B	B	B
HKMCC	B	B	B	-	-	-	-	B	B	B
IDMCC	B	B	B	-	-	-	-	O	B	B*
INMCC	B	B	B	-	-	-	-	B	B	B
ITMCC	B	B	B	-	-	-	-	B	B	TBD
JAMCC	B	B	B	-	-	-	-	B	B	B
KOMCC	B	B	B	-	-	-	-	B	B	B
NIMCC	B	B	B	-	-	-	-	B	B	B
NMCC	B	B	B	-	-	-	-	B	B	B
PAMCC	B	B	B	-	-	-	-	O	B	B
PEMCC	B	B	B	-	-	-	-	B	B	B
SAMCC	B	B	B	-	-	-	-	B	B	B
SIMCC	B	B	B	-	-	-	-	B	B	B
SPMCC	B	B	B	-	-	-	-	B	B	B
TAMCC	B	B	B	-	-	-	-	B	B	B
THMCC	B	B	B	-	-	-	-	B	B	B
TRMCC	B	B	B	-	-	-	-	B	B	B
UKMCC	B	B	B	-	-	-	-	B	B	B
USMCC	B	B	B	-	-	-	-	O	B	B
VNMCC	B	B	B	-	-	-	-	B	B	B

Legend: O originate
 B both originate and receive
 TBD to be determined

 R receive
 - not implemented
 * under development

- END OF ANNEX I / B -

ANNEX I / C**STATUS OF SPACE SEGMENT**

The Cospas-Sarsat website provides the current status of Cospas-Sarsat Space Segment payloads.

Each satellite platform provider shall commission new satellite payloads according to the procedures documented in documents C/S T.004, C/S T.013 and C/S T.017. Additionally, after a payload is declared operational, and whenever there is a change in the configuration or status of a satellite payload, the Space Segment Providers shall notify all Ground Segment Operators and the Secretariat. The message format described in Figure I / C.1 shall be used to provide this notification.

Figure I / C.2 is a standard message for reporting satellite manoeuvres.

Figure I / C.3 shows a standard message for reporting reactivation of the SARP instrument.

Figure I / C.4 is a standard message for reporting a spacecraft anomaly.

*This document has been superseded
by a later version*

/12345 00000/3660/97 123 1234

/605/5030

/TO: ALL MCCS

FROM: <MCC ASSOCIATED WITH SATELLITE OR PAYLOAD PROVIDER>

SUBJECT: A) INITIAL OPERATIONAL CAPABILITY FOR <S/C> SAR PAYLOAD

B) DECLARATION OF OPERATION FOR <S/C> SAR PAYLOAD

C) CHANGE IN STATUS FOR <S/C> SAR PAYLOAD

D) DECOMMISSIONING OF <S/C> SAR PAYLOAD

DATA CONSIDERED OPERATIONAL IN COSPAS-SARSAT (WWW.COSPAS-SARSAT.INT)

(L/G/M) 406 SARR: A) OPERATIONAL, B) NOT OPERATIONAL OR C) NOT APPLICABLE
 (L) 406 SARP (LOCAL): A) OPERATIONAL OR B) NOT OPERATIONAL
 (L) 406 SARP (GLOBAL): A) OPERATIONAL OR B) NOT OPERATIONAL
 (L) PSEUDO MODE: A) OPERATIONAL, B) NOT OPERATIONAL OR C) NOT APPLICABLE

STATUS OF SAR PAYLOAD (WWW.COSPAS-SARSAT.INT)

(L/M) L-BAND DOWNLINK: A) NORMAL, B) DEGRADED, C) UNUSABLE OR D) NOT APPLICABLE
 (Ms) S-BAND DOWNLINK: A) NORMAL, B) DEGRADED OR C) UNUSABLE
 (L/G/M) 406 SARR: A) NORMAL, B) DEGRADED, C) UNUSABLE OR D) NOT APPLICABLE
 (L/G/M) 406 SARR GAIN CONTROL: A) AUTOMATIC, B) FIXED OR C) NOT APPLICABLE
 (L) 406 SARP (LOCAL): A) NORMAL, B) DEGRADED OR C) UNUSABLE
 (L) 406 SARP (GLOBAL): A) NORMAL, B) DEGRADED OR C) UNUSABLE
 (L) PSEUDO MODE: A) ENABLED, B) DISABLED OR C) NOT APPLICABLE
 (L/G/M) BANDWIDTH: A) 27 KHZ, B) 40 KHZ, C) 80 KHZ OR D) NOT APPLICABLE
 (G) POSITION:
 (G) DOWNLINK FREQUENCY/TYPE:
 (L) SAR INSTRUMENTS ACTIVE DURING SATELLITE MANOEUVRE: A) YES, B) NO OR C) NOT APPLICABLE

COMMENTS

(G/M) TEST RESULTS PER SPACECRAFT COMMISSIONING STANDARD

QQQQ

/LASSIT

/ENDMSG

Notes: (L) - Applies to LEOSAR only.

(G) - Applies to GEOSAR only.

(L/G) - Applies to both LEOSAR and GEOSAR.

(M) - Applies to MEOSAR only

(Ms) - Applies to MEOSAR S-band only

(G/M) - On declaration of Initial Operational Capability, GEOSAR and MEOSAR commissioning test results shall be reported per documents C/S T.013, Annex D and C/S T.017, section 5, respectively.

(L/G/M) - Applies to LEOSAR, GEOSAR and MEOSAR.

Figure I / C.1: Standard Message for Reporting Satellite Payload Status

/12345 00000/3660/05 123 1412
/605/5030
/TO: ALL MCCS
FROM: <MCC RESPONSIBLE FOR THE SATELLITE MANOEUVRE >
SUBJECT: MANOEUVRE OF SATELLITE <XNN>

STATUS OF MANOEUVRE: <SCHEDULED, EXECUTED OR CANCELLED>
TYPE OF MANOEUVRE: <IN PLANE, OUT OF PLANE OR BOTH>
SAR INSTRUMENTS ACTIVE DURING MANOEUVRE: <YES OR NO>

MANOEUVRE START TIME: <DD MON YEAR HHMM> UTC
MANOEUVRE END TIME: <DD MON YEAR HHMM> UTC
[REPEAT INFORMATION ABOUT MANOEUVRE START AND END TIME AS NEEDED]

TIME NEW ORBIT VECTORS ARE EXPECTED: <DD MON YEAR HHMM> UTC

MAXIMUM EXPECTED CHANGE IN SATELLITE POSITION DUE TO THE SATELLITE
MANOEUVRE: <XX> KM AFTER <YY> HOURS
MAXIMUM EXPECTED ERROR IN DOPPLER LOCATION: <XX> KM AFTER <YY> HOURS

THIS DOPPLER LOCATION ERROR INCLUDES A NOMINAL SYSTEM ERROR OF 5 KM.

COMMENTS - MCCS SHOULD <EXECUTE OR REFER TO> PROCEDURES ON SATELLITE
MANOEUVRES CONTAINED IN SECTION 3.6.5 OF C/S A.001.

QQQQ
/LASSIT
/ENDMSG

Figure I / C.2: Standard Message for Reporting Satellite Manoeuvres

/12345 00000/2270/12 222 1412
/605/2730

TO: ALL MCCS
FROM: FMCC
SUBJECT: REACTIVATION OF THE SARP INSTRUMENT ON [SXX]

THE SARP INSTRUMENT WAS REACTIVATED AT [DD MON YEAR HH:MM]
THE SARP RESUMED NORMAL OPERATIONS AT [DD MON YEAR HH:MM]
NEW SARP TCAL DATA WILL BE SENT AT [DD MON YEAR HH:MM]

WHEN NEW SARP TCAL DATA IS RECEIVED BY THE MCC FOR THIS SATELLITE,
FOLLOW THE PROCEDURE ON SARP REACTIVATION DESCRIBED IN C/S A.001
SECTION 3.6.6. SPECIFICALLY, THE GROUND SEGMENT PROVIDER SHALL:

- A) ENSURE THAT THE CALIBRATION TIME IN THE NEW SARP TCAL DATA IS TREATED AS VALID IN ITS MCC, WITHOUT REGARD TO THE PREVIOUS SARP TCAL DATA.
- B) ENSURE THAT THE NEW SARP TCAL DATA IS USED TO INITIALIZE THE SARP TCAL DATA IN ITS LEOLUTS, WITHOUT REGARD TO THE PREVIOUS SARP TCAL DATA.
- C) ENSURE THAT ALL DOPPLER SOLUTIONS GENERATED BY ITS LEOLUT(S) THAT CONTAIN SARP DATA FOR THIS SATELLITE ARE FILTERED UNTIL NEW SARP TCAL DATA IS LOADED INTO THE ASSOCIATED LEOLUT.

COMMENTS:

QQQQ
/LASSIT
/ENDMSG

Figure I / C.3: Standard Message for Reporting Reactivation of the SARP Instrument

[...]

/12345 00000/AAA0/12 222 1412

/605/BBB0

TO: ALL MCCS

FROM: <MCC ASSOCIATED WITH THE RELEVANT SPACE SEGMENT PROVIDER >

SUBJECT: SPACECRAFT ANOMALY FOR [XXX]

AN ANOMALY HAS OCCURRED FOR SATELLITE [XXX] AS DESCRIBED BELOW.
[DETAILS OF PROBLEM, INCLUDING START TIME, IF KNOWN]]

WHILE THE IMPACT AND MITIGATION OF THIS ANOMALY ARE BEING EVALUATED,
GROUND SEGMENT PROVIDERS SHOULD:

[...]*

THE NEXT UPDATE ON THIS ANOMALY IS PLANNED FOR: [DD MON YEAR HH:MM].

QQQQ
/LASSIT
/ENDMSG

Figure I / C.4: Standard Message for Reporting a Spacecraft Anomaly

* Message content may vary. For example, the message may include one or more of the following statements:

- a) EVALUATE THEIR GROUND SYSTEM IN RESPECT OF THIS ANOMALY AND CONSULT WITH THEIR LUT OR MCC VENDOR, AS APPROPRIATE.
- b) NOTIFY THEIR ASSOCIATED RCCS AND SPOCS THAT [SARR/SARP/YYY] ALERT DATA FROM THE SATELLITE MAY BE UNRELIABLE.
- c) FILTER [SARR/SARP/YYY] ALERT DATA FROM THE SATELLITE.

- END OF ANNEX I / C -

C/S A.001 ANNEXES

PART II:

OPERATIONAL PROCEDURES FOR COSPAS-SARSAT MCCs

ANNEX II / A**DATA DISTRIBUTION REGIONS AND INTER-MCC DATA EXCHANGE****II / A.1 INTRODUCTION**

This annex describes the inter-DDR arrangements for data exchange and includes the particular regional arrangements or agreements that affect MCCs within a DDR. It may be amended by the MCCs involved. However, other MCCs should be notified of any changes in the event that the changes impact MCCs outside the region. If so, agreement of the Joint Committee is needed prior to implementation.

These procedures and arrangements become effective for MCCs under development only after confirmation by the appropriate host MCC, that the MCC under development has achieved Initial Operational Capability (IOC).

II / A.2 DEFINITION OF DDR

A data distribution region (DDR) is a region comprising two or more MCC service areas. Cospas-Sarsat alert data and System information are exchanged between DDRs through an MCC in each DDR which is the single point of contact for that DDR. This MCC is identified as the nodal MCC of the DDR.

II / A.3 DATA EXCHANGE BETWEEN DDRS

The inter-nodal network diagram is provided as Figure II / A.1.

The nodes of the MCC communication network and the associated DDRs are identified as follows:

Australia:	AUMCC – South West Pacific DDR	AU
France:	FMCC - Central DDR	FR
Japan:	JAMCC – North West Pacific DDR	JA
Russia:	CMC - Eastern DDR	RU
Spain:	SPMCC - South Central DDR	SP
USA:	USMCC - Western DDR	US

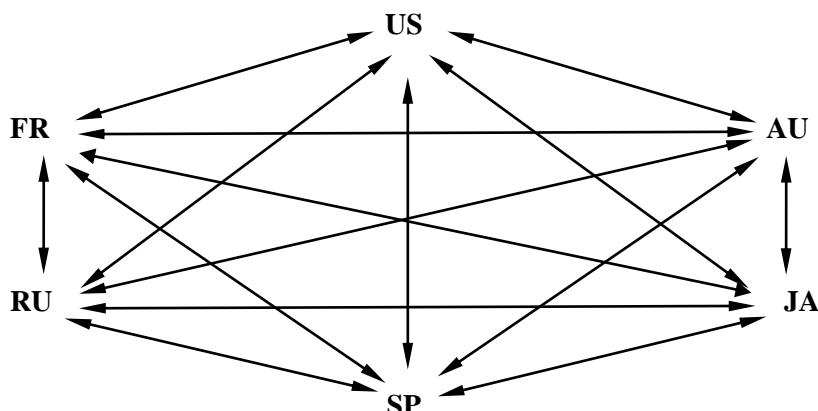


Figure II / A.1: Inter-Nodal Network Diagram

II / A.4 DATA EXCHANGE WITHIN DDRs

II / A.4.1 Western DDR

The USMCC, as a nodal MCC, has accepted responsibility for passing alert information in this region and for the filtering of global mode alert or NOCR messages. Specific SRRs are outlined in Annex I / C.

Data flow in Western DDR (ARMCC, BRMCC, CHMCC, CMCC, PEMCC, and USMCC) is described in Figure II / A.2.

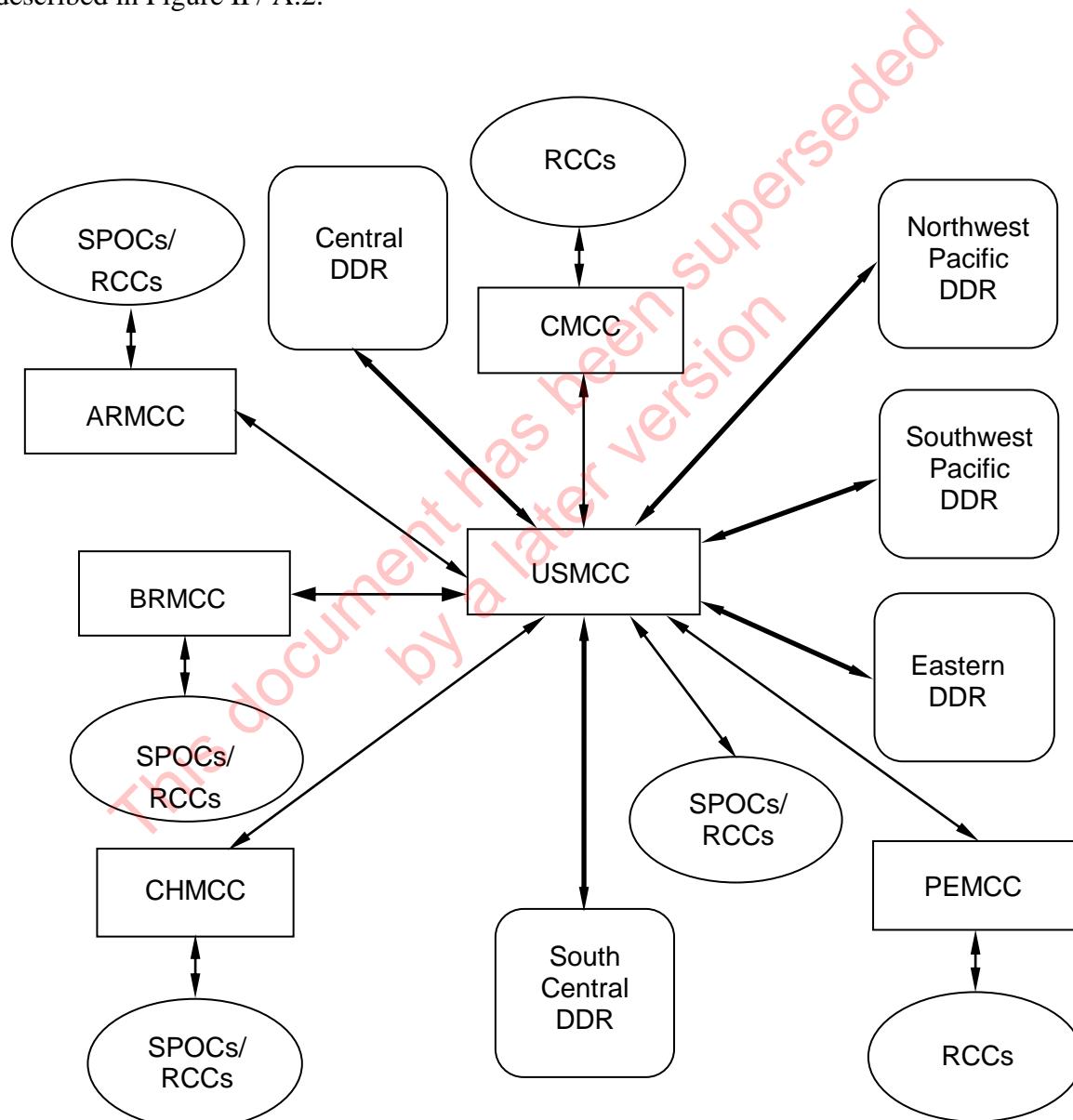


Figure II / A.2: Western DDR Network Diagram

II / A.4.2 Central DDR

Data flow in Central DDR (CYMCC*, FMCC, GRMCC, ITMCC, NMCC, TRMCC and UKMCC) is described in Figure II / A.3. Central DDR MCCs validate locations before forwarding them to the SAR organisations.

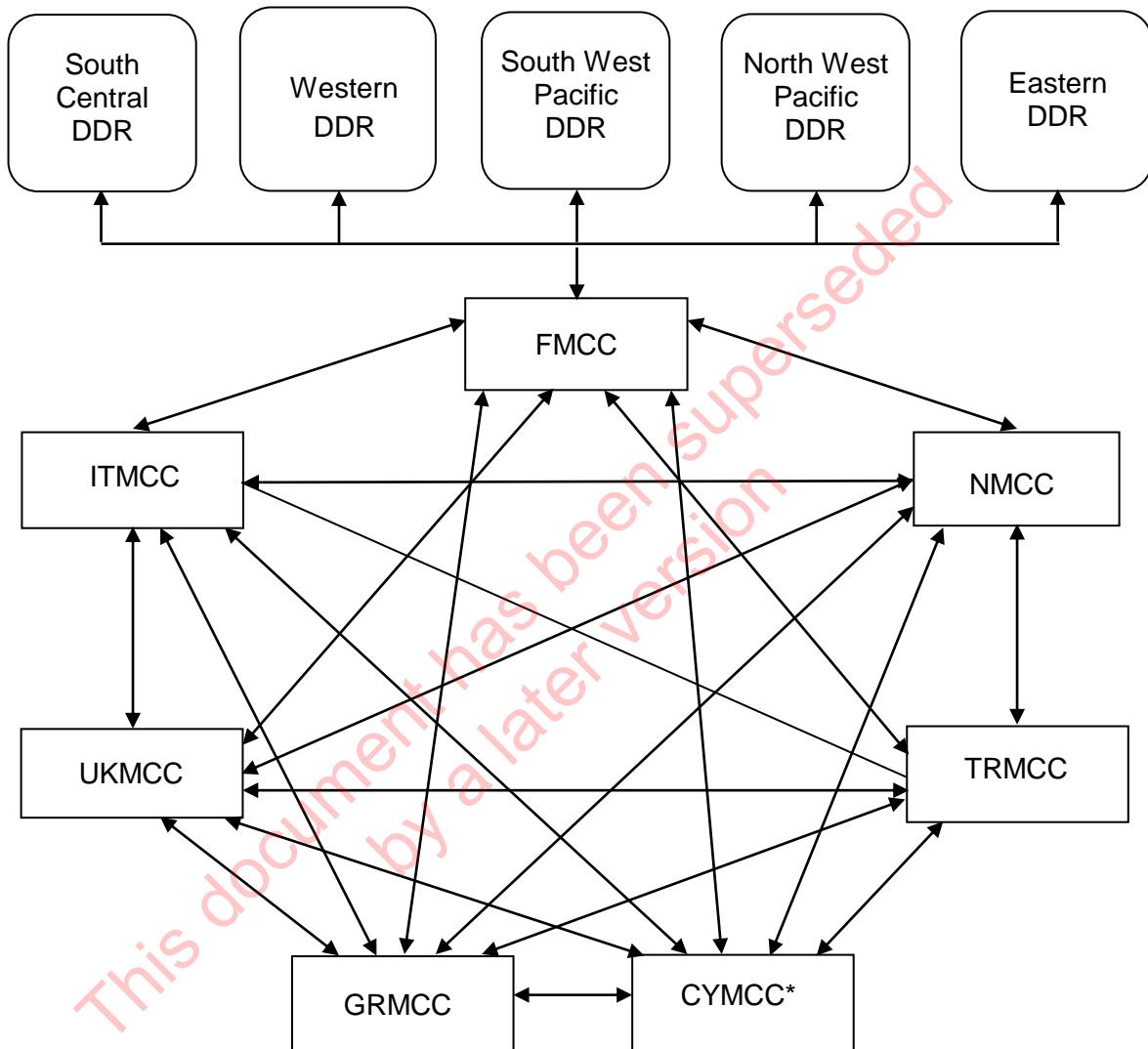


Figure II / A.3: Central DDR Network Diagram

Note: * Under development until commissioned once the MEOSAR system is at IOC.

II / A.4.3 Eastern DDR

The CMC has no formal regional agreements.

Data flow in Eastern DDR (CMC, INMCC and PAMCC) is described in Figure II / A.4.

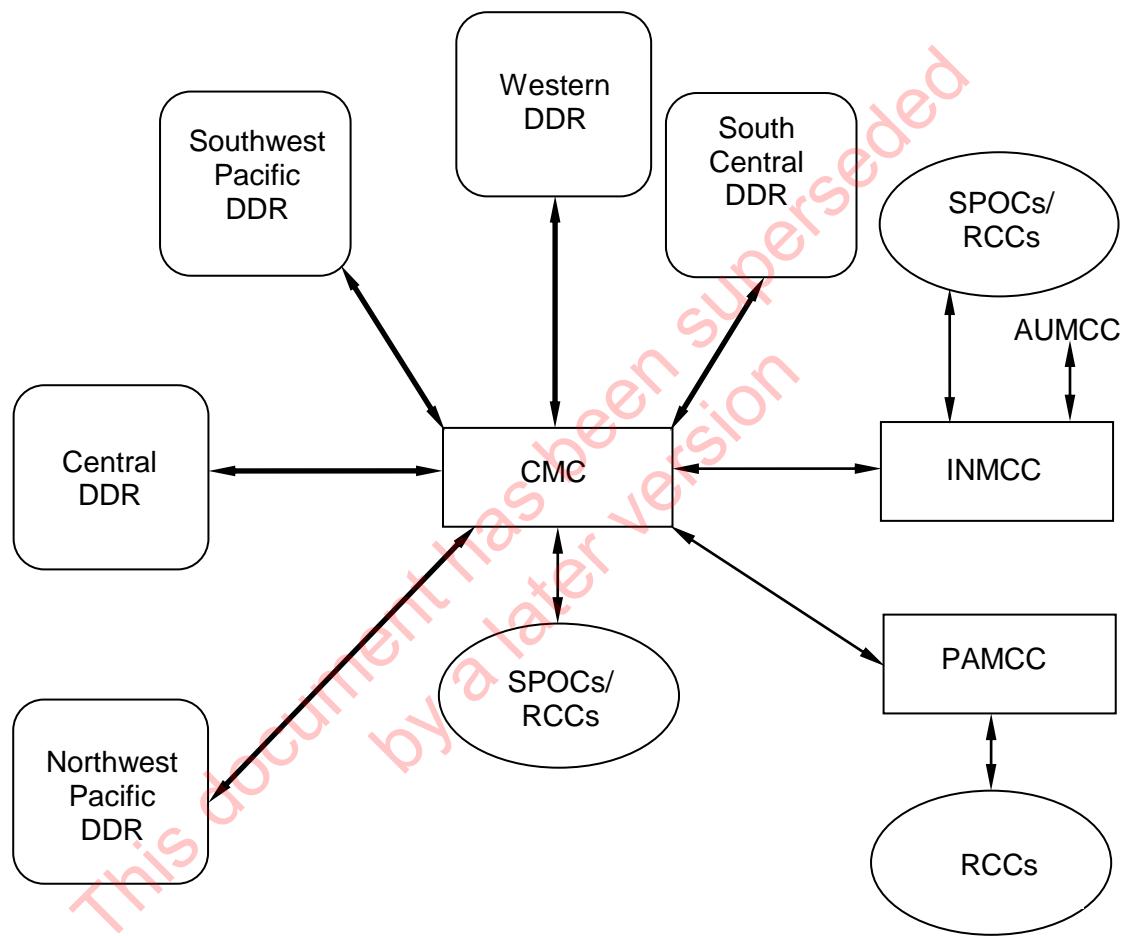


Figure II / A.4: Eastern DDR Network Diagram

II / A.4.4 South West Pacific DDR

Data flow in South West Pacific DDR (ASMCC, AUMCC, IDMCC, SIMCC and THMCC) is described in Figure II / A.5.

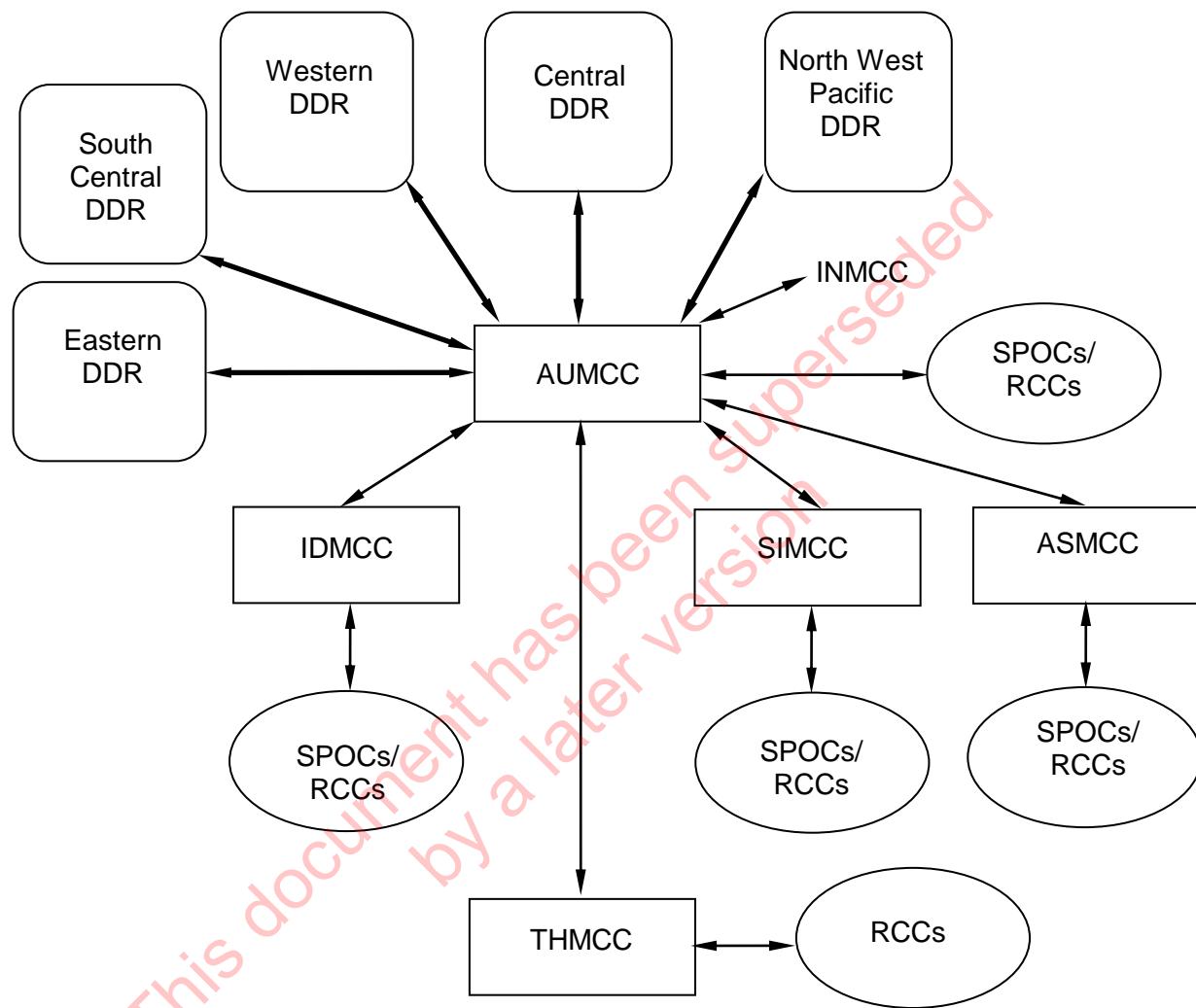


Figure II / A.5: South West Pacific DDR Network Diagram

II / A.4.5 North West Pacific DDR

Data flow in North West Pacific DDR (CNMCC, HKMCC, JAMCC, KOMCC, TAMCC and VNMCC) is described in Figure II / A.6.

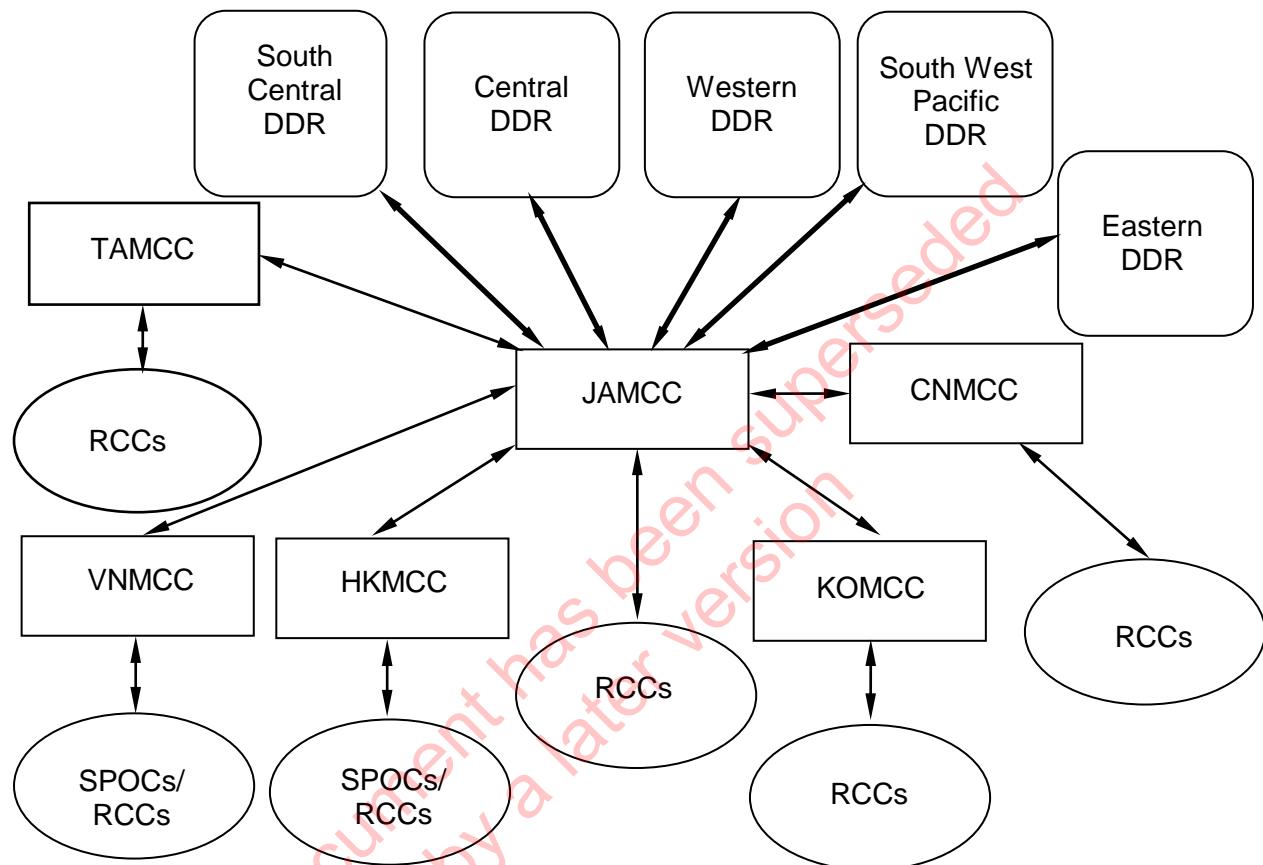


Figure II / A.6: North West Pacific DDR Network Diagram

II / A.4.6 South Central DDR

Data flow in South Central DDR (AEMCC, ALMCC, NIMCC, QAMCC*, SAMCC) and SPMCC) is described in Figure II / A.7.

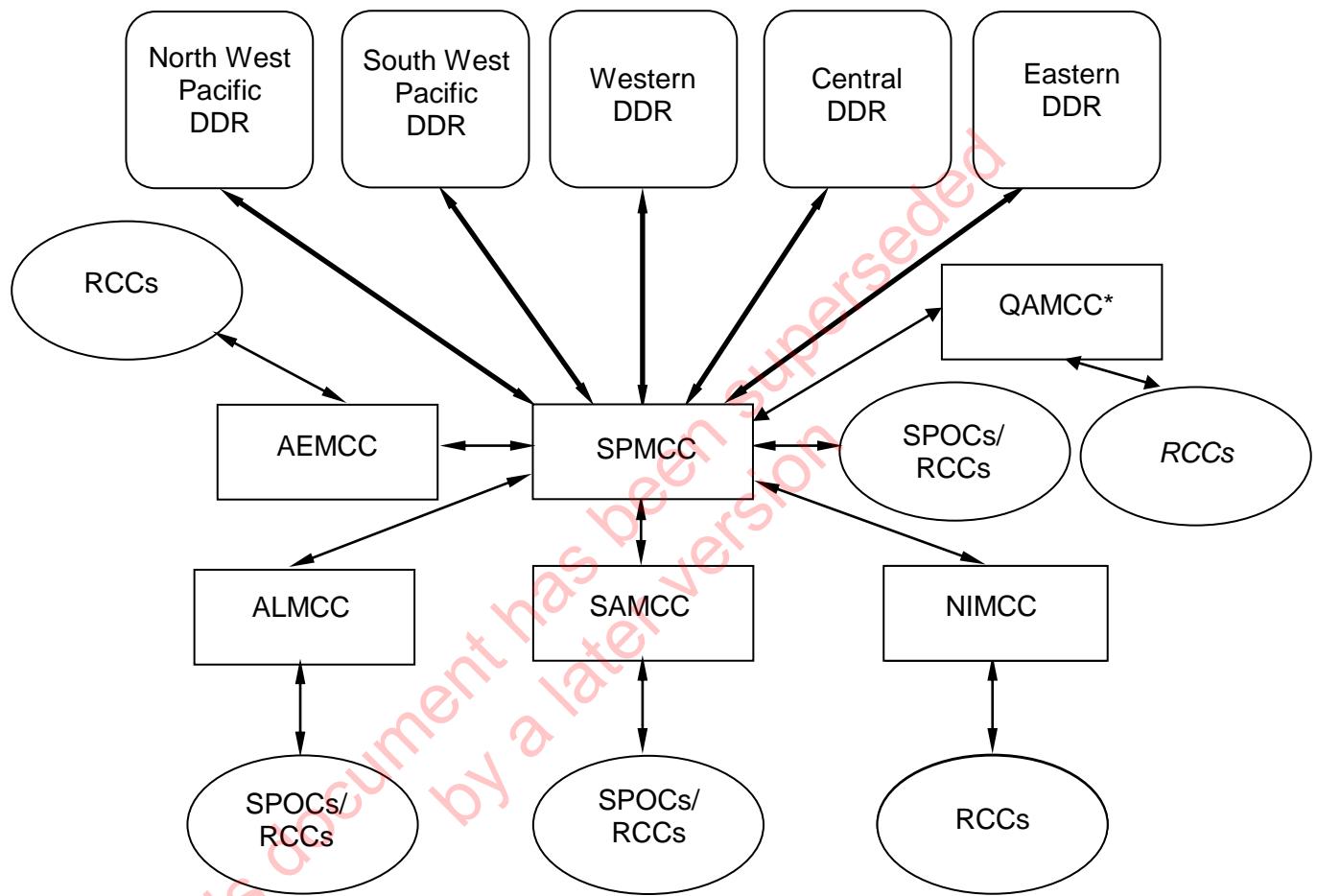


Figure II / A.7: South Central DDR Network Diagram

Note: * Under development.

II / A.5 INTER-MCC ROUTING OF ALERT DATA

The receiving MCC shall route alert data to the MCC in which service area the alert is located (i.e., the destination MCC) as described in Figure II / A.8.

II / A.6 INTER-MCC ROUTING OF SYSTEM INFORMATION

The routing of System information between MCCs is described in Figure II / A.9 “System Information Distribution”. MCCs shall route System information as described in Figure II / A.8.

*This document has been superseded
by a later version*

Receiving MCC:	AEMCC	ALMCC	ARMCC	ASMCC	AUMCC	BRMCC	CHMCC	CMC	CMCC	CNMCC	CYMCC**	FMCC	GRMCC	HKMCC	IDMCC	INMCC
<i>Destination MCC:</i>																
AEMCC	Nat.Pr.	SPMCC	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
ALMCC	SPMCC	Nat. Pr.	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
ARMCC	SPMCC	SPMCC	Nat. Pr.	AUMCC	USMCC	USMCC	USMCC	USMCC	USMCC	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
ASMCC	SPMCC	SPMCC	USMCC	Nat. Pr.	ASMCC	USMCC	USMCC	AUMCC	USMCC	JAMCC	FMCC	AUMCC	FMCC	JAMCC	AUMCC	CMC
AUMCC	SPMCC	SPMCC	USMCC	AUMCC	Nat. Pr.	USMCC	USMCC	AUMCC	USMCC	JAMCC	FMCC	AUMCC	FMCC	JAMCC	AUMCC	AUMCC
BRMCC	SPMCC	SPMCC	USMCC	AUMCC	USMCC	Nat. Pr.	USMCC	USMCC	USMCC	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
CHMCC	SPMCC	SPMCC	USMCC	AUMCC	USMCC	USMCC	Nat. Pr.	USMCC	USMCC	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
CMC	SPMCC	SPMCC	USMCC	AUMCC	CMC	USMCC	USMCC	Nat. Pr.	USMCC	JAMCC	FMCC	CMC	FMCC	JAMCC	AUMCC	CMC
CMCC	SPMCC	SPMCC	USMCC	AUMCC	USMCC	USMCC	USMCC	USMCC	Nat. Pr.	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
CNMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	Nat. Pr.	FMCC	JAMCC	FMCC	JAMCC	AUMCC	CMC
CYMCC**	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	Nat. Pr.	CYMCC	CYMCC	JAMCC	AUMCC	CMC
FMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	FMCC	Nat. Pr.	FMCC	JAMCC	AUMCC	CMC
GRMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	GRMCC	GRMCC	Nat. Pr.	JAMCC	AUMCC	CMC
HKMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	JAMCC	FMCC	JAMCC	FMCC	Nat. Pr.	AUMCC	CMC
IDMCC	SPMCC	SPMCC	USMCC	AUMCC	IDMCC	USMCC	USMCC	AUMCC	USMCC	JAMCC	FMCC	AUMCC	FMCC	JAMCC	Nat. Pr.	CMC
INMCC	SPMCC	SPMCC	USMCC	AUMCC	INMCC	USMCC	USMCC	INMCC	USMCC	JAMCC	FMCC	CMC	FMCC	JAMCC	AUMCC	Nat.Pr.
ITMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	ITMCC	ITMCC	JAMCC	AUMCC	CMC	
JAMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	JAMCC	FMCC	JAMCC	FMCC	JAMCC	AUMCC	CMC
KOMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	JAMCC	FMCC	JAMCC	FMCC	JAMCC	AUMCC	CMC
NIMCC	SPMCC	SPMCC	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
NMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	NMCC	NMCC	JAMCC	AUMCC	CMC	
PAMCC	SPMCC	SPMCC	USMCC	AUMCC	CMC	USMCC	USMCC	PAMCC	USMCC	JAMCC	FMCC	CMC	FMCC	JAMCC	AUMCC	CMC
PEMCC	SPMCC	SPMCC	USMCC	AUMCC	USMCC	USMCC	USMCC	USMCC	USMCC	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
QAMCC*	SPMCC	SPMCC	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
SAMCC	SPMCC	SPMCC	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
SIMCC	SPMCC	SPMCC	USMCC	AUMCC	SIMCC	USMCC	USMCC	AUMCC	USMCC	JAMCC	FMCC	AUMCC	FMCC	JAMCC	AUMCC	CMC
SPMCC	SPMCC	SPMCC	USMCC	AUMCC	SPMCC	USMCC	USMCC	SPMCC	USMCC	JAMCC	FMCC	SPMCC	FMCC	JAMCC	AUMCC	CMC
TAMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	JAMCC	FMCC	JAMCC	FMCC	JAMCC	AUMCC	CMC
THMCC	SPMCC	SPMCC	USMCC	AUMCC	THMCC	USMCC	USMCC	AUMCC	USMCC	JAMCC	FMCC	AUMCC	FMCC	JAMCC	AUMCC	CMC
TRMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	TRMCC	TRMCC	JAMCC	AUMCC	CMC	
UKMCC	SPMCC	SPMCC	USMCC	AUMCC	FMCC	USMCC	USMCC	FMCC	USMCC	JAMCC	UKMCC	UKMCC	JAMCC	AUMCC	CMC	
USMCC	SPMCC	SPMCC	USMCC	AUMCC	USMCC	USMCC	USMCC	USMCC	USMCC	JAMCC	FMCC	USMCC	FMCC	JAMCC	AUMCC	CMC
VNMCC	SPMCC	SPMCC	USMCC	AUMCC	JAMCC	USMCC	USMCC	JAMCC	USMCC	JAMCC	FMCC	JAMCC	FMCC	JAMCC	AUMCC	CMC

Figure II / A.8: MCC Data Routing Matrix (1/2)

Notes: Nat.Pr. - National Procedures.
 * - Under development.

** - Under development until commissioned once the MEOSAR system is at IOC.

Receiving MCC:	ITMCC	JAMCC	KOMCC	NIMCC	NMCC	PAMCC	PEMCC	QAMCC*	SAMCC	SIMCC	SPMCC	TAMCC	THMCC	TRMCC	UKMCC	USMCC	VNMCC
Destination MCC	This document is a draft and is not yet finalised.																
AEMCC	FMCC	SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	AEMCC	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
ALMCC	FMCC	SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	ALMCC	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
ARMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	ARMCC	JAMCC
ASMCC	FMCC	AUMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	AUMCC	JAMCC	AUMCC	FMCC	FMCC	AUMCC	JAMCC
AUMCC	FMCC	AUMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	AUMCC	JAMCC	AUMCC	FMCC	FMCC	AUMCC	JAMCC
BRMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	BRMCC	JAMCC
CHMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	CHMCC	JAMCC
CMC	FMCC	CMC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	CMC	JAMCC	AUMCC	FMCC	FMCC	CMC	JAMCC
CMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	CMCC	JAMCC
CNMCC	FMCC	CNMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	JAMCC	AUMCC	FMCC	FMCC	JAMCC	JAMCC
CYMCC**	ITMCC	FMCC	JAMCC	SPMCC	CYMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	CYMCC	CYMCC	FMCC	JAMCC
FMCC	FMCC	FMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	FMCC	FMCC	FMCC	JAMCC
GRMCC	GRMCC	FMCC	JAMCC	SPMCC	GRMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	GRMCC	GRMCC	FMCC	JAMCC
HKMCC	FMCC	HKMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	JAMCC	AUMCC	FMCC	FMCC	JAMCC	JAMCC
IDMCC	FMCC	AUMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	AUMCC	JAMCC	AUMCC	FMCC	FMCC	AUMCC	JAMCC
INMCC	FMCC	CMC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	CMC	JAMCC	AUMCC	FMCC	FMCC	CMC	JAMCC
ITMCC	Nat. Pr.	FMCC	JAMCC	SPMCC	ITMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	ITMCC	ITMCC	FMCC	JAMCC
JAMCC	FMCC	Nat. Pr.	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	JAMCC	AUMCC	FMCC	FMCC	JAMCC	JAMCC
KOMCC	FMCC	KOMCC	Nat. Pr.	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	JAMCC	AUMCC	FMCC	FMCC	JAMCC	JAMCC
NIMCC	FMCC	SPMCC	JAMCC	Nat. Pr.	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	NIMCC	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
NMCC	NMCC	FMCC	JAMCC	SPMCC	Nat. Pr.	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	NMCC	NMCC	FMCC	JAMCC
PAMCC	FMCC	CMC	JAMCC	SPMCC	FMCC	Nat. Pr.	USMCC	SPMCC	SPMCC	AUMCC	CMC	JAMCC	AUMCC	FMCC	FMCC	CMC	JAMCC
PEMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	Nat. Pr.	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	PEMCC	JAMCC
QAMCC*	FMCC	SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	Nat. Pr.	SPMCC	AUMCC	NIMCC	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
SAMCC	FMCC	SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	Nat. Pr.	AUMCC	SAMCC	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
SIMCC	FMCC	AUMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	Nat. Pr.	AUMCC	JAMCC	AUMCC	FMCC	FMCC	AUMCC	JAMCC
SPMCC	FMCC	SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	Nat. Pr.	JAMCC	AUMCC	FMCC	FMCC	SPMCC	JAMCC
TAMCC	FMCC	TAMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	Nat. Pr.	AUMCC	FMCC	FMCC	JAMCC	JAMCC
THMCC	FMCC	AUMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	AUMCC	JAMCC	Nat. Pr.	FMCC	FMCC	AUMCC	JAMCC
TRMCC	TRMCC	FMCC	JAMCC	SPMCC	TRMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	Nat. Pr.	TRMCC	FMCC	JAMCC
UKMCC	UKMCC	FMCC	JAMCC	SPMCC	UKMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	FMCC	JAMCC	AUMCC	UKMCC	Nat. Pr.	FMCC	JAMCC
USMCC	FMCC	USMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	USMCC	JAMCC	AUMCC	FMCC	FMCC	Nat. Pr.	JAMCC
VNMCC	FMCC	VNMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	SPMCC	AUMCC	JAMCC	JAMCC	AUMCC	FMCC	FMCC	JAMCC	Nat. Pr.

Figure II / A.8: MCC Data Routing Matrix (2/2)

Notes: Nat.Pr. - National Procedures. * - Under development. ** - Under development until commissioned once the MEOSAR system is at IOC.

Transmitting MCC:	AEMCC	ALMCC	ARMCC	ASMCC	AUMCC	BRMCC	CHMCC	CMC	CMCC	CNMCC	CYMCC*	FMCC	GRMCC	HKMCC	IDMCC	INMCC	
System Information:																	
Sarsat, GPS/DASS Spacecraft & Ephemeris Data**	LUTs	LUTs	LUTs	ASMCC IDMCC SIMCC THMCC LUTs	LUTs	LUTs	INMCC PAMCC LUTs	LUTs	LUTs	LUTs	CYMCC* ITMCC GRMCC NMCC TRMCC UKMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	
Cospas, Glonass Spacecraft & Ephemeris Data**	LUTs	LUTs	LUTs	ASMCC IDMCC SIMCC THMCC LUTs	LUTs	LUTs	AUMCC FMCC INMCC JAMCC PAMCC SPMCC USMCC LUTs	LUTs	LUTs	LUTs	CYMCC* ITMCC GRMCC NMCC TRMCC UKMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	
Sarsat SARP Time Calibration**, Galileo Spacecraft & Ephemeris Data	LUTs	LUTs	LUTs	ASMCC IDMCC SIMCC THMCC LUTs	LUTs	LUTs	INMCC PAMCC LUTs	LUTs	LUTs	LUTs	AUMCC CMC CYMCC* GRMCC ITMCC JAMCC NMCC SPMCC TRMCC UKMCC USMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	
SARP Commands																	
SARP Cmd Response & Housekeeping																	
SARR Commands																	
SARR Cmd Response & Housekeeping																	
System Status	SPMCC	SPMCC	USMCC	AUMCC	ASMCC CMC FMCC JAMCC IDMCC SIMCC SPMCC THMCC USMCC	USMCC	USMCC	AUMCC FMCC INMCC JAMCC PAMCC SPMCC USMCC	USMCC	JAMCC	FMCC	AUMCC CMC CYMCC* GRMCC ITMCC JAMCC NMCC SPMCC TRMCC UKMCC USMCC	FMCC	JAMCC	AUMCC	CMC	
406 MHz SARR Frequency Calibration																	

Figure II / A.9: System Information Distribution (1/2)

Notes: * Under development until commissioned once the MEOSAR system is at IOC.

** - Sarsat and Cospas ephemeris data and Sarsat SARP Time Calibration are distributed to LEOLUTs.

Transmitting MCC:	ITMCC	JAMCC	KOMCC	NIMCC	NMCC	PAMCC	PEMCC	SAMCC	QAMCC*	SIMCC	SPMCC	TAMCC	THMCC	TRMCC	UKMCC	USMCC	VNMCC	
System Information:																		
Sarsat, GPS/DASS Spacecraft & Ephemeris Data**	LUTs	CNMCC HKMCC KOMCC TAMCC VNMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	AEMCC ALMCC NIMCC QAMCC* SAMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	ARMCC AUMCC BRMCC CHMCC CMC CMCC FMCC JAMCC SPMCC PEMCC LUTs	LUTs		
Cospas, Glonass Spacecraft & Ephemeris Data**	LUTs	CNMCC HKMCC KOMCC TAMCC VNMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	AEMCC ALMCC NIMCC QAMCC* SAMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	ARMCC AUMCC BRMCC CHMCC CMCC PEMCC LUTs	LUTs		
Sarsat SARP Time Calibration**, Galileo Spacecraft & Ephemeris Data	LUTs	CNMCC HKMCC KOMCC TAMCC VNMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	AEMCC ALMCC NIMCC QAMCC* SAMCC LUTs	LUTs	LUTs	LUTs	LUTs	LUTs	ARMCC BRMCC CHMCC CMCC PEMCC	LUTs		
SARP Commands																NOAA		
SARP Cmd Response & Housekeeping																FMCC		
SARR Commands																NOAA		
SARR Cmd Response & Housekeeping																CMCC		
System Status	FMCC	AUMCC CNMCC CMC FMCC HKMCC KOMCC TAMCC USMCC VNMCC SPMCC	JAMCC	SPMCC	FMCC	CMC	USMCC	SPMCC	AUMCC ALMCC AUMCC CMC FMCC JAMCC NIMCC QAMCC* SAMCC USMCC	AEMCC ALMCC AUMCC CMC FMCC JAMCC NIMCC QAMCC* SAMCC USMCC	JAMCC	AUMCC	FMCC	FMCC	FMCC	ARMCC AUMCC BRMCC CHMCC CMC CMCC FMCC JAMCC PEMCC SPMCC	JAMCC	
406 MHz SARR Frequency Calibration																		

Figure II / A.9: System Information Distribution (2/2)

Notes: * - Under development.

** - Sarsat and Cospas ephemeris data and Sarsat SARP Time Calibration are distributed to LEOLUTs.

ANNEX II / B

DETAILED IMPLEMENTATION OF DATA DISTRIBUTION PROCEDURES

The following sections provide detailed implementation information on selected data distribution procedures and requirements. These procedures are agreed by the Joint Committee and apply to all MCCs unless otherwise stated. A reference to the contents of this Annex follows:

II / B.1	Alert Message Validation (Filtering Anomalous Data)	II / B-1
II / B.2	Position Matching	II / B-7
II / B.3	Position Confirmation.....	II / B-8
II / B.4	Procedures to Determine Better Quality LEOSAR Alert Data for Same Beacon Event Position Conflicts.....	II / B-9
II / B.5	Detailed Procedures for Alert Data Distribution.....	II / B-11
II / B.6	Distribution of Beacon Registration Information	II / B-24
II / B.7	NOCR Procedures.....	II / B-25
II / B.8	Distribution of 406 MHz Ship Security Alerts	II / B-27
II / B.9	Processing and Distribution of 406 MHz Interference Data.....	II / B-30
II / B.10	Return Link Service (RLS) Procedures.....	II / B-30

II / B.1 ALERT MESSAGE VALIDATION (FILTERING ANOMALOUS DATA)

Alert message validation should be performed at each MCC to prevent incorrect data from being transmitted to other MCCs and eventually to RCCs and SPOCs. The flowchart (Figure II / B.1) is provided to illustrate data validation procedures for ease of comprehension, given the complexity of the validation process. The flowchart is intended to clarify data validation procedures and incorporates all the validation requirements of Annex II / B. It is not intended to replace the detailed requirements provided in the remainder of Annex II / B. The associated alert message validation table (Table II / B.1) follows the logic of the flowchart and includes the same decision diamonds.

II / B.1.1 Validation of Alert Message Format and Content

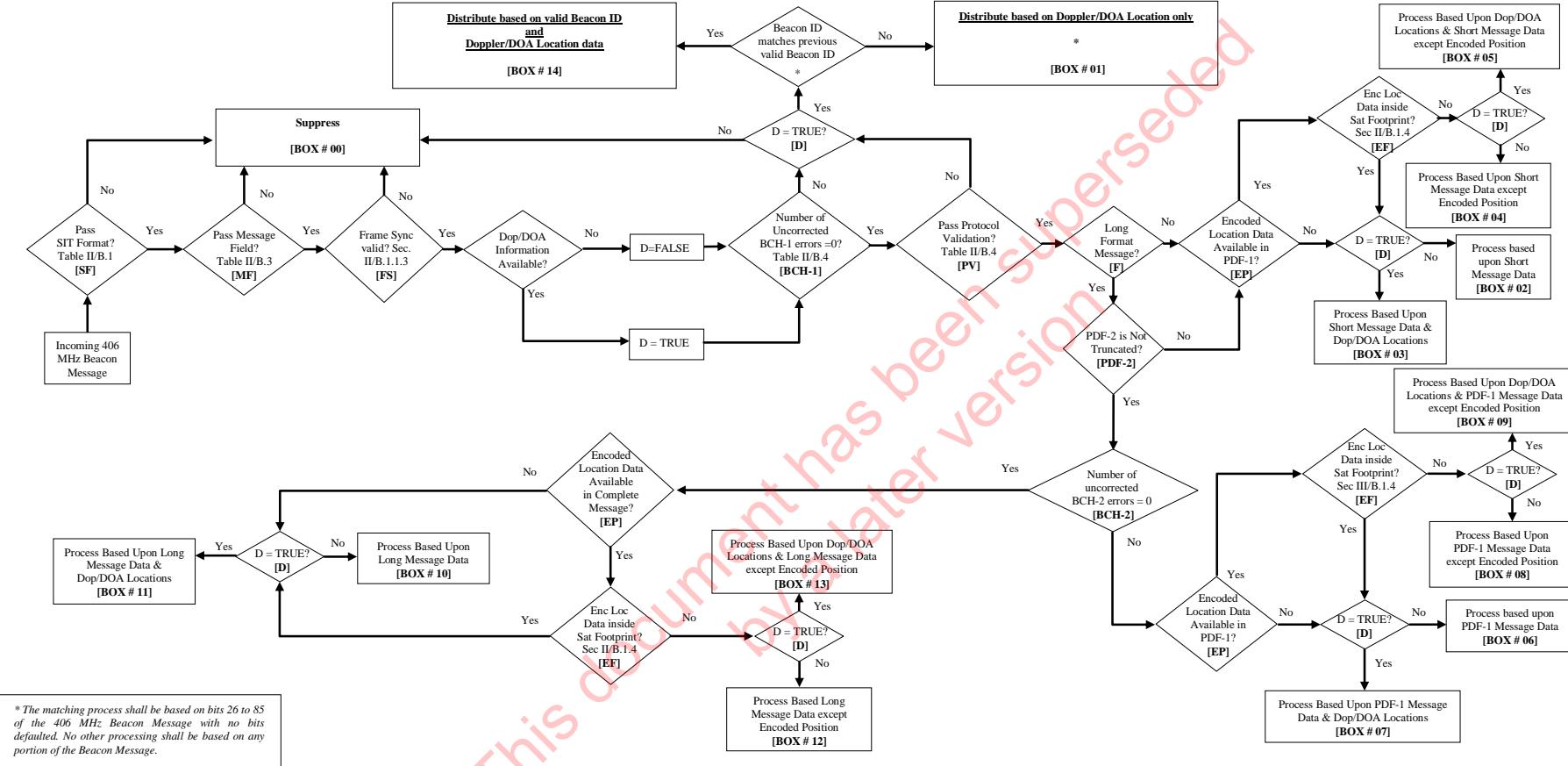
Each MCC should validate all incoming beacon alert messages based on the format and content of the SIT message.

II / B.1.1.1 Validation of SIT Message Format

The format of a SIT message should be deemed corrupt if:

- any message field is missing;
- the size of any message field is incorrect;
- a numeric message field contains non-numeric character(s); or
- a space or decimal point is incorrectly placed.

The resultant MCC action is defined by Table II / B.1.



* The matching process shall be based on bits 26 to 85 of the 406 MHz Beacon Message with no bits defaulted. No other processing shall be based on any portion of the Beacon Message.

Figure II / B.1: 406 MHz Alert Message Validation Flowchart

Note: «Dop/DOA» denotes Doppler/DOA. MEOSAR single packet alerts are processed per Section II/B.1.4.

SIT Format		Action	
Corrupt		Suppress	
Not Corrupt		See Table II / B.2	

Table II / B.1: MCC Action Based on SIT Format

	1	2	3	4	5	6	7	8	9	10	11	12	
	SF	MF	FS	BCH-1	PV	PrVal	F	PDF-2	BCH-2	EP	EF	D	BOX
1	0												00
2	1	0											00
3	1	1	0										00
4	1	1	1	0								0	00
5	1	1	1	0		0						1	01
6	1	1	1	0		1						1	14
7	1	1	1	1	0							0	00
8	1	1	1	1	0	0						1	01
9	1	1	1	1	0	1						1	14
10	1	1	1	1	1		0			0		0	02
11	1	1	1	1	1		0			0		1	03
12	1	1	1	1	1		0			1	0	0	04
13	1	1	1	1	1		0			1	0	1	05
14	1	1	1	1	1		0			1	1	0	02
15	1	1	1	1	1		0			1	1	1	03
16	1	1	1	1	1		1	0		0		0	02
17	1	1	1	1	1		1	0		0		1	03
18	1	1	1	1	1		1	0		1	0	0	04
19	1	1	1	1	1		1	0		1	0	1	05
20	1	1	1	1	1		1	0		1	1	0	02
21	1	1	1	1	1		1	0		1	1	1	03
22	1	1	1	1	1		1	1	0	0		0	06
23	1	1	1	1	1		1	1	0	0		1	07
24	1	1	1	1	1		1	1	0	1	0	0	08
25	1	1	1	1	1		1	1	0	1	0	1	09
26	1	1	1	1	1		1	1	0	1	1	0	06
27	1	1	1	1	1		1	1	0	1	1	1	07
28	1	1	1	1	1		1	1	1	0		0	10
29	1	1	1	1	1		1	1	1	0		1	11
30	1	1	1	1	1		1	1	1	1	0	0	12
31	1	1	1	1	1		1	1	1	1	0	1	13
32	1	1	1	1	1		1	1	1	1	1	0	10
33	1	1	1	1	1		1	1	1	1	1	1	11

Table II / B.2: 406 MHz Alert Message Validation**Legend – Flowchart abbreviation equivalence:**

SF: Equivalent to diamond: <"Pass SIT Format? Table II/B.1">: (0= No / 1=Yes)

MF: Equivalent to diamond: <"Pass Message Field? Table II/B.2">: (0=No / 1=Yes)

FS: Equivalent to diamond: <"Frame Sync valid? Sec II/B.1.1.3">: (0=No / 1=Yes)

BCH-1: Equivalent to diamond <"Number of Uncorrected BCH-1 errors=0? Table II/B.3">: (0=No /1=Yes)

PV: Protocol Validation (0=Fail / 1=Pass)

PrVal:	Equivalent to diamond: <"Beacon ID matches previous valid beacon ID">: (0=No / 1=Yes)
F:	Format (0=Short / 1=Long)
PDF-2:	Equivalent to diamond <PDF-2 is Not Truncated?>: (0=No / 1=Yes)
BCH-2:	Equivalent to diamond <Number of uncorrected BCH-2 errors=0?>: (0=No / 1=Yes)
EP:	Encoded Position (0=No / 1=Yes)
EF:	Encoded Location in Footprint (0=No / 1=Yes).
D:	Doppler/DOA Locations <i>Used</i> . Equivalent to Diamond <D=TRUE?>: (0 =No / 1=Yes). Yes for Doppler/DOA location.

Note: If a test is irrelevant in a particular context (e.g. the BCH-2 test for Short Format Messages [F=0]) then the cell in the table is shaded.

II / B.1.1.2 Validation of SIT Message Field Content

Some message fields are essential to MCC alert processing. MCCs shall validate SIT message fields against allowable values as specified in Table II / B.3.

Message Field	Data Contents (According to C/S A.002, Table B.1)	
	In Range	Out of Range
2, 4, 6, 8, 10, 11, 12, 13, 14, 14a, 14b, 21, 25, 26, 27, 31 and 83	Process	Suppress
Other SIT Fields	Process	Process

Table II / B.3: MCC Action Based on Message Field Content

Alert messages shall not be suppressed based on out-of-range values unless the message field is contained in the above list.

II / B.1.1.3 406 MHz Beacon Message Validation

Normal mode beacon messages have a perfect match of bits 16 to 24 with the 9-bit frame synchronization pattern described in document C/S T.001 (beacon specification). If bits 16 to 24 of the beacon message (as contained in message field 77) do not perfectly match the 9-bit frame synchronization pattern (000101111), then the MCC shall suppress the associated MEOSAR alert.

In addition to the above validation, each MCC should perform a BCH check of all incoming 406 MHz alert messages from MCCs and LUTs to ensure that the 406 MHz beacon message (message field 23) is valid.

In addition, when the first protected field has no uncorrected BCH errors, each MCC should compare the beacon message contents against a known protocol specification. Specifically, the following items in the protected field(s) shall be validated against document C/S T.001:

- country code,
- user protocol,
- Baudot characters,
- supplementary data field,
- binary coded decimal fields,

- encoded latitude and longitude.

A 406 MHz beacon alert message fails when one or more of the conditions in Table II/ B.4 below are met.

Item to Check	Bits	Fail if:
Country Code Not Allocated	27 - 36	Decimal Value < 200 or > 780 or not allocated between 200 and 780
User Protocol	37 - 39	Bit 26 = 1 and Bits 37 - 39 = 101
Serial User Protocol	40 - 42	Bit 26 = 1 and Bits 40 - 42 = 101 or 111
Short Format Location Protocol	25 - 26	Bit 25 = 0 and Bit 26 = 0
Standard Location Ship Security Protocol	61 - 64	Bit 25 = 1 and Bit 26 = 0 and Bits 37 - 40 = 1100 and Bits 61 - 64 ≠ 0000
Maritime User or Radio Call Sign	82 - 83	Bit 26 = 1 and Bits 37 - 39 = 010 or 110 and Bits 82 - 83 are non-zero
Unallocated Location Protocols	37 - 40	Bit 26 = 0 and Bits 37 - 40 = 0000, 0001 or 1001
Modified Baudot Code	Varies	Unassigned Baudot Character
Binary Coded Decimal	Varies	Decimal Value for Four Bit Group > 10
Encoded Latitude and Longitude	Varies	Encoded Latitude > 90 or Encoded Longitude > 180
Supplementary Data (Standard Location Protocols)	107 - 110	Bit 26 = 0 and Bits 37 - 40 = 0010, 0011, 0100, 0101, 0110, 0111 1110, and Bits 107 - 110 ≠ 1101
Supplementary Data (Standard Location Ship Security Protocol)	107 - 110	Bit 25 = 1 and Bit 26 = 0 and Bits 37 - 40 = 1100, and Bits 107 - 110 ≠ 1101
Supplementary Data (National Location Protocol, Long)	107 - 109	Bit 25 = 1 and Bit 26 = 0, and Bits 37 - 40 = 1000, 1010, 1011 or 1111, and Bits 107 - 109 ≠ 110

Table II / B.4: Protocol Validation for 406 MHz Alert Messages

If the first protected field (bits 25 - 106) contains any uncorrected BCH errors or the 406 MHz beacon fails any condition in Table II / B.4, then the MCC shall:

- match for the “same beacon ID” based on bits 26 - 85 of the 406 MHz Beacon Message with no bits defaulted;
- in case of successful match with a previous alert having a valid 406 MHz Beacon Message, distribute using the valid 406 MHz Beacon Message (per items d and e below);
- perform no other processing based on any portion of the 406 MHz Beacon Message;
- distribute the alert based on Doppler/DOA position only; and

- e) not distribute the data if there is no Doppler/DOA position.

If the second protected field (bits 107 - 144) has uncorrected BCH errors, then no processing shall be based on any portion of this field, except for the Supplementary Data Bits as defined in Table II / B.4.

If the second protected field has no uncorrected BCH errors and a component value of the encoded position (i.e., minutes or seconds) in the second protected field for a standard or national location protocol contains an out of range value (per document C/S T.001), then the encoded position information in the second protected field shall not be processed.

II / B.1.1.4 Additional Validation

MCCs may perform additional validation to meet national requirements, however, additional validation shall not affect the distribution of data to other MCCs.

II / B.1.2 Doppler/DOA Position Footprint Validation

Each MCC shall implement the “Algorithm to Determine if Computed Position is Inside Satellite Footprint”, as specified in document C/S A.002 to determine if:

- a) the Doppler positions are inside the satellite footprint at the time of detection; and
- b) the DOA position is inside the satellite footprints at the time of detection.

If one of the LEOSAR Doppler positions or the DOA position is conclusively outside the footprint then this failure shall be flagged in alert messages sent by the MCC, as specified in document C/S A.002.

II / B.1.3 Encoded Position Footprint Validation

Each MCC shall implement the “Algorithm to Determine if Computed Position is Inside Satellite Footprint” as specified in document C/S A.002 to determine if the encoded position is inside the satellite footprint(s) at the time of detection (MF#14 or MF#14a per document C/S A.002). If the encoded position is conclusively outside the footprint then no processing shall be based on the encoded position.

II / B.1.4 Single Packet MEOSAR Alerts¹

If a MEOSAR alert is from a single packet (per Message Field 88 in document C/S A.002) and no previous alert was generated for the alert site (beacon activation), then the MCC shall not distribute the MEOSAR alert to SPOCs or to LEOSAR/GEOSAR only capable MCCs. Single packet MEOSAR alerts shall be

¹ The filtering of single packet MEOSAR alerts is a temporary mitigation measure to address the high number of suspect alerts being delivered by MEOLUTs. It is expected that MEOLUT manufacturers will resolve this issue before the end of the MEOSAR EOC phase.

included in an alert site regardless of whether they are distributed, so that they are used in subsequent processing for the beacon activation.

II / B.2 POSITION MATCHING

Position matching is the comparison of the computed distance between two beacon positions and a set distance criterion. It is used to decide if two positions should be considered operationally as a unique beacon position or as separate beacon positions. The matching process can include other technical parameters.

Matching criteria are necessary to determine if two sets of independent position data should be regarded as corresponding to the same beacon position. Such matching criteria are used in the ambiguity resolution process to determine whether two Doppler positions from two independent beacon events, or an encoded position and a Doppler position, are sufficiently close to determine which Doppler position is the “true” position and which is the image or incorrect position(s). Matching criteria are also used to decide if a separate alert message should be transmitted for a beacon when a new position is at a distance from any previously received position greater than the distance separation defined by the matching criteria.

The points listed below concerning the matching of positions apply to the matching criteria distance to be used by MCCs:

- a) the Doppler to Doppler distance match criterion shall be 20 kilometres for position confirmation and position conflict;
- b) the Doppler to encoded distance match criterion shall be 20 kilometres for position confirmation and position conflict;
- c) the encoded to encoded distance match criterion shall be 3 kilometres for position conflict;
- d) the DOA to DOA distance match criterion shall be 20 kilometres for position confirmation and position conflict;
- e) the DOA to encoded distance match criterion shall be 20 kilometres for position confirmation and position conflict;
- f) the DOA to Doppler distance match criterion shall be 20 kilometres for position confirmation and position conflict;
- g) each of the above distance match criteria shall be independently configurable;
- h) in the match process, the “best” match shall be used to confirm position when multiple candidate positions meet the match criterion; however
- i) if both pairs of Doppler positions meet the match criterion prior to position confirmation for different satellite passes, this is deemed an Unresolved Doppler Position Match (see Fig. II / B.2) and:

- (i) position shall not be confirmed from either pair of Doppler positions; and
- (ii) other pairs of positions shall remain eligible to resolve ambiguity, even if the “best” distance match was between ineligible Doppler positions; and
- j) the distance between positions shall be computed independent of altitude (which may be provided for DOA positions).

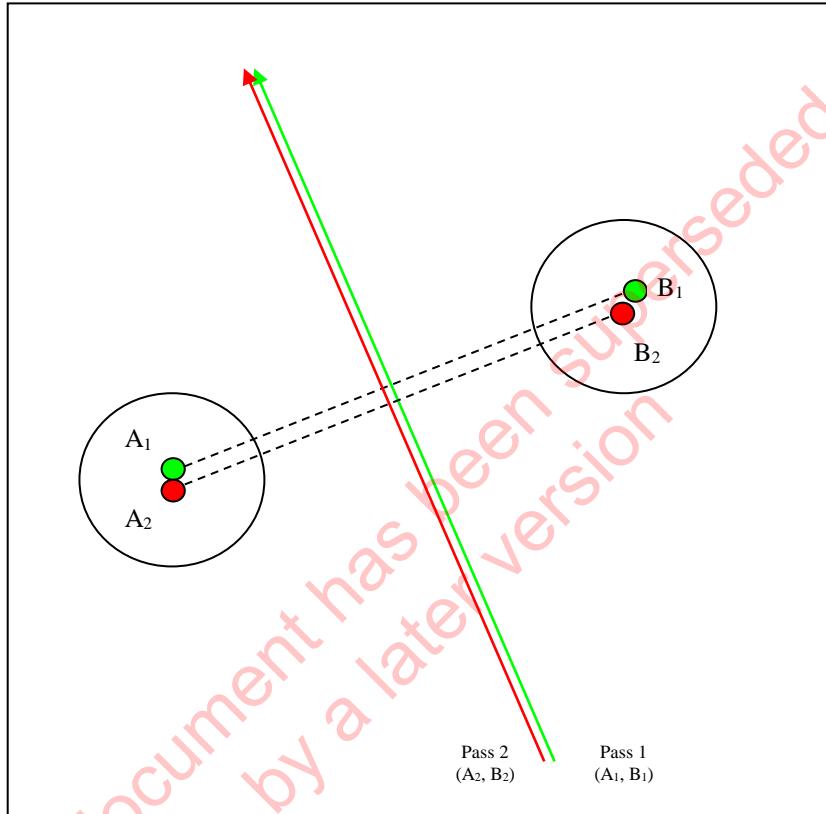


Figure II / B.2: Unresolved Doppler Match Scenario (20 km circles)

II / B.3 POSITION CONFIRMATION

Position Confirmation is the determination of the confirmed beacon position (the resolved position), as described in section 3.2.4. Details on position matching are provided in Annex II / B.2.

II / B.4 PROCEDURES TO DETERMINE BETTER QUALITY LEOSAR ALERT DATA FOR SAME BEACON EVENT POSITION CONFLICTS

II / B.4.1 Introduction

A position conflict exists when an alert is received at an MCC and the position data fails to match (see section II / B.2 above) any previously received position data for the same beacon. MCCs shall use the filtering procedure detailed below for filtering Doppler position conflict alerts for the same beacon event prior to and after position confirmation.

The purpose of the filtering procedure is to minimise the distribution of alert messages containing “poor” quality Doppler position data. If a new alert with Doppler position conflict is for the same beacon event as previously received data, additional checks can be performed to determine if the new Doppler position data is of better quality than previously received Doppler position data and should be transmitted, or is of poorer quality and can be deemed redundant. If the relative quality of the Doppler positions cannot be determined, then the new data should be transmitted. The procedure below ensures that “good” data will not be suppressed while limiting the amount of erroneous data distributed to RCCs and SPOCs.

II / B.4.2 Doppler Position Conflict Procedure

An MCC should identify a reference alert with Doppler position data for each beacon event. By default, the first alert for each pass becomes the reference until another alert of better quality is received. If an alert with new Doppler position data for the same beacon event is received which is determined to be of better quality, and the new Doppler position fails to match any previously received position data for the same beacon, the new alert becomes the reference and a position conflict alert is transmitted.

An MCC determines if a new alert contains Doppler position data of better quality by performing the following checks in sequence. The appropriate action is then taken as indicated (see Table II / B.6).

Step 1:

If both alerts have a bias standard deviation less than 20 Hz, then proceed to Step 2. If both alerts have a bias standard deviation equal to or greater than 20 Hz, or if either bias standard deviation is not available, then quality differentiation cannot be made and the new alert is transmitted.

If the reference alert has a bias standard deviation equal to or greater than 20 Hz, and the new alert has a bias standard deviation less than 20 Hz, then the new alert is deemed to be of better quality, a position conflict alert is transmitted, and the new alert becomes the reference alert. If the reverse is true, the new alert is deemed to be of poorer quality and the new alert is not transmitted.

Step 2:

In this step both alerts are assumed to have bias standard deviations less than 20 Hz. If both alerts have WF values < 2 , then go to Step 3. If the new alert contains a $WF \geq 2$, and the reference alert contains a $WF < 2$ then the new alert is not transmitted. If the WF of the reference alert contains a value ≥ 2 and the new alert contains a $WF < 2$, then the new alert is transmitted and becomes the reference alert. If both alerts have $WF \geq 2$, then quality differentiation cannot be made and the new alert is transmitted.

Step 3:

This step applies when both bias standard deviations are < 20 Hz and both Window Factors are < 2 . In this case, the dimensions of the minor axis of the error ellipse are compared.

If the error ellipse minor axis (MIN) of the new alert is ≥ 99.9 and the MIN of the reference alert < 99.9 , then the new alert is not transmitted. If the MIN for the new alert is < 99.9 and the MIN for the reference alert is ≥ 99.9 , then the new alert is transmitted and becomes the reference alert. Finally, if either of the above conditions are not met, then quality differentiation cannot be made and the new alert is transmitted.

If for any reason the relative quality cannot be determined in the comparison of the Doppler positions from alerts for the same beacon event, the new position data should be transmitted.

	Parameters						
	Bias Std Dev (Hz) MF #13		Window Factor (0 - 9) MF #15		Min. Axis Error Ellipse (km) MF #27		
Steps	Reference Alert	New Alert	Reference Alert	New Alert	Reference Alert	New Alert	Action ³
Step 1	< 20 Hz	< 20 Hz					Go to Step 2
	default ¹	default ¹					New alert transmitted
	≥ 20 Hz	< 20 Hz					New alert transmitted ²
	< 20 Hz	≥ 20 Hz					New alert NOT transmitted
	≥ 20 Hz	≥ 20 Hz					New alert transmitted
Step 2	< 20 Hz	< 20 Hz	< 2	< 2			Go to Step 3
	< 20 Hz	< 20 Hz	< 2	≥ 2			New alert NOT transmitted
	< 20 Hz	< 20 Hz	≥ 2	< 2			New alert transmitted ²
	< 20 Hz	< 20 Hz	≥ 2	≥ 2			New alert transmitted
Step 3	< 20 Hz	< 20 Hz	< 2	< 2	< 99.9	≥ 99.9	New alert NOT transmitted
	< 20 Hz	< 20 Hz	< 2	< 2	≥ 99.9	< 99.9	New alert transmitted ²
	< 20 Hz	< 20 Hz	< 2	< 2	< 99.9	< 99.9	New alert transmitted
	< 20 Hz	< 20 Hz	< 2	< 2	≥ 99.9	≥ 99.9	New alert transmitted

¹ indicates that at least one bias standard deviation is not available.

² indicates that the new alert becomes the reference alert.

³ if the new alert is transmitted, then the Poor Quality Flag (PQF) is set to 0; otherwise, PQF is set to 1.

Table II / B. 5: Procedures to Determine Better Quality Alert Data for Same Beacon Event Doppler Position Conflicts

II / B.5 DETAILED PROCEDURES FOR ALERT DATA DISTRIBUTION

II / B.5.1 Analysis and General Representation of Alert Data Processing

Alert data received by a Cospas-Sarsat MCC, either from its associated LUTs or from another MCC, shall be forwarded to a MCC, a SPOC or a RCC if it contains ‘new’ information useful to SAR services. The alert data distribution process consists of a set of rules commonly used by Cospas-Sarsat MCCs for deciding whether new input data concerning a particular 406 MHz beacon ID contains ‘new’ information. It is based on a number of parameters (defined in the Cospas-Sarsat Glossary (document C/S G.004) and in the “Acronyms and Terminology” page on the Cospas-Sarsat website, available at <http://www.cospas-sarsat.int/en/pro>, under the Documents menu) and matching rules (defined in this document), which include:

- the definitions of ‘beacon events’, ‘position confirmation’ and ‘position conflict’; and
- the definition of distance criteria for matching Doppler and encoded position data.

However, these basic rules and the variety of position data available in 406 MHz alert messages create a large number of possible combinations which need to be thoroughly analysed to ensure the consistency of the alert data distribution process throughout the Cospas-Sarsat MCC network.

In order to implement this data distribution process, the ‘position information content’ of each valid incoming alert message (referred to as ‘Input’ or ‘I’ in this Annex) must be compared with the information already transmitted concerning the same beacon ID. Therefore, the history of all data already transmitted must be preserved. For each beacon ID, that history can be summarised in a ‘Status word’ (Sw). Input and Status words are both characterised by the type of position information (received in the input or transmitted in previous messages). Similarly, the ‘action(s)’ resulting from the process (i.e., the message to be transmitted, its format and recipients) can be summarised in an ‘Action word’ (Aw) and characterised by the type of position information to be forwarded, taking also into account position data already distributed. The functional relations between ‘Input’, ‘Status word’ and ‘Action word’ in the process are summarised in Figure II / B.2.

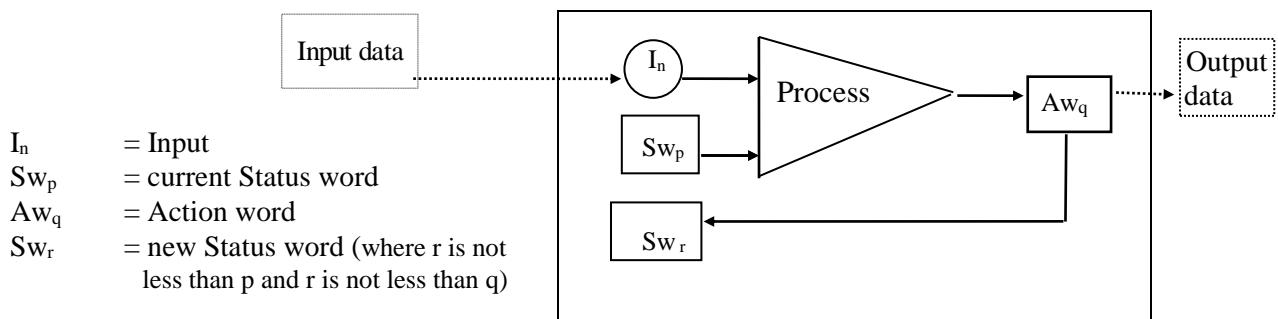


Figure II / B. 3: Alert Data Processing Concept

II / B.5.2 Definition of Input, Status and Action Words

The possible combinations of position data which characterise an input (I), the current status (Sw) or the resulting action (Aw) of the process concerning a given beacon ID, are described in Figure II / B.3. No other combinations of the type of position data are allowed and the possible position information contents of I, Sw and Aw are summarised in the last column. Figure II / B.3 only describes the definition of ‘Input’, ‘Status word’ and ‘Action word’; the functional relations between ‘Input’, ‘Status word’ and ‘Action word’ are described in Figure II / B.2.

Figure II / B.4: Definition of the Input, Status and Action Words for 406 MHz Alerts

Input	Type of position data					Status word	Action word	Comments Position Information Content
	No Position Data	DOA Doppler Positions	Encoded Position Data	Dop/DOA Pos. Confirmed	Dop/DOA & E Positions Matched			
-	0	0	0	0	0	Sw ₀	Aw ₀	No message received or sent
I ₁	1	0	0	0	0	Sw ₁	Aw ₁	Unlocated alert
I ₂	0	1	0	0	0	Sw ₂	Aw ₂	Doppler/DOA positions only
I ₃	0	0	1	0	0	Sw ₃	Aw ₃	Encoded position only
I ₄	0	1	1	0	0	Sw ₄	Aw ₄	Doppler, DOA & E positions all unmatched
I ₅	0	1	0	1	0	Sw ₅	Aw ₅	Doppler/DOA pos. only, position confirmed
I ₆	0	1	1	1	0	Sw ₆	Aw ₆	Doppler/DOA pos. (pos. confirmed) + E pos. unmatched
I ₇	0	1	1	1	1	Sw ₇	Aw ₇	Resolved positions (Doppler/DOA & E matched)

Notes: - The Input word (I) is specific to each individual input and independent of the origin of the data (e.g. another MCC or the LUTs associated with the receiving MCC).

- The Status word (Sw) summarises all previous inputs and actions in respect of a particular beacon ID. Sw₅, Sw₆ and Sw₇ each mean that position has been confirmed. However, the distinction between the various position information contents after position confirmation is relevant for the Input and Action words.
- The Actions to be carried out as a result of the process depend on the Input / Status combination, but also on the results of comparisons (matching tests) between ‘old’ and ‘new’ position data received by the MCC, as shown in the matrix (Figure II / B.3). The selected Action word is also used to define the message format to be sent and, before

position confirmation, characterises the new status associated with that beacon ID after completion of the selected Action (i.e.: $Aw_i \rightarrow Sw_i$).

II / B.5.3 Process Matrix for Alerts

The process is summarised in Figures II / B.5.1 and II / B.5.2 for input LEOSAR/GEOSAR alerts and input MEOSAR alerts, respectively. These figures define, for each Input / Status combination the possible output (Action words), the corresponding SIT message numbers (to be used if the new data in the Input has to be forwarded to another MCC, outside the processing MCC service area) and the appropriate recipient(s) of this information, as determined by the geographic sorting of position data. A single Action Word applies to a specific beacon activation regardless of whether the data source is the LEOSAR, GEOSAR or MEOSAR system.

II / B.5.3.1 Processing Before Position Confirmation (Sw₀, Sw₁, Sw₂, Sw₃, Sw₄ Status)

The process is quite simple when no data was previously received for the beacon ID in a new Input (Status Sw₀), or when the previously received alert(s) for that ID did not include any position information (Status Sw₁).

However, as shown in Figures II / B.5.1 and II / B.5.2, a number of Input / Status combinations may result in several possible Actions. This occurs when a number of alert messages have been received prior to the new input, but the available position data did not satisfy the matching criteria for position confirmation. The new position data in the input message must then be compared with all positions previously received for the same beacon ID, and these matching tests can lead to different Actions. The position information content of each possible Action is used to select the appropriate Action word as illustrated in the special algorithm described in section II / B.5.4 (Figures II / B.6, II / B.7, II / B.8 and II / B.9).

II / B.5.3.2 Processing After Position Confirmation (Sw₅, Sw₆, Sw₇ Status)

After position confirmation, the distribution of input alert data is normally continued, and a different processing logic must be implemented since the initial objective of increasing the position information content to obtain a confirmed position has already been achieved. To reflect this different approach, the new 'Actions' are identified in the matrices as C_t (see Figures II / B.5.1, II / B.5.2 and II / B.9).

Except for additional encoded position, all input position data is compared to the last resolved position transmitted by the MCC, in accordance with the usual processing criteria. If the process results in an Action different from C_{t0} (redundant data not to be distributed), the input position data is sent to the destination(s) for which continued transmission is enabled.

Notes:

The suffix of Inputs (I words), Actions (C_t) and Status (Sw) remain consistent with the definitions of Figure II / B.3, although there is no practical differences between the

three Status words (Sw₅, Sw₆, and Sw₇) in terms of processing after position confirmation in the proposed procedure.

Figures II / B.5.1 and II / B.5.2 indicates several possible outcome for all Inputs but one after position confirmation. However, only one comparison is performed between the new position data in the Input and the known resolved position, except for additional encoded position. Therefore, the outcome is always unambiguous and no 'priority rule' is required.

This document has been superseded
by a later version

Figure II / B.5.1: Processing Matrix, Message Formats and Distribution of new 406 MHz LEO SAR/GEOSAR Alerts

I ₁ (no position data)			I ₂ (A / B Doppler positions)			I ₃ (Encoded only)			I ₄ (A / B / E unmatched)			I ₅ (Confirmed Doppler)			I ₆ (Conf. Doppler + E unmatched)			I ₇ (Confirmed Doppler and E)			
	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest			
Sw ₀	Aw ₁	122	C	Aw ₂	125	AB	Aw ₃	122	E	Aw ₄	126	ABE	Aw ₅	127	R	Aw ₆	127	R	Aw ₇	127	R
Sw ₁	Aw ₀	-	-	Aw ₂	125	ABP	Aw ₃	122	EP	Aw ₄	126	ABEP	Aw ₅	127	RP	Aw ₆	127	RP	Aw ₇	127	RP
Sw ₂	Aw ₀	-	-	Aw ₅	127	RIP	Aw ₇	124	RIP	Aw ₇	127	RIP	Aw ₅	127	RIP	Aw ₆	127	RIP	Aw ₇	127	RIP
Sw ₃	Aw ₀	-	-	Aw ₇	127	RIP	Aw ₀	-	-	Aw ₇	127	RIP	Aw ₇	127	RIP	Aw ₇	127	RIP	Aw ₇	127	RIP
Sw ₄	Aw ₀	-	-	Aw ₇	127	RIP	Aw ₇	124	RIP	Aw ₇	127	RIP	Aw ₇	127	RIP	Aw ₇	127	RIP	Aw ₇	127	RIP
Sw ₅ Sw ₆ Sw ₇	C _{t0}	-	-	C _{t0}	-	-	C _{t0}	-	-	C _{t0}	-	-	C _{t0}	-	-	C _{t0}	-	-	C _{t0}	-	-
	C _{t2}	126	RD	C _{t3}	123	RD	C _{t4}	126	RD	C _{t5}	127	RD	C _{t6}	127	RD	C _{t7}	127	RD			
	C _{t5}	127	RD	C _{t7}	124	RD	C _{t7}	127	RD												

Notes: For Ship Security alerts, the destination is "C" for all transmitted messages.

I_i = Input

A = A Doppler position

R = Confirmed position

Dest = Destination of SIT message

Sw_i = Status word

B = B Doppler position

I = Incorrect previous position(s)

SIT = Subject Indicator Type /
(standard message format)

Aw_i = Action word

E = Encoded position

C = Country code destination

P = Previous recipient(s)

Ct_i = Continue transmission

O = DOA position

RD= Post Confirmation destination

Figure II / B.5.2: Processing Matrix, Message Formats and Distribution of new 406 MHz MEOSAR Alerts

I ₁ (no position data)			I ₂ (DOA position)			I ₃ (Encoded only)			I ₄ (DOA / E unmatched)			I ₅ (Confirmed DOA)			I ₆ (Conf. DOA + E unmatched)			I ₇ (Confirmed DOA and E)			
	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest	Aw	SIT	Dest			
Sw ₀	Aw ₁	142	C	Aw ₂	145	O	Aw ₃	142	E	Aw ₄	146	OE	Aw ₅	147	R	Aw ₆	147	R	Aw ₇	147	R
Sw ₁	Aw ₀	-	-	Aw ₂	145	OP	Aw ₃	142	EP	Aw ₄	146	OEP	Aw ₅	147	RP	Aw ₆	147	RP	Aw ₇	147	RP
Sw ₂	Aw ₀	-	-	Aw ₅	147	RIP	Aw ₇	144	RIP	Aw ₇	147	RIP	Aw ₅	147	RIP	Aw ₆	147	RIP	Aw ₇	147	RIP
Sw ₃		Aw ₂	146	OP	Aw ₃	145	OP	Aw ₄	143	EP	Aw ₅	146	OEP	147	RIP	Aw ₆	147	RIP	Aw ₇	147	RIP
Sw ₄		Aw ₀	-	-		Aw ₇	147	RIP	Aw ₀	-	-	147	RIP	Aw ₇	147	RIP	Aw ₇	147		RIP	
Sw ₅ Sw ₆ Sw ₇	Ct ₀	Aw ₆	147	RIP		Aw ₇	144	RIP	Aw ₀	-	-	147	RIP	Aw ₇	147	RIP	Aw ₇	147		RIP	
Sw ₅ Sw ₆ Sw ₇		Aw ₆	147	RIP		Aw ₀	-	-	Aw ₄	143	EP	147	RIP	Aw ₆	147	RIP	Aw ₆	147		RIP	
Sw ₅ Sw ₆ Sw ₇		Aw ₄	146	OP	Ct ₂	146	RD	Ct ₃	143	RD	Ct ₄	146	RD	Ct ₅	147	RD	Ct ₆	147	RD	Ct ₇	147

Note: See Figure II / B.4.1

II / B.5.4 Special Processing Procedures

II / B.5.4.1 Tests and Flag Setting for Special Processing Procedures

Multiple flags may be positioned to determine the output of an In / Swp combination which requires special procedures:

DEM = Doppler / DOA to Encoded positions Matching flag: set to “1” if a D (Doppler or DOA) position and an Encoded position match the distance separation criterion (and other criteria as may be required) and set to “0” otherwise. However, in some Input / Status combinations this flag has no relevance, for example, if the Input is the I₂ type, containing only Doppler or DOA position data. In such cases the DEM flag is assumed to be set to default value “0”. The DEM test is not applicable after position confirmation.

In the DEM test, the E position of the Input is compared to all previously received Doppler and DOA positions, if the position is not confirmed. After position confirmation, the E position is compared to previously received non-redundant E positions if there is previous encoded position, or to the confirmed position if there is no previous encoded position.

Alternatively, the A / B Doppler positions or DOA position of the Input are compared with any E position previously received at the MCC, if the position is not confirmed. A correct match with one Doppler or DOA position is sufficient to achieve position confirmation. After position confirmation, the confirmed position is compared to the input Doppler positions or DOA position.

SBE = the ‘Same Beacon Event’ flag is to be set for each matching test as follows:

SBE set to “1” if, for the same Beacon ID, previous A / B Doppler positions to be compared with Input are from same satellite and same TCA \pm 20 minutes.

Otherwise, SBE set to “0”.

The SBE flag is used only in relation with the Doppler to Doppler position matching tests. It has no relevance for Doppler to DOA, DOA to DOA, DEM or EEM tests and is set to the default value “0” in such cases.

DBE = the ‘Dependent Beacon Event’ flag is to be set for each matching test as follows:

DBE set to “1” if, for the same Beacon ID:

a) prior to position confirmation:

- i. the unique set of satellites used to compute the new DOA position is not contained in (or does not contain) the unique set of satellites used

to compute a previously sent DOA position and every portion of the time period associated with the new DOA position (i.e., the time from the first to last burst used to compute the new DOA position) is within 2 seconds of some portion of the time period associated with a previously sent DOA position; or

ii. the unique set of satellites used to compute the new DOA position is contained in (or contains) the unique set of satellites used to compute a previously sent DOA position and the time of the latest beacon burst used to compute the new DOA position is within 30 minutes of the time of the latest beacon burst used to compute the previously sent DOA position; or

b) after position confirmation:

- i. the new DOA position matches the confirmed position, and the time of the latest beacon burst used to compute the new DOA position is within 15 minutes of the time of the latest beacon burst used to compute a previously sent DOA position that matched the confirmed position; and
- ii. the new DOA position does not match the confirmed position, and the time of the latest beacon burst used to compute the new DOA position is within 10 minutes of the time of the latest beacon burst used to compute a previously sent DOA position that did not match the confirmed position.

Otherwise DBE = 0, including DOA to Doppler, Doppler to Doppler, DEM and EEM position matching tests.

DDM = LUT computed (i.e., Doppler/DOA) position Matching flag: set to “1” if two Doppler positions, a Doppler position and a DOA position, or two DOA positions match the distance separation criterion (and other criteria as may be required) and set to “0” otherwise. For an Unresolved Doppler Position Match (as specified in Annex II / B.2) set to “0”. However, in some Input/ Status combinations this flag has no relevance, for example, if the current status is Sw₃ (previous alert data received at the MCC contain only encoded position data). In such cases the DDM flag is set to default value “0”.

After position confirmation, input Doppler or DOA position is compared for redundancy test only with the confirmed position previously processed by the MCC. In this context, the DDM test is reinterpreted as a DRM test (Doppler or DOA to Confirmed position Matching).

EEM = Encoded position / Encoded position Matching flag : set to “1” if two encoded positions match the distance separation criterion (and other criteria as may be required) and set to “0” otherwise. However, the EEM test is relevant only

in a limited number of cases (e.g. for the processing of I_3 type Inputs (E position only) in a Sw_3 context (only E positions were previously received)). In all other situations the EEM flag should be set to its default value “0”.

After position confirmation, the E position is compared to previously received non-redundant E positions if there is previous encoded position, or to the confirmed position if there is no previous encoded position.

PQF = Poor Quality Flag : The Poor Quality Flag is used in conjunction with the DDM test only, when a position conflict exists between Doppler positions for the same beacon event ($SBE = 1$ and $DDM = 0$). In such cases, parameters characterising the quality of the position data are tested to determine whether the new data provide a better quality position.

PQF is set to “1” if the new position data is of inferior quality than the data previously processed by the MCC for the same beacon event. The new data should then be considered as redundant.

PQF is set to “0” if the new position data is of better quality than the data previously processed for the same beacon event, if the relative quality of the new versus the old position data cannot be determined for the same beacon event or if $SBE = 0$. PQF is set to “0” for Doppler to DOA position matches. For DOA to DOA matches, PQF is set to “1” if $DDM = 0$ and position has been confirmed; otherwise PQF is set to “0” for DOA to DOA matches.

SRF = Send Redundant Flag : SRF is used to determine if an alert that is otherwise redundant should be transmitted. SRF is set to “1”:

- prior to position confirmation, if the time of the latest beacon burst used to compute the new DOA position is more than 5 minutes after from the time of the latest beacon burst used to compute all previously sent DOA positions; or
- has better quality DOA position, per the procedure “Distribution of Alerts with Better Quality DOA Position” in section 3.2.3.3; or
- prior to position confirmation, if the new Doppler alert provides Image Position Determination.

Otherwise SRF is set to “0”.

II / B.5.4.2 Selection of the Relevant Action in Input / Status Combinations with Multiple Outputs

When the I / Sw combination leads to several possible actions, it is essential to clarify which Action in the sequence supersedes others and should be completed. The logic to be followed in this selection is always that:

Actions enhancing the ‘position information content’ of the alert to be forwarded by the MCC should have overall precedence ($Aw_7 > Aw_6 > Aw_5 > \text{etc.}$) provided the ‘position information content’ (or suffix) of the Action word is superior to the suffix of the current Status word; and

Action Aw_0 (which means that the same data as in the Input has already been processed) has precedence over an Action which has same ‘position information content’ as the current Status (in Sw_4 status, $Aw_0 > Aw_4$), except when $SRF = 1$. This rule reflects the fact that the Input is redundant, i.e. the Input matches all the characteristics of at least one set of data previously received, and all other matching tests have failed to enhance the ‘position information content’ of the possible output.

II / B.5.4.3 Definition of Special Processing Matrices

Special processing matrices are defined for each Status of the process to clarify the implementation of the test sequence to be performed for each possible input data. The Input / Status combinations which have a unique output Action (see Figure II / B.5) are not repeated in the special processing matrices shown in the following sections.

Notes:

Shaded cells in the ‘Input’ columns correspond to flag combinations which are not applicable for the particular Input / Status combination.

The default value for all flags is “0”. If a test is irrelevant in a particular context (e.g. in the Sw_2 status, $DEM = 1$ and $DDM = 1$ means the PQF test is irrelevant) then the corresponding flag is set to “0” and the cell in the matrix is shaded. The flag column is entirely shaded if the corresponding test is inapplicable for all inputs in the Sw context (e.g. the EEM column in the Sw_2 status).

An “X” indicated in the flag column means that both flag values are possible, but the actual flag value does not affect the output Action (therefore the test can be ignored in this context).

II / B.5.4.3.1 Sw_2 Special Processing Matrix

Doppler and/or DOA positions for the same beacon ID have already been processed by the MCC which receives the new input I_j .

Since no encoded position has previously been received, the EEM test is irrelevant (see shaded column). Similarly, the PQF test is irrelevant when a DEM test or a DDM test show a successful match ($DEM = 1$ and / or $DDM = 1$).

Figure II / B.6: Special Processing for Sw₂ Status

DEM	SBE/ DBE ₁	DDM	PQF ₂	EEM	SRF	I ₂ [A / B] or [O]	I ₃ [E]	I ₄ [A / B / E] or [O / E]
1	X	1	0	0	0			Aw ₇
1	X	0	0	0	0		Aw ₇	Aw ₇
0	1	1	0	0	0	Aw ₀		Aw ₄
0	1	1	0	0	1	Aw ₂		Aw ₄
0	1	0	1	0	0	Aw ₀		Aw ₄
0	1	0	1	0	1	Aw ₂		Aw ₄
0	1	0	0	0	0	Aw ₂	Aw ₄	Aw ₄
0	0	1	0	0	0	Aw ₅		Aw ₆
0	0	0	0	0	0	Aw ₂	Aw ₄	Aw ₄
Aw priority if multiple matching tests are required						Aw ₅ > Aw ₀ > Aw ₂	Aw ₇ > Aw ₄	Aw ₇ > Aw ₆ > Aw ₄

1 DBE is used for MEOSAR input. SBE is used for LEOSAR input.

2 PQF is always 0 on DOA to Doppler, and DOA to DOA matches.

II / B.5.4.3.2 Sw₃ Special Processing Matrix

An 'E' (encoded) position for the same beacon ID has already been processed by the MCC which receives the new input I_j, but no Doppler or DOA position data were received.

Therefore, the Doppler / Doppler, Doppler / DOA and DOA / DOA matching tests, and the associated SBE, DDM, SRF and PQF tests, are irrelevant in this Status (columns SBE, DDM and PQF are shaded).

Figure II / B.7: Special Processing for Sw₃ Status

DEM	SBE/ DBE ₁	DDM	PQF	EEM	I ₂ [A / B] or [O]	I ₃ [E]	I ₄ [A / B / E] or [O / E]	I ₅ [A / B] or [O]	I ₆ [A / B+(E)] or [O / E]
1	0	0	0	1			Aw ₇		Aw ₇
1	0	0	0	0	Aw ₇		Aw ₇	Aw ₇	Aw ₇
0	0	0	0	1		Aw ₀	Aw ₄		Aw ₆
0	0	0	0	0	Aw ₄	Aw ₃	Aw ₄	Aw ₆	Aw ₆
Aw priority if multiple matching tests are required					Aw ₇ > Aw ₄	Aw ₀ > Aw ₃	Aw ₇ > Aw ₄	Aw ₇ > Aw ₆	Aw ₇ > Aw ₆

1 DBE is used for MEOSAR input. SBE is used for LEOSAR input.

II / B.5.4.3.3 Sw4 Special Processing Matrix

D (Doppler or DOA) positions data and encoded position data for the same beacon ID have already been processed by the MCC which receives the new input, but no position matching tests have confirmed position.

Figure II / B.8: Special Processing for Sw4 Status

DEM	SBE/ DBE ₁	DDM	PQF ₂	EEM	SRF	I ₂ [A / B] or [O]	I ₃ [E]	I ₄ [A / B / E] or [O / E]	I ₅ [A / B] or [O]	I ₆ [A / B+(E)] or [O / E]
1	X	1	0	0	0	Aw ₇		Aw ₇	Aw ₇	Aw ₇
1	X	0	0	0	0	Aw ₇	Aw ₇	Aw ₇	Aw ₇	Aw ₇
0	1	1	0	1	1			Aw ₄		Aw ₆
0	1	1	0	1	0			Aw ₀		Aw ₆
0	1	1	0	0	1	Aw ₂		Aw ₄	Aw ₆	Aw ₆
0	1	1	0	0	0	Aw ₀		Aw ₄	Aw ₆	Aw ₆
0	1	0	1	1	1			Aw ₄		Aw ₆
0	1	0	1	1	0			Aw ₀		Aw ₆
0	1	0	1	0	1	Aw ₂		Aw ₄	Aw ₆	Aw ₆
0	1	0	1	0	0	Aw ₀		Aw ₄	Aw ₆	Aw ₆
0	X	0	0	1	0			Aw ₀	Aw ₄	Aw ₆
0	X	0	0	0	0	Aw ₄	Aw ₄	Aw ₄	Aw ₆	Aw ₆
0	0	1	0	1	0			Aw ₆		Aw ₆
0	0	1	0	0	0	Aw ₆		Aw ₆	Aw ₆	Aw ₆
Aw priority if multiple matching tests are required						Aw ₇ > Aw ₆ > Aw ₀ > Aw ₄ > Aw ₂	Aw ₇ > Aw ₆ > Aw ₄ > Aw ₀ > Aw ₂	Aw ₇ > Aw ₆ > Aw ₄ > Aw ₀ > Aw ₂	Aw ₇ > Aw ₆	Aw ₇ > Aw ₆

1 DBE is used for MEOSAR input. SBE is used for LEOSAR input.

2 PQF is always 0 on DOA to Doppler, and DOA to DOA matches.

II / B.5.4.3.4 Special Filtering Matrix After Position Confirmation

It is assumed that continued transmission is enabled, otherwise no action should be taken when receiving new alerts for the particular beacon ID under consideration.

The filtering procedure after position confirmation is as follows:

- the Doppler or DOA position data received in the new input is compared only to the resolved position (R) used for reference (i.e. the DRM test replaces the DDM test);
- the encoded position data received in the new input is compared to previous encoded position, unless there is no previous encoded position, in which case it is compared to the resolved position (R) used for reference;
- all new beacon events are transmitted, based on the setting of the Same/Dependent Beacon Event flag; and
- position data for Same/Dependent beacon events is forwarded if any one of the possible tests fails.

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Figure II / B.9: Special Processing for Sw₅, Sw₆ and Sw₇ Status

SBE/ DBE ¹	DRM	PQF ²	EEM*	SRF	I ₂ [A / B] or [O]	I ₃ [E]	I ₄ [A / B / E] or [O / E]	I ₅ [D]	I ₆ [D+(E)]	I ₇ [Conf. D+E]
1	1	0	1	1			Ct ₇		Ct ₆	Ct ₇
1	1	0	1	0			Ct ₀		Ct ₀	Ct ₀
1	1	0	0	1	Ct ₇			Ct ₅	Ct ₆	Ct ₇
1	1	0	0	0	Ct ₀		Ct ₄	Ct ₀	Ct ₆	Ct ₇
1	0	1	1	0 ³			Ct ₀		Ct ₀	Ct ₀
1	0	1	0	1	Ct ₂		Ct ₄	Ct ₅	Ct ₆	Ct ₇
1	0	1	0	0	Ct ₀		Ct ₄	Ct ₀	Ct ₆	Ct ₇
1	0	0	1	0		Ct ₀	Ct ₄		Ct ₆	Ct ₇
1	0	0	0	0	Ct ₂	Ct ₃	Ct ₄	Ct ₅	Ct ₆	Ct ₇
0	1	0	1	0			Ct ₇		Ct ₆	Ct ₇
0	1	0	0	0	Ct ₅		Ct ₄	Ct ₅	Ct ₆	Ct ₇
0	0	0	1	0		Ct ₇	Ct ₄		Ct ₆	Ct ₇
0	0	0	0	0	Ct ₂	Ct ₃	Ct ₄	Ct ₅	Ct ₆	Ct ₇

1 DBE is used for MEOSAR input. SBE is used for LEOSAR input.

2 PQF is always 0 on DOA to Doppler, and DOA to DOA matches.

3 After position confirmation, PQF = 1 implies a Doppler to Doppler matches and SRF is always 0 for Doppler to Doppler matches.

* The encoded position data received in the new input is compared to the resolved position (R) used for reference if there is no previous encoded position.

II / B.6 DISTRIBUTION OF BEACON REGISTRATION INFORMATION

The identification data in the beacon message includes a code which identifies the country where the beacon is registered. When an MCC acquires distress alert or NOCR data (based on the alert's country code), the MCC can determine if it has access to the registry data. If so, the beacon registration could be transmitted to the MCC in whose service area the Doppler, DOA or encoded position is located using the SIT 925 message format. Registration data shall be routed in accordance with Figure II / A.8. The registration data would only be sent upon the first reception of an alert or NOCR message.

The beacon ID contained in the beacon message in the SIT 925 message can be used by the receiving MCC to correlate it to a previously received alert message and forward the registry data to the appropriate RCC/SPOC.

An MCC is not required to automatically transmit registration data from its registry to other MCCs. However, the reception of this data is required by all MCCs.

An MCC receiving an NOCR alert may respond with registration data without being specifically requested.

II / B.7 NOCR PROCEDURES

II / B.7.1 Procedure

An NOCR message is initiated by an MCC when a 406 MHz alert for a beacon ID is first located in its service area and the country code in the 406 MHz beacon message is associated with another country's search and rescue region (SRR). The MCC service area includes the entire service area of the MCC and is not limited to its national SRR. The location can be provided by Doppler location processing, DOA location processing or the encoded position contained in beacons coded using a location protocol. In some conditions multiple MCCs may initiate an NOCR message to the same support MCC.

An MCC in whose service area an alert is located, transmits the NOCR message to the associated MCC (i.e., the destination MCC) based on the distribution matrix provided in Figure II / A.8. The appropriate associated MCC for NOCR message distribution is determined by the country code contained in the beacon ID of the message, so that the NOCR is distributed to the country that maintains the beacon registry for that country code, as provided on the Cospas-Sarsat website at www.cospas-sarsat.int "Contact List" for "406 MHz Beacon Registers (available 24/7 for SAR Services)".

An MCC that has assumed backup responsibilities for another MCC shall initiate and distribute NOCR messages on behalf of the MCC being backed up.

In addition to distributing the NOCR message to the appropriate SPOC or MCC, the associated MCC shall process the NOCR message as an alert message, in accordance with Figures II/B.5.1 and II/B.5.2.

An NOCR message is not sent for unlocated alerts because, by definition, the message initiation process is based on geographic position information. An MCC is not required to send an NOCR message to another MCC when the sending MCC has already sent to the receiving MCC an alert located in the service area of the receiving MCC.

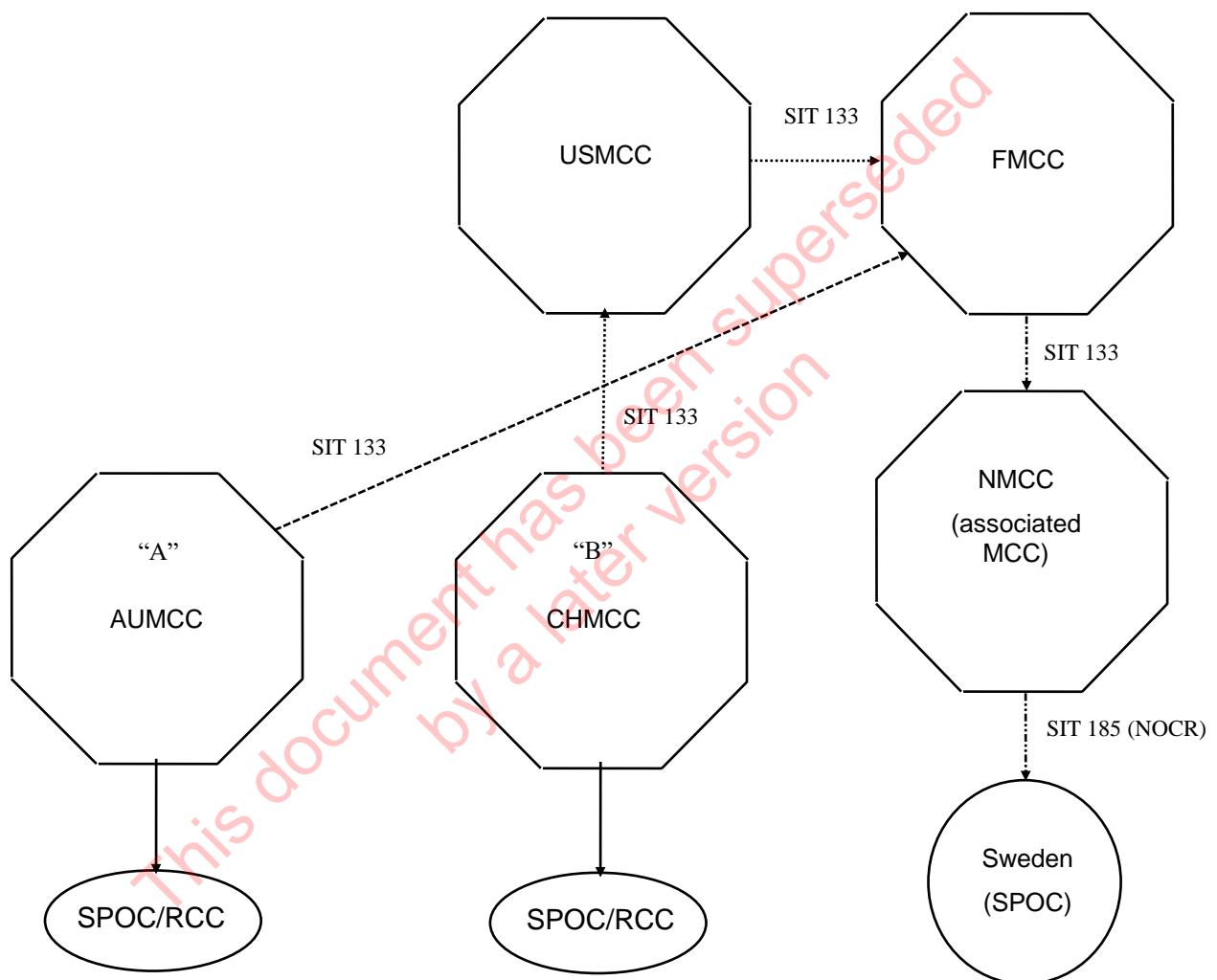
The receiving MCC may filter redundant NOCRs for the same beacon ID.

II / B.7.2 NOCR ExampleScenario

Country code in Beacon ID: Sweden (265)

“A” Position Service Area: AUMCC (Australian MCC)

“B” Position Service Area: CHMCC (Chilean MCC)



II / B.8 DISTRIBUTION OF 406 MHz SHIP SECURITY ALERTS

The identification data in the beacon message includes a protocol code which can identify the 406 MHz transmission as a ship security alert. In addition, the beacon message also contains a country code which can be associated with the “flag state” of the vessel. When an MCC receives a ship security alert, the alert shall be processed according to the same procedures that apply for distress alerts except that the resulting ship security alert message will be forwarded based only on the country code included in the beacon message.

All States wishing to use the Cospas-Sarsat System to relay ship security alerts should make the necessary arrangements with their associated MCC. Arrangements should include the identification of the competent authority responsible for receiving the ship security alert and the communication link to the competent authority

II / B.8.1 Procedure

An MCC shall process ship security alerts (beacon message bits 37-40 = 1100) according to the logic provided in Figures II / B.1 and B.4.2. Routing of ship security alerts shall be based on the country code contained in the beacon message, that is, the message will be transmitted to the MCC associated with the country code, and not transmitted to other MCCs, RCCs, or SPOCs based on the Doppler locations, DOA position or encoded position contained in the beacon message. Message routing for ship security alerts shall follow the data distribution matrix as provided at Figure II / A.8. Ship security alerts shall be exchanged between MCCs using the formats and data content for alert messages as contained in document C/S A.002 (SID).

When a ship security alert is received by the Associated MCC, MCC shall notify the relevant competent security authority as provided by IMO or another appropriate point of contact as previously arranged.

The Associated MCC shall continue to provide information to the competent authority after positive confirmation, as described in section 3.2.5.

II / B.8.2 Ship Security Alerts Examples

Scenario

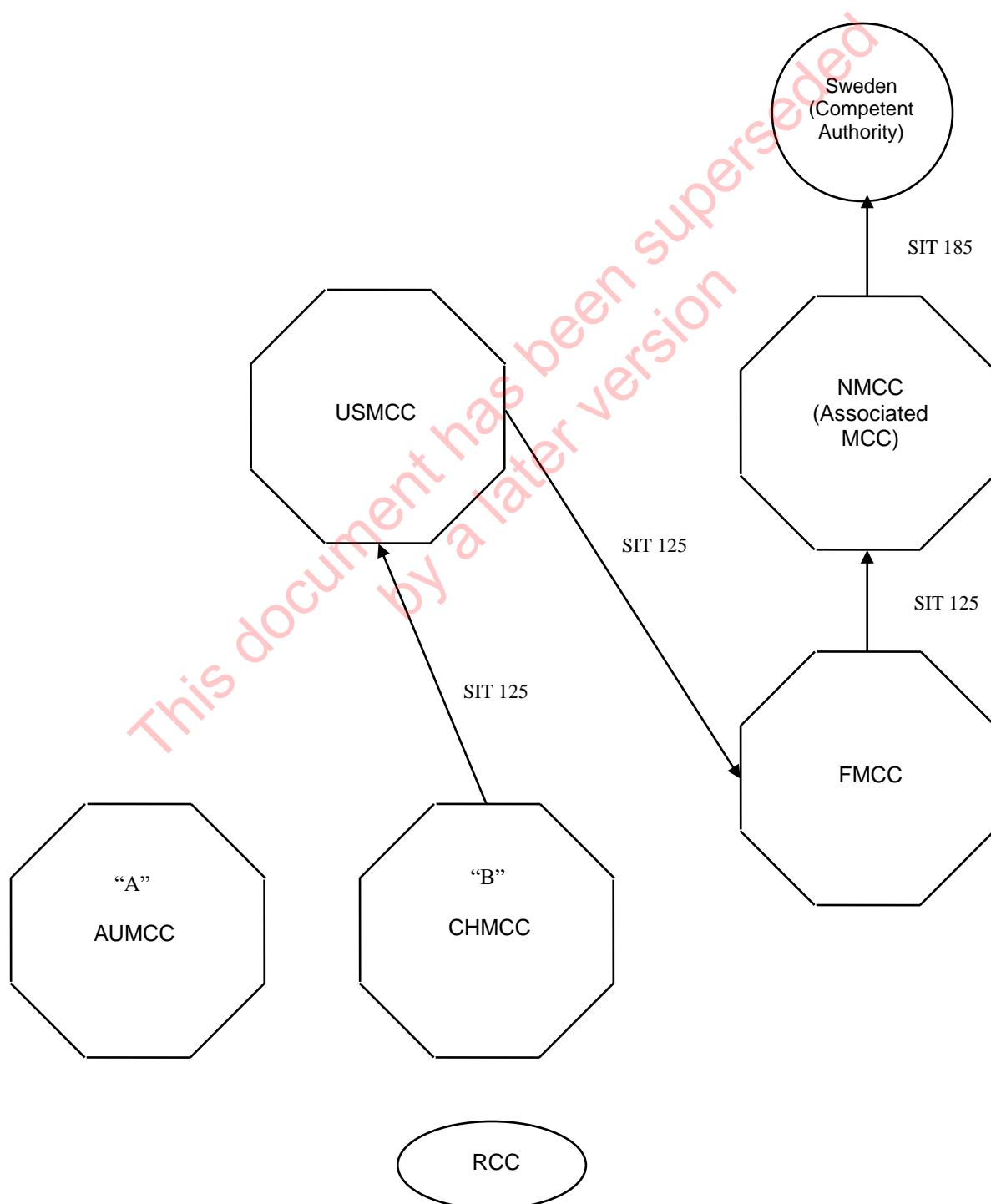
Country code in Beacon ID: Sweden (265)

Initial Alert with Doppler Location

“A” Position Service Area: AUMCC (Australian MCC)

“B” Position Service Area: CHMCC (Chilean MCC)

Receiving MCC: CHMCC



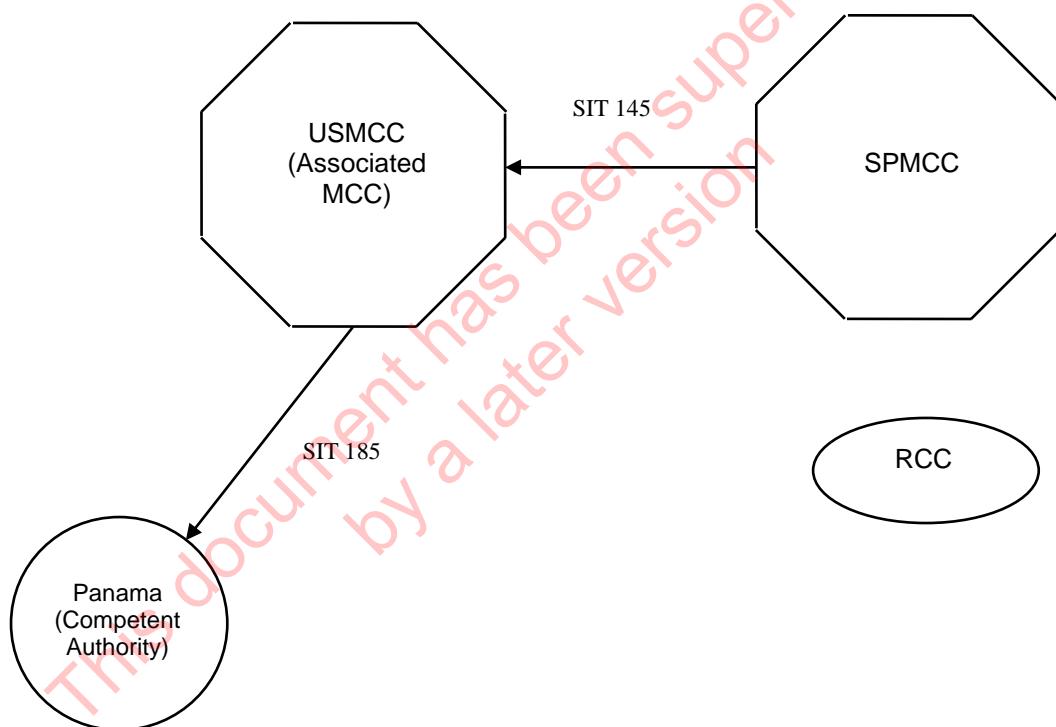
Scenario

Country code in Beacon ID: Panama

Initial Alert with DOA Position

DOA Position Service Area: SPMCC (Spanish MCC)

Receiving MCC: SPMCC



II / B.9 PROCESSING AND DISTRIBUTION OF 406 MHz INTERFERENCE DATA

II / B.9.1 406 MHz Interference Data Processing

When processing 406 MHz interference data, the matching of interferer solutions is based strictly on location, with a 100 km criterion. In addition, the thresholds for closing interferer sites (i.e., for resetting the interferer activation status to zero) 72 hours without new data or 20 missed LEO satellite passes, takes into account the fact that interferers often do not transmit continually.

II / B.9.2 406 MHz Interference Data Distribution

MCCs exchange 406 MHz interference data from LEOLUTs and MEOLUTs in the SIT 121 and SIT 141 message formats, respectively. MCCs shall automatically distribute 406 MHz interference data to other MCCs only when the position is confirmed, based on the location of the interferer. MCCs shall send at least two messages to other MCCs for each interferer site.

Interference data received from MEO satellites shall be processed and distributed independently from interference data received from LEO satellites.

II / B.10 RETURN LINK SERVICE (RLS) PROCEDURES

II / B.10.1 Procedure

An MCC shall initiate a Return Link Service (RLS) message to the MCC associated with the Return Link Service Provider (RLSP) when the position of a 406 MHz beacon with Return Link capability as specified in document C/S T.001 is confirmed to be in the MCC's service area. An RLS message is only sent for beacons with Return Link capability. Beacon position is confirmed, as specified in section 3.2.4. The MCC associated with the RLS provider shall distribute RLS messages to the designated RLSP, as specified in Figure II/B.9. If the designated RLSP is not known (i.e., PDF-2 of the beacon message is not usable), then a position confirmation alert shall be sent to each MCC associated with a designated RLS provider.

Figure II / B.10: Associated MCCs for Return Link Service Providers

Satellite Constellation RLSP	Associated MCC
SAR/Galileo	FMCC
(Glonass)*	CMC

* Glonass is not currently a designated RLS provider, but may provide this capability in the future.

RLS messages shall be transmitted to the MCC(s) associated with the RLS provider(s) based on the distribution matrix provided in Figure II / A.8. In addition to distributing the RLS message to the appropriate MCC or the RLSP, MCCs shall also process the RLS message as an alert message, in accordance with Figures II/B.4.1 and II / B.4.2.

After position confirmation, if the status of the Automatic Acknowledgement Received by the Beacon (beacon message bit 111, as specified in document C/S T.001) changes, then the new alert shall be sent to the MCC(s) associated with RLS provider(s) previously notified with a position confirmation alert. A new alert shall only be sent to the MCC(s) associated with RLS provider(s) if:

- a. PDF-2 of the beacon message is usable; and
- b. The time of the latest burst in the new alert is later than the time of the latest burst in the previous alert sent for the beacon to the associated MCC(s) for the RLS provider(s).

MCCs shall distribute alerts for test coded RLS beacons (beacon message bits 41-42 = 11, as specified in document C/S T.001) to other MCCs, including the MCC(s) associated with the RLS provider(s), in the same manner that operationally coded RLS beacons are distributed. MCCs shall not distribute alerts for test coded RLS beacons to RCCs and SPOCs.

An MCC that has assumed backup responsibilities for another MCC shall initiate and distribute RLS messages on behalf of the MCC being backed up.

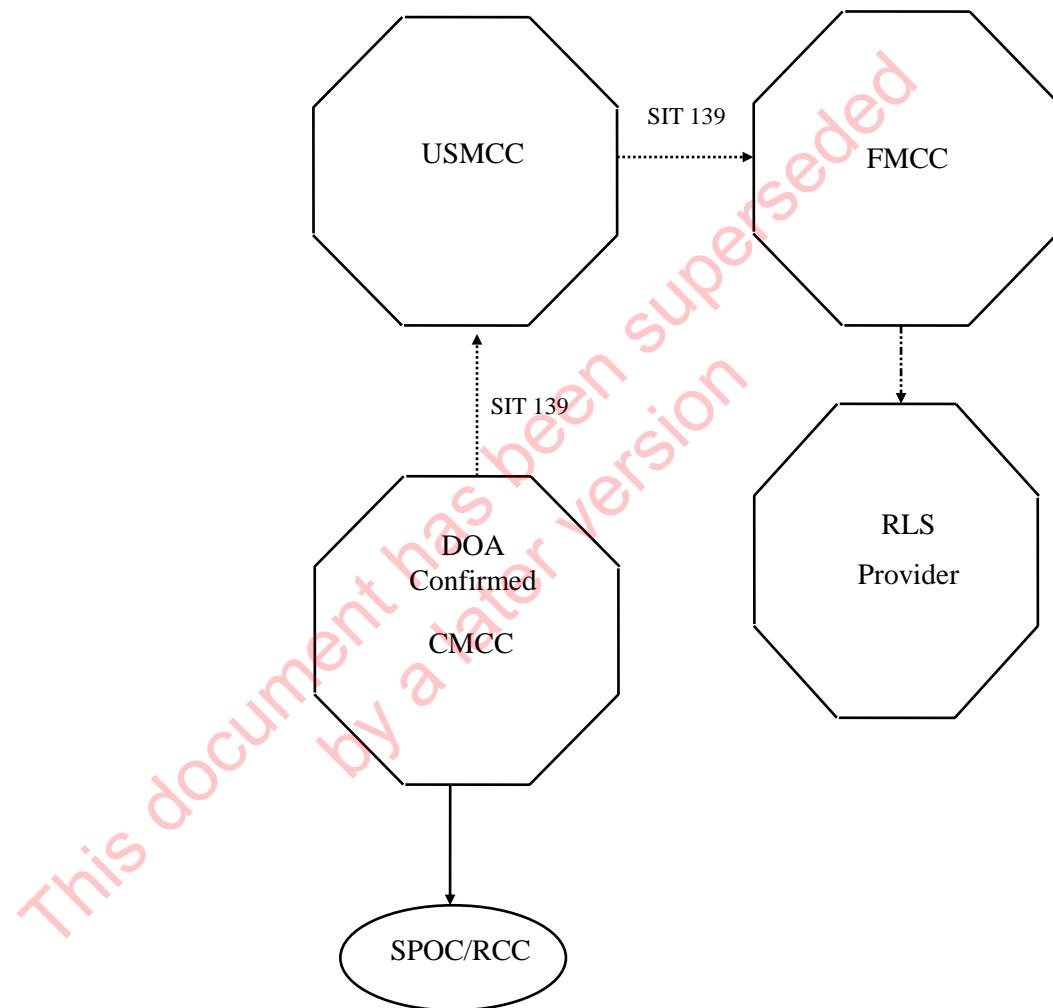
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II / B.10.2 RLS ExampleScenario

Country code in Beacon ID: Australia (503)

Confirmed (DOA) Position Service Area: CMCC (Canadian MCC)

Beacon coded for the Sar/Galileo Return Link Service



ANNEX II / C**PROCEDURES FOR THE CO-ORDINATION
OF BEACON TESTS**

Section 3.8 of C/S A.001 defines the principles governing the implementation of tests using beacons coded with operational protocols or beacons coded with a Test Protocol. The following procedures should be implemented by the MCC responsible for the test for co-ordinating the requirements of the test with all affected MCCs. This procedure does not apply to international exercises co-ordinated through the Cospas-Sarsat Joint Committee.

The co-ordination shall consist of an advance submission of a text (SIT 605) message shown in Figure II / C.1. The extent of required co-ordination will depend on beacon protocol (operational or test) and the number of beacons used, as shown in Table II / C.1.

The Beacon ID must conform to the definition given in the Cospas-Sarsat Glossary (document C/S G.004) and in the "Acronyms and Terminology" page on the Cospas-Sarsat website, available at <http://www.cospas-sarsat.int/en/pro>, under the Documents menu.

Figure II / C.1: Beacon Test Co-ordination Message

SIT 605 < MESSAGE >

DATE: DD MM YY
FM: MCC SUPPORTING THE 406 MHz TEST
TO: ALL MCCs
SUBJ: BEACON TEST

A. TEST OBJECTIVE:
B. TEST DESCRIPTION:
C. LOCATION OF TEST:
D. DATE, TIME AND DURATION OF TEST:
E. BEACON ID (15 CONTIGUOUS HEXADECIMAL CHARACTERS):
F. SPECIAL DATA COLLECTION AND PROCESSING REQUIREMENTS:
G. POINT OF CONTACT
NAME:
LOCATION:
TELEPHONE NO:
AFTN NO:
TELEX NO:
FACSIMILE NO:

**Table II / C.1: Notification Time Requirement for Submission
of Co-ordination Information Indicated in Figure II / C.1**

Number of Beacons Used	Messages Required	Beacon Protocol	
		Operational	Test
1 -3	Initial Notification	As soon as practical	Not required
	Second Notification	24 hours prior to the activation of the first beacon *	Not required
	End-of-Test Notification	Upon deactivation of the last beacon as required	Not required
maximum 6	Initial Notification	30 days prior to the date of the test	30 days prior to the date of the test
	Second Notification	24 hours prior to the activation of the first beacon *	24 hours prior to the activation of the first beacon *
	End-of-Test Notification	Upon deactivation of the last beacon as required	Upon deactivation of the last beacon as required

Note: * This set of information will be an update, if necessary, of the original set.

-END OF ANNEX II / C -

ANNEX II / D**LEOLUT ORBIT VECTOR UPDATE METHOD**

There are three methods for LEOLUT orbit vector updates for each Cospas-Sarsat satellite: use of the downlink signal, use of orbitography beacon information and use of orbit vector data supplied by an MCC. Which method offers the more accurate orbit vector determination for a given satellite pass depends on the satellite's SAR instrument status and how often orbit vectors are available at the LUT from the MCC.

If the SAR instrument status of a satellite is such that any of the three update methods can be used, the preferred update method is through orbitography beacons. Table II / D.1 provides guidelines for each satellite with the update methods listed such that the preferred method is number 1.

Table II / D.1: Orbit Vector Update Method

Satellite	Orbit Vector Update Method
Sarsat-7, Sarsat-10, Sarsat-11, Sarsat-12 and Sarsat-13	<ol style="list-style-type: none">1. Orbitography2. MCC Provided Orbit Vectors3. Downlink

- END OF ANNEX II / D -

- END OF PART II -

- END OF DOCUMENT -

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